

T-REX 500

INSTRUCTION MANUAL

使用說明書

KX017014T



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Thank you for buying ALIGN products. The **T-REX 500** is the latest technology in Rotary RC models. Please read this manual carefully before assembling and flying the new **T-REX 500** helicopter. We recommend that you keep this manual for future reference regarding tuning and maintenance.

承蒙閣下選用亞拓遙控世界系列產品，謹表謝意。進入遙控世界之前必須告訴您許多相關的知識與注意事項，以確保您能夠在學習的過程中較得心應手。在開始操作之前，請務必詳閱本說明書，相信一定能夠給您帶來相當大的幫助，也請您妥善保管這本說明書，以作為日後參考。

Thank you for buying ALIGN Products. The T-REX 500 Helicopter is designed as an easy to use, full featured Helicopter R/C model capable of all forms of rotary flight. Please read the manual carefully before assembling the model, and follow all precautions and recommendations located within the manual. Be sure to retain the manual for future reference, routine maintenance, and tuning. The T-REX 500 is a new product developed by ALIGN. It features the best design available on the Micro-Heli market to date, providing flying stability for beginners, full aerobatic capability for advanced fliers, and unsurpassed reliability for customer support.

感謝您選購亞拓產品，為了讓您容易方便的使用 T-REX 500 直昇機、請您詳細的閱讀完這本說明書之後再進行組裝以及操作這台直昇機，同時請您妥善的保存這本說明書、作為日後進行調整以及維修的參考。T-REX 500 是由亞拓自行研發的新產品，不論你是需求飛行穩定性的初學者或是追求性能的飛行愛好者。T-REX 500 將是你最佳的選擇。

WARNING LABEL LEGEND 標誌代表涵義

 WARNING 警告	Mishandling due to failure to follow these instructions may result in damage or injury. 因為疏忽這些操作說明，而使用錯誤可能造成財產損失或嚴重傷害。
 CAUTION 注意	Mishandling due to failure to follow these instructions may result in danger. 因為疏忽這些操作說明，而使用錯誤可能造成危險。
 FORBIDDEN 禁止	Do not attempt under any circumstances. 在任何禁止的環境下，請勿嘗試操作。

IMPORTANT NOTES 重要聲明

R/C helicopters, including the T-REX 500 are not toys. R/C helicopter utilize various high-tech products and Technologies to provide superior performance. Improper use of this product can result in serious injury or even death. Please read this manual carefully before using and make sure to be conscious of your own personal safety and the safety of others and your environment when operating all ALIGN products.

Manufacturer and seller assume no liability for the operation or the use of this product.

Intended for use only by adults with experience flying remote control helicopters at a legal flying field. After the sale of this product we cannot maintain any control over its operation or usage.

T-REX 500 遙控直昇機並非玩具，它是結合了許多高科技產品所設計出來的休閒用品，所以商品的使用不當或不熟悉都可能造成嚴重傷害甚至死亡，使用之前請務必詳讀本說明書，勿輕忽並注意自身安全。注意！任何遙控直昇機的使用，製造商和經銷商是無法對使用者於零件使用的損耗異常或組裝不當所發生之意外負任何責任，本產品是提供給有操作過模型直昇機經驗的成人或有相當技術的人員在旁指導於當地合法遙控飛行場飛行，以確保安全無虞下操作使用，產品售出後本公司將不負任何操作和使用控制上的任何性能與安全責任。

We recommend that you obtain the assistance of an experienced pilot before attempting to fly our products for the first time. A local expert is the best way to properly assemble, setup, and fly your model for the first time. The T-REX 500 requires a certain degree of skill to operate, and is a consumer item. Any damage or dissatisfaction as a result of accidents or modifications are not covered by any warrantee and cannot be returned for repair or replacement. Please contact our distributors for free technical consultation and parts at discounted rates when you experience problems during operation or maintenance.

