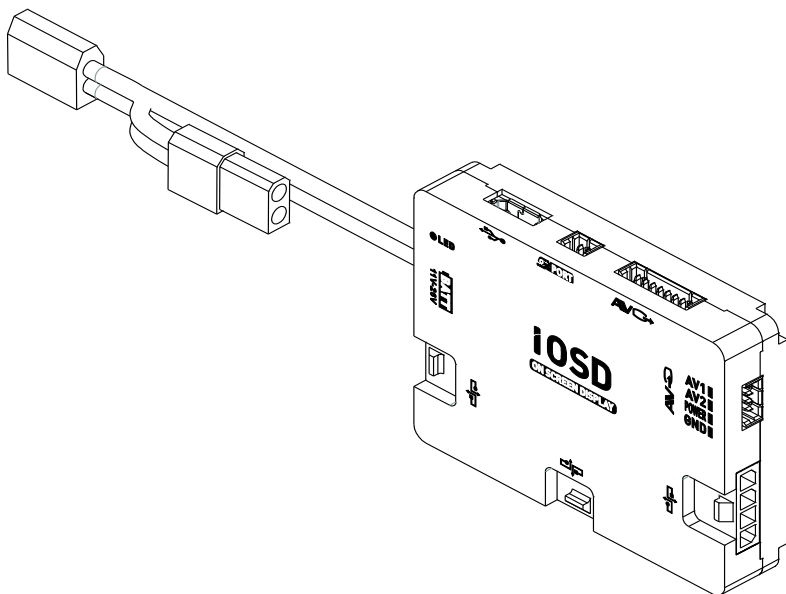# iOSD (On Screen Display)
User Manual

V2.10

For iOSD Firmware Version V3.01 & iOSD Assistant V4.0*

April 7, 2014

* iOSD Firmware V3.01 compatible with iOSD Assistant V4.0.

Disclaimer

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Contents

Introduction

DJI iOSD is specially designed for DJI autopilot system during the FPV flight or other aero-modeling activates. DJI iOSD can transmit video and iOSD information in real time, which will help you to obtain the aircraft status information during a FPV flight. It can display power voltage, flight velocity, height, distance from the home point, horizontal attitude, GPS satellite number, etc. iOSD and video information are superposed on the receiver, making iOSD data clearly visible and bringing you a more involved flight experience.

DJI iOSD should be used in conjunction with a DJI autopilot system. It supports two video input sources under PAL or NTSC mode, which can be selected remotely by an R/C transmitter switch. The R/C TX switch can also change the wireless video transmitter channel remotely when user uses the wireless video transmitter specified by DJI. The iOSD supports online upgrades. The iOSD has built-in BEC, which is on one hand for the power supply of the camera, on the other hand for the power supply of the autopilot system's main controller to improve the power supply reliability of the main controller.

Specified autopilot systems for the iOSD

Status	Autopilot system & Aircraft
Supported	A2, WKM, NAZA-M*, NAZA-M V2*, PHANTOM 2
Not yet supported	WKH、ACE ONE、ACE WAYPOINT

*iOSD should be connected to the NAZA-M or NAZA-M V2 via the PMU V2 (NAZA-M V2 Accessory).

*iOSD should not be connected to the WKM and NAZA-M/ NAZA-M V2 at the same time.

*NAZA-M should be upgrade to the firmware version of V3.16 (or above), with the same assistant software V2.16 of Naza-M V2.

In the Box

iOSD Controller ×1

Connect the iOSD controller to your DJI autopilot system via CAN-Bus Cable. It communicates with the main controller, receives data from the main controller, superimposes the data with the video image, and then transmits the whole information via a transmitter.
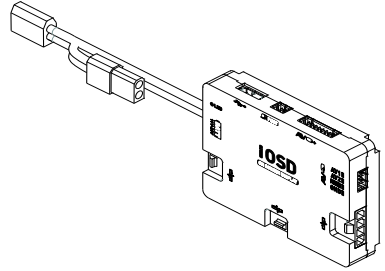
CAN-Bus Cable ×2

Connect the iOSD to your autopilot system through a CAN-Bus cable.
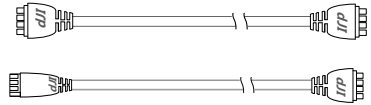
Video Input Cable ×1

Connect the iOSD with video input source (i.e. camera or DJI Z15) for video input and power supply, with maximum current of 1A. If you connect the iOSD to DJI Z15, please use the 4Pin-Audio Head cable.

If connect to other camera, use the 4Pin cable for the connection in accordance with the wiring diagram.

Video Output Cable ×2

Only when you use the wireless video transmitter module specified by DJI, you can use the bi-port cable to connect the iOSD with the video transmitter module. Otherwise, you can use the one-port cable for your own connection in accordance with the wiring diagram.
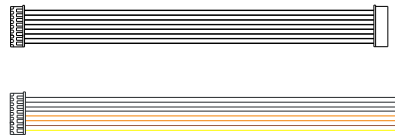
2-PIN to 3-PIN Cable ×1

Connect the iOSD with the R/C receiver through this cable. When there are two video signal inputs, it is used for the selection of video signal sources. It can be used for the selection of AVL58 video channel.

Assembly

1. Fix the iOSD controller on your aircraft.

2. Connect the iOSD with the video signal source, wireless video TX module, DJI autopilot system and R/C receiver. Make sure the connection is correct in accordance with the wiring diagram.

3. Setup a 3-position switch on the R/C TX as the iOSD control switch.

4. Connect your wireless video RX module with the display screen.

Please refer to DJI autopilot system manual, your TX manual, and your wireless video RX for more details.

3-Position Switch Control

Choose a 3-position switch and make sure you connect the correct channel of the receiver to the iOSD switch port.

- Position -1→ Position -2, (hold position -2 for 1.5s): every toggle from Position -1 to Position -2 increases the channel of the wireless video transmitter module by 1 (from CH1 to CH8), only for the wireless video transmitter module specified by DJI.

- Position -3→ Position -2, (hold position -2 for 1.5s): toggle the switch to select the required video input, when there are two video inputs. Only the toggle from Position -3 to Position -2 can change the video input source. AV1 is default.

Position -1   **Position -2**   **Position -3**
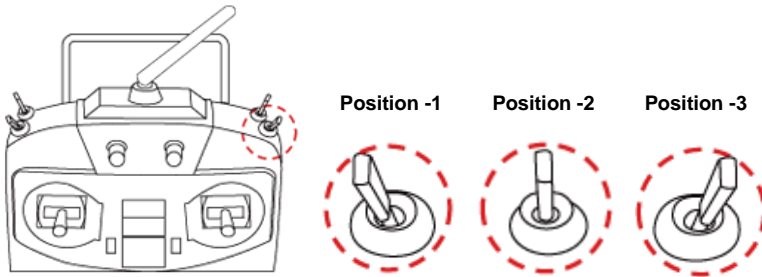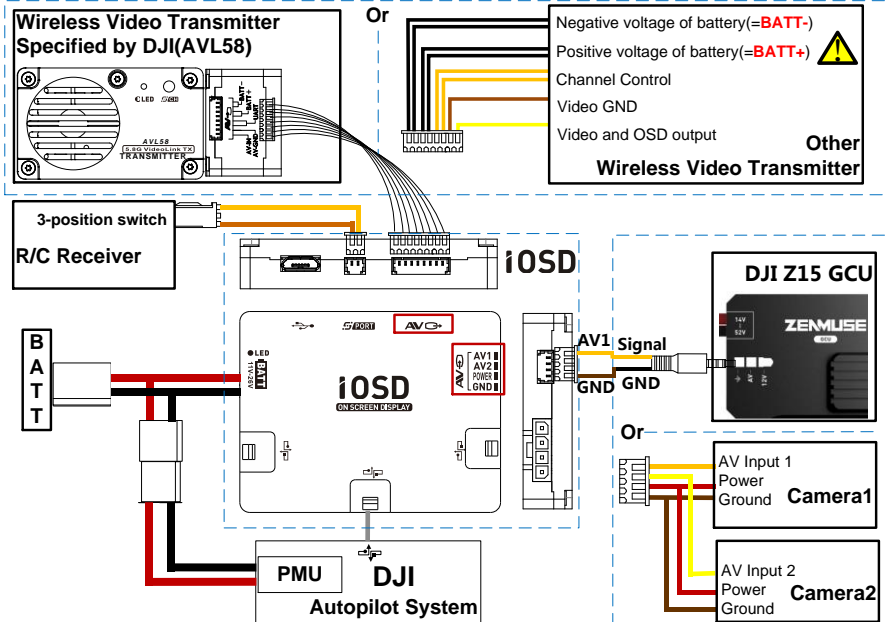
Video Output Port

- If you use wireless video transmission module AVL58 specified by DJI, connect through the bi-port cable.
- If you use your own module, please connect through the one-port cable according the pin description.