模型商品屬於需高操作技術且為消耗性之商品，如經拆裝使用後，會造成不等情況零件損耗，任何使用情況所造成商品不良或不滿意，將無法於保固條件內更換新品或退貨，如遇有使用操作維修問題，本公司全省分公司或代理商將提供技術指導、特價零件供應服務。

2. SAFETY NOTES 安全注意事項



Fly only in safe areas, away from other people. Do not operate R/C aircraft within the vicinity of homes or crowds of people. R/C aircraft are prone to accidents, failures, and crashes due to a variety of reasons including, lack of maintenance, pilot error, and radio interference. Pilots are responsible for their actions and damage or injury occurring during the operation or as of a result of R/C aircraft models.

遙控模型飛機、直昇機屬高危險性商品，飛行時務必遠離人群，人為組裝不當或機件損壞、電子控制設備不良，以及操控上的不熟悉、都有可能導致飛行失控損傷等不可預期的意外，請飛行者務必注意飛行安全，並需了解自負疏忽所造成任何意外之責任。



LOCATE AN APPROPRIATE LOCATION 遠離障礙物及人群

R/C helicopters fly at high speed, thus posing a certain degree of potential danger. Choose an a legal flying field consisting of flat, smooth ground without obstacles. Do not fly near buildings, high voltage cables, or trees to ensure the safety of yourself, others and your model. For the first practice, please choose a legal flying field and can use a training skid to fly for reducing the damage. Do not fly your model in inclement weather, such as rain, wind, snow or darkness.

直昇機飛行時具有一定的速度，相對的也潛在著危險性，場地的選擇也相對的重要，請需遵守當地法規到合法搖控飛行場地飛行。必須注意周遭有沒有人、高樓、建築物、高壓電線、樹木等等，避免操控的不當造成自己與他人財產的損壞。初次練習時，務必選擇在空曠合法專屬飛行場地並適當搭配練習架練習飛行，這對飛行失誤所造成的損傷將會大幅的降低。請勿在下雨、打雷等惡劣天候下操作，以確保本身及機體的安全。



PREVENT MOISTURE 遠離潮濕環境

R/C models are composed of many precision electrical components.

It is critical to keep the model and associated equipment away from moisture and other contaminants. The introduction or exposure to water or moisture in any form can cause the model to malfunction resulting in loss of use, or a crash. Do not operate or expose to rain or moisture.

直昇機內部也是由許多精密的電子零組件組成，所以必須絕對的防止潮濕或水氣，避免在浴室或雨天時使用，防止水氣進入機身內部而導致機件及電子零件故障而引發不可預期的意外！



PROPER OPERATION 勿不當使用本產品

Please use the replacement of parts on the manual to ensure the safety of instructors. This product is for R/C model, so do not use for other purpose.

請勿自行改造加工，任何的升級改裝或維修，請使用亞拓產品目錄中的零件，以確保結構的安全。請確認於產品限界內操作，請勿過載使用，並勿用於安全、法令外其它非法用途。



OBTAIN THE ASSISTANCE OF AN EXPERIENCED PILOT 避免獨自操控

Before turning on your model and transmitter, check to make sure no one else is operating on the same frequency. Frequency interference can cause your model, or other models to crash. The guidance provided by an experienced pilot will be invaluable for the assembly, tuning, trimming, and actual first flight. (Recommend you to practice with computer-based flight simulator.)

至飛行場飛行前，需確認是否有相同頻率的好手正進行飛行，因為開啓相同頻率的發射機將導致自己與他人立即干擾等意外危險。遙控飛機操控技巧在學習初期有著一定的難度，要盡量避免獨自操作飛行，需有經驗的人士在旁指導，才可以操控飛行。(勤練電腦模擬器及老手指導是入門必要的選擇)



SAFE OPERATION 安全操作

Operate this unit within your ability. Do not fly under tired condition and improper operation may cause in danger.

請於自己能力內及需要一定技術範圍內操作這台直昇機，過於疲勞、精神不佳或不當操作，意外發生風險將可能會提高。



ALWAYS BE AWARE OF THE ROTATING BLADES 遠離運轉中零件

During the operation of the helicopter, the main rotor and tail rotor will be spinning at a high rate of speed. The blades are capable of inflicting serious bodily injury and damage to the environment. Be conscious of your actions, and careful to keep your face, eyes, hands, and loose clothing away from the blades. Always fly the model a safe distance from yourself and others, as well as surrounding objects. Never take your eyes off the model or leave it unattended while it is turned on. Immediately turn off the model and transmitter when you have landed the model.