Channel Control pin : Control signal for the video transmitter channel number (CH1.....CH8).If your video transmitter does not support this feature, then ignore this pin.

Video and OSD output pin: make sure this is correctly connected.

Positive/Negative voltage of battery pin: its output voltage is equate to the voltage of the battery, supplying power for your wireless video transmitter. It is recommended to solder the two cables of the same function.

⚠️ Please make sure the input voltage of your own wireless video transmitter is matched to the voltage of BATT, to prevent damage from your wireless video transmitter module. For example, if the Battery is 6S(25V) and the input voltage of the wireless video transmitter is 3S(12V), then you cannot use the BATT+ to supply power since the 25V is larger than 12V.

Wireless Video Transmitter Specified by DJI(AVL58)

Or

Negative voltage of battery(=**BATT-**)
Positive voltage of battery(=**BATT+**) ⚠️
Channel Control
Video GND
Video and OSD output

Other Wireless Video Transmitter

3-position switch
R/C Receiver

iOSD

DJI Z15 GCU

B A T T

AV1 Signal
GND GND

Or

AV Input 1
Power
Ground **Camera1**

AV Input 2
Power
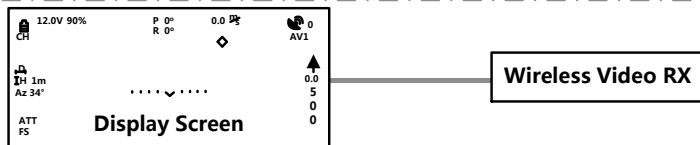Ground **Camera2**

PMU **DJI**
Autopilot System

Important: iOSD can be connected to any CAN-Bus port of the WKM system, BUT should be connected to the NAZA-M or NAZA-M V2 via the PMU V2 (NAZA-M V2 Accessory). NAZA-M should be upgraded to the firmware version of V3.10 or above when using with the PMU V2 , with the same assistant software V2.10 of NAZA-M V2. iOSD should not be connected to the WKM and NAZA-M/NAZA-M V2 at the same time. Refer to the Appendix for more connection details.
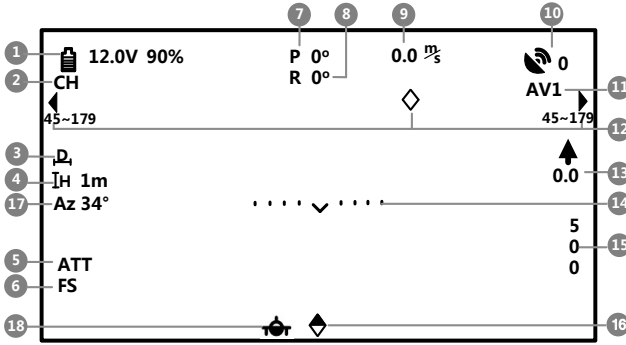
Video Input Port

- If you use the DJI Z15, it is recommended to use the 4Pin- Audio Head cable for connecting the iOSD and GCU. If you use the 4Pin cable, please connect the iOSD to the Z15's GCU according to the above chart.
- If you use your own camera(s), please connect through the Video Input Cable according the pin description. **AV1/AV2 pin** : you can select the required input. AV1 is default. **POWER pin** : supply power for Video input source such as a camera, with the maximum current of 1A. If the battery is 3S LiPo then: Output Voltage = Input Votage. If 4S~6S then: Output Voltage=11.2V. Make sure your camera is rated for this voltage and current(1A), if not, please use a separate battery supply.
- If you use other wireless video transmitter and the rated voltage is over the voltage of BATT+, you can use the **POWER pin** to apply power. Make sure the total current consumption of wireless video transmitter and camera is lower than 1A, otherwise will damage your iOSD.

Aircraft End
Ground End

12.0V 90%   P 0°   0.0   0 AV1
CH   R 0°
H 1m   0.0
Az 34°   · · · · ∨ · · · ·   5
                                  0
ATT   0
FS   **Display Screen**

Wireless Video RX

Display Description

The iOSD information is displayed on the screen as shown below.

NO.	Function	Display	Description
1	Power voltage	🔋、🔋blink	Real time battery voltage of the aircraft power, unit in V. (For PHANTOM 2 there will be current battery level percentage shown in addition.) 🔋Blink: first level low-voltage alert, the alert threshold is same to the protection voltage value set in the assistant software.
2	Channel	CH1、CH2、......CH8	Wireless video transmitter channel selection.
3	Distance between aircraft and home points	**D**	When the home point is successfully recorded, this item will show, unit in m.
4	Height	**H**	The vertical height between the aircraft and the take-off point, unit in m.
5	Control mode	ATT、M、GPS	The autopilot system control mode. ● ATT is Atti mode ● GPS is GPS Atti. mode ● M is Manual mode
6	Fail-safe mode	FS 、 APT 、 GHome	● FS is in Fail-safe mode ● APT is in ground station mode ● GHome is in go home status
7	Pitch attitude	P 0°	Positive value means the aircraft nose is up; negative value means the

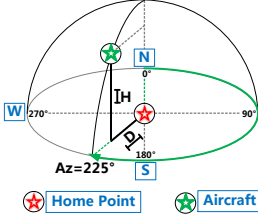|			
			aircraft nose is down.
8	Roll attitude	R 0°	Positive value means the aircraft is right. Negative value means the aircraft is left.
9	Flight velocity	0.0m/s	The aircraft horizontal speed.
10	GPS satellite	📶 0	Number of GPS satellites acquired.
11	Video input	AV1、AV2	Video input source selected, AV1 or AV2 can be chosen.
12	Aircraft nose direction	◇ `◀ ▶	Display the relative angle between aircraft nose and home point. The aircraft nose is pointing to the home point when the icon ◇ is in the middle of the screen, this may help you to bring back the aircraft by distinguishing the aircraft nose direction. For example, when the icon ◇ on your display screen is located in the Orientation-3 as shown in the following figure, you can change the aircraft nose direction through operating your R/C TX. When the icon arrives at the Orientation-1, your aircraft nose is heading the home point, which can help you pull your aircraft back to the home point easily.
13	Vertical velocity	▲ 0.0 `0.0 ▼	▲ : Upward speed ▼ : Downward speed
14	Attitude line	· · · · ∨ · · · ·	Use attitude line for aircraft attitude observation ● craft up： ● craft down： ● craft left： ● craft right：

15	Gimbal Attitude	**5** **0** **0**	Display the 3-axis attitude of the gimbal when a gimbal is used. 5 —— Roll Direction 0 —— Pitch Direction 0 —— Yaw Direction
16	Compass error indicator	◆ blink	For NAZA-M user, Blinking ◆ will appear when compass has errors, please calibrate your compass.
17	Azimuth angle	**Az(0º ~360º)**	Azimuth angle is a horizontal angle measured clockwise from the North base line to the line goes through the home point and aircraft position. Users can locate the aircraft by calculating the aircraft position using Az, D, H.
18	Airport alert	Blink	Blinks when the aircraft enters a no-fly zone*. Disappears when the aircraft exits no-fly zone.

Notes:

* For more information about the no-fly zones, visit www.dji.com and download the *Phantom 2 User Manual*.

Test

Please use the following procedures to test your installation, in order to make sure the iOSD is working properly.
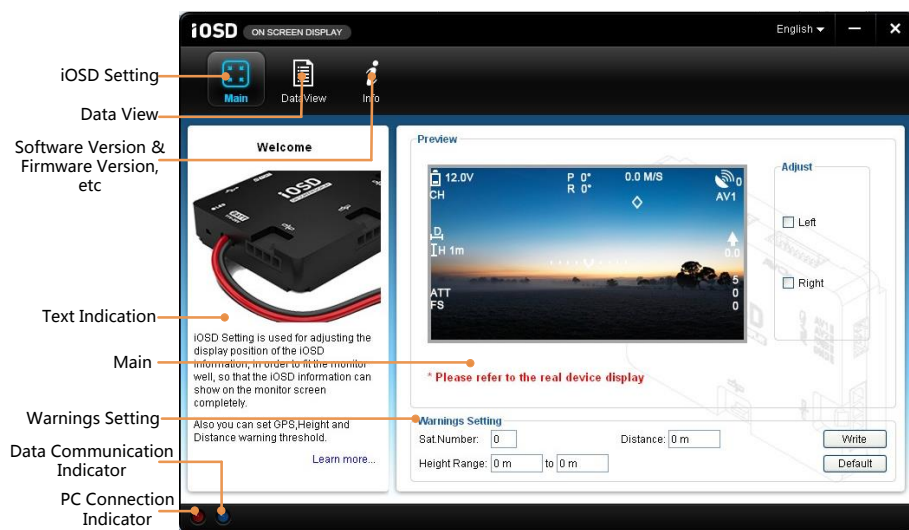
1. Ensure batteries are fully charged for R/C transmitter, iOSD and all the other devices on your aircraft.