當直昇機主旋翼與尾旋翼運轉時，切勿觸摸並遠離任何物件，以避免造成危險及損壞。








KEEP AWAY FROM HEAT 遠離熱源

R/C models are made of various forms of plastic. Plastic is very susceptible to damage or deformation due to extreme heat and cold climate. Make sure not to store the model near any source of heat such as an oven, or heater. It is best to store the model indoors, in a climate-controlled, room temperature environment.









遙控飛機多半是以 PA 纖維或聚乙烯、電子商品為主要材質，因此要盡量遠離熱源、日曬，以避免因高溫而變形甚至熔毀損壞的可能。



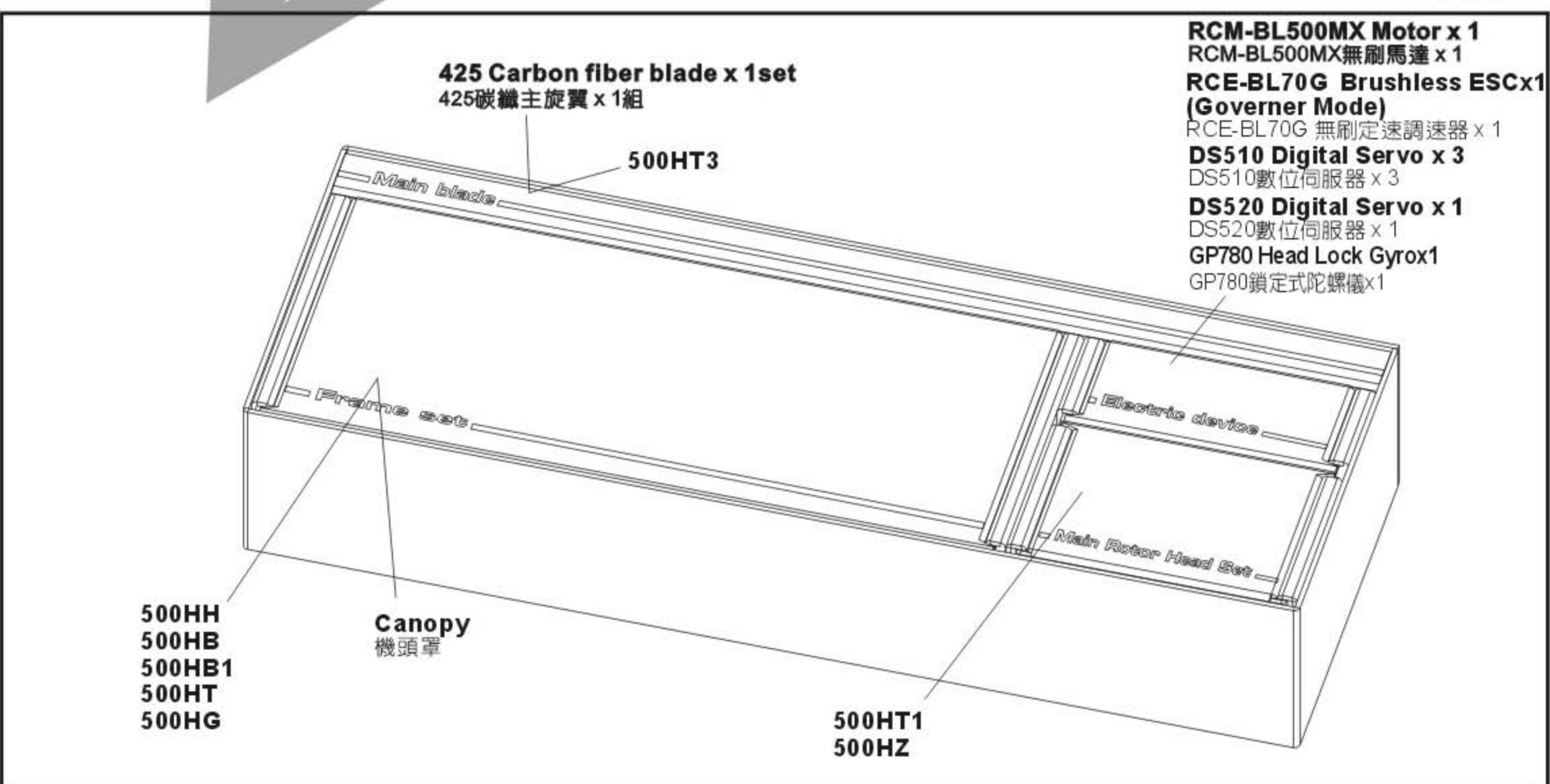
RADIO TRANSMITTER AND ELECTRONIC EQUIPMENT REQUIRED FOR ASSEMBLY 自備遙控及電子設備