2. Make sure all connections and wiring are correct and secure.

3. Make sure the communication between the wireless video RX and TX modules is normal.

4. Switch on the R/C transmitter, and power on the iOSD and autopilot system.

5. Check the LED indicator on the iOSD. The iOSD is powered when the LED is on.

6. If there are two video inputs, please select an input by toggling the TX 3-position switch; otherwise, please skip to the next step.

7. If you use the wireless video RX and TX modules specified by DJI, please select the channel you require by toggling the TX 3-position switch; otherwise, please skip to next step.

8. Observe the display screen to make sure the video and iOSD information are displaying on the screen.

Assistant Software

Software and Driver Installation

1. Please download driver installer and assistant software from the iOSD page of DJI website.

2. Connect the iOSD Controller and the PC via USB cable, power on the iOSD Controller system.

3. Run driver installer, and follow the instructions strictly to finish installation.

4. Run assistant software installer, and follow the instructions strictly to finish installation.

Assistant Software GUI

iOSD Setting
Data View
Software Version & Firmware Version, etc
Text Indication
Main
Warnings Setting
Data Communication Indicator
PC Connection Indicator

Assistant Software Usage

Using the assistant software, adjust the display position of the iOSD information, upgrade the firmware and assistant software are available. In addition, the flight data will automatically be saved as files in the iOSD, which can be viewed by connecting to the PC.

1. Power on your computer.

2. Make sure the iOSD is power on. Connect the iOSD Controller to the PC with a USB cable. (If the iOSD is connected to the autopilot system and both of them are power on, and then switch on the transmitter first.)

3. Run the iOSD Assistant Software.

4. If the Data Communication Indicator is Red on, please double check the connections and driver installation; otherwise if the indicator is blinking Green, go to next step.

5. Select the Main item to adjust the display position of the iOSD information if necessary. And then configure the warning of GPS Satellite Number, Distance and Height Range if warnings are required.

6. Click the DataView item, and follow the tips to get the flight attitude data, main control input and output information, etc.

Note:

(1) If you do not configure the Warnings Setting, the iOSD will show warnings in default values.

(2) It will auto detect the firmware version when you open the assistant software and prompt the check for updates window if your version is not the latest one.

(3) If enter the Data View mode, the iOSD controller will temporarily quit the parameter configuration mode, and act as a USB Device to connect to the PC. You can manually select and read any data file from the USB Device. If you need to re-enter the parameter configuration mode, please power cycle the iOSD.

(4) The speed of data loading will be very slow for large files. For the large file on the iOSD controller, please copy the file to the local hard drives of the PC, and then open the file for viewing.

(5) The Compass Data Recording is added in the iOSD Firmware version V2.00 (or above); you can read the Compass data in the DataView item of the iOSD assistant software V2.00.

Firmware & Assistant Software Upgrade

Please follow the procedure for firmware upgrade; otherwise the iOSD might not work properly.

1. Make sure your computer is connected to the Internet. Please close all the other applications during the firmware upgrade, including anti-virus software and firewall.

2. Make sure the power supply is securely connected. DO NOT un-plug the power supply until firmware upgrade has finished.

3. Connect the iOSD to PC with Micro-USB cable, DO NOT break connection until firmware upgrade is finished.

4. Run the assistant software and wait for connection.

5. Select Info➔Software and Firmware.

6. DJI server will check your current software and firmware version, and get the latest software and firmware prepared for the unit.

7. If there is a software version more up-to-date than your current version, you will be able to click to download the

new version. Please re-install the assistant software follow the prompts

8. If there is a firmware version more up-to-date than your current version, you will be able to click to update them.

9. Wait until Assistant software shows "finished".

10. Click OK and power cycle. Your unit is now up-to-date.

Note:

If firmware upgrade failed, the iOSD will enter waiting for firmware upgrade status automatically, please try again with the above procedures.

Appendix

Port Description

BATT	Power Battery Input Port，input voltage range: 11V~26V
PORT	Control Signal Input Port，for wireless video module channel selection and video input source selection
AV	Video Signal Output Port ● AV-OUT：Video Signal Output, including both video and iOSD information ● AV- GND：Video Signal Ground ● UART： transmit the wireless channel control signal to the wireless video transmitter (For example AVL58) ● BATT+：it is equate to the Positive Voltage of Battery ● BATT-：it is equate to the Negative Voltage of Battery
AV	Video Input Port，2 input sources are available, and the default setup is AV1 ● AV1：Video Input Source 1 ● AV2：Video Input Source 2 ● POWER：11~13V, supply power for video input source with the maximum current of 1A ● GND：Ground
⌁	Micro-USB Port：Connects the iOSD with PC for firmware upgrade
⌁	CAN-Bus : Communication of the iOSD with autopilot system through CAN-Bus
LED	LED indicator for power

Specifications

| Performance Parameter	
Video Input Mode	PAL/NTSC
Video Output Mode	PAL/NTSC
Physical	
Temperature (V1.0)	-20~70ºC
(Mark II)	-20~60ºC
Size	52mm X 41mm X 11mm
Weight (V1.0)	42g
(Mark II)	56 g
Hardware Supported	
Voltage	3S~6S(LiPos)
Current (Typical Value) (V1.0)	51mA@25.2V; 87mA@12.6V
(Mark II)	60mA@25.2V; 103mA@12.6V
Rated Power	1.25W
Controller Supported	WKM, NAZA-M, NAZA-M V2
Software Supported	
Built-in Functions	- iOSD Information Transmission - Video Transmission，2 Video Signal input Channels/Switchable - Remote channel selection of the Wireless Video Transmitter Module, when using the video transmitter specified by DJI - Built-in BEC: improve the reliability of power supply for the main controller - DJI Z15 Supported

Trouble Shooting

| No.	What	Why	How to
1	Only iOSD information, video signal loss.	Video input error.	Make sure the connection between iOSD controller and video input port is OK.
2	Only video signal, iOSD information loss.	Connection between iOSD controller and autopilot system error.	Make sure the connection between iOSD controller and DJI autopilot system is OK.
3	Both video signal and iOSD information loss.	Signal transmission error.	● Make sure the Wireless Video Transmitter Channel Setting is correct. ● Make sure the communication between the video transmitter and the receiver is working correctly.
4	Both video signal and iOSD information loss.	The video signal cable to display screen is unconnected or short circuit.	Make sure the connection of video signal cable is OK.

Some Descriptions for the iOSD Version1.0

There is an adapter for the Version1.0, to solve the problem that the iOSD is incompatible with your camera. If there is the incompatible problem with your device, please contact your authorized dealer to get an adapter for free.

There are two adapter versions, including SAO and SAO for Z15. If the iOSD is working with the Z15, please use the version of SAO for Z15, otherwise if with your camera, use the SAO. Please connect the adapter according to the below figure.

Using the SAO:
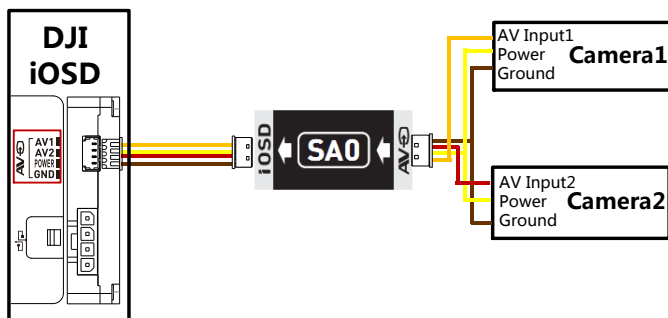
Using the SAO for Z15:
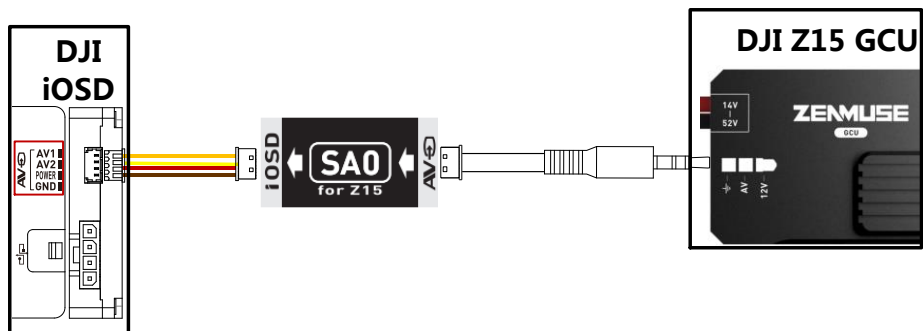
Connection Between iOSD and Autopilot System

Connection Between iOSD and NAZA-M/NAZA-M V2

1. If use with DJI multi-rotor, you can solder the power cable of the PMU V2 to the power pads on frame bottom board. Please refer to DJI multi-rotor manual for details. Then connect the iOSD to a battery.

2. If use with 3rd part aircraft, you can make a connecter by yourself to connect PMU V2 and battery.

   (1) NAZA-M (Fig.1): Make a connecter to connect the PMU V2 (NAZA-M V2 Accessory), iOSD, VU and battery.

   (2) NAZA-M V2 (Fig.2): Make a connecter to connect the PMU V2, iOSD and battery.
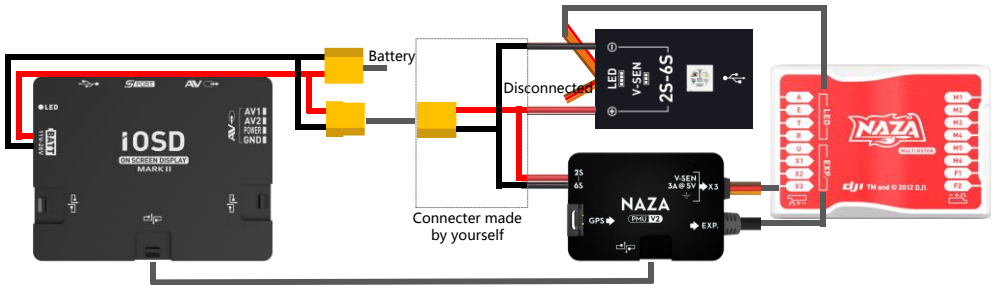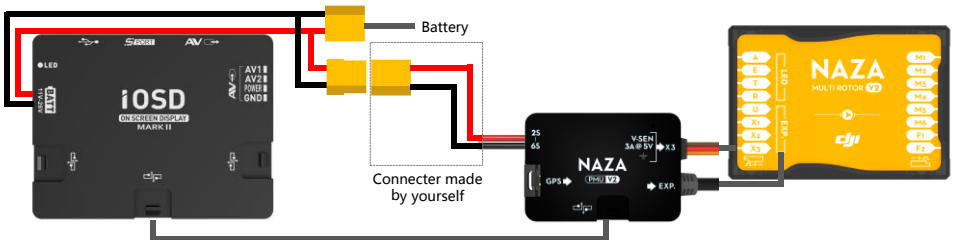
Fig.1 Connection between iOSD and NAZA-M

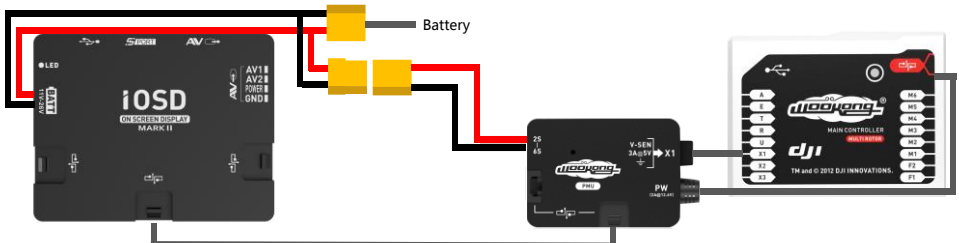Fig.2 Connection between iOSD and NAZA-M V2

Connection Between iOSD and WKM (Fig.3)

Fig.3 Connection between iOSD and WKM