 Transmitter (6-channel or more, helicopter system) 發射機(六動以上直昇機模式遙控器)	 Receiver(6-channel or more) 接收機(六動以上)
 22.2V 6S 2100~ 2600mAh Li-Po Battery x 1pc 22.2V 6S 2100~2600mAh Li-Po電池 x 1	 Dial Pitch Gauge x 1pc 旋轉式螺距規 x 1
 Li-Po Battery Charger RCC-6CX Li-Po電池充電器 RCC-6CX	

ADDITIONAL TOOLS REQUIRED FOR ASSEMBLY 自備工具

 Scissors 剪刀	 Cutter Knife 刀子	 Diagonal Cutting Pliers 斜口鉗	 Needle Nose Pliers 尖嘴鉗
 Oil 潤滑油	 CA 瞬間膠	 Hexagon Screw Driver 六角螺絲起子 3mm/2.5mm/2mm/1.5mm	 Philips Screw Driver 十字螺絲起子 φ 3.0/ φ 1.8mm

4.PACKAGE ILLUSTRATION 包裝說明







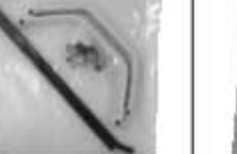









CAREFULLY INSPECT BEFORE REAL FLIGHT 請嚴格執行飛行前檢查義務

- ☆ **Before flying, please check to make sure no one else is operating on the same frequency for the safety.**
- ☆ **Before flight, please check if the batteries of transmitter and receiver are enough for the flight.**
- ☆ **Before turn on the transmitter, please check if the throttle stick is in the lowest position. IDLE switch is OFF.**
- ☆ **When turn off the unit, please follow the power on/off procedure. Power ON- Please turn on the transmitter first, and then turn on receiver. Power OFF- Please turn off the receiver first and then turn off the transmitter. Improper procedure may cause out of control, so please to have this correct habit.**
- ☆ **Before operation, check every movement is smooth and directions are correct. Carefully inspect servos for interference and broken gear.**
- ☆ **Check for missing or loose screws and nuts. See if there is any cracked and incomplete assembly of parts. Carefully check main rotor blades and rotor holders. Broken and premature failures of parts possibly cause resulting in a dangerous situation.**
- ☆ **Check all ball links to avoid excess play and replace as needed. Failure to do so will result in poor flight stability.**
- ☆ **Check the battery and power plug are fastened. Vibration and violent flight may cause the plug loose and result out of control.**
- ☆ **Please use 425~430mm carbon fiber/glass fiber main blades which are rated for 2800 RPM. Do not use wooden blades.**

- ★ 每次飛行前應先確認所使用的頻率是否會干擾他人，以確保你自身與他人的安全。
- ★ 每次飛行前確定您發射機與接收機電池的電量是在足夠飛行的狀態。
- ★ 開機前確認油門搖桿是否位於最低點，熄火降落開關，定速開關(IDLE)是否於關閉位置。
- ★ 關機時必須遵守電源開關機的程序，開機時應先開啓發射機後，再開啓接收機電源；關機時應先關閉接收機後，再關閉發射機電源。不正確的開關程序可能會造失控的現象，影響自身與他人的安全，請養成正確的習慣。
- ★ 開機請先確定直昇機的各個動作是否順暢，及方向是否正確，並檢查伺服器的動作是否有干涉或崩齒的情形，使用故障的伺服器將導致不可預期的危險。
- ★ 飛行前確認沒有缺少或鬆脫的螺絲與螺帽，確認沒有組裝不完整或損毀的零件，仔細檢查主旋翼是否有損壞，特別是接近主旋翼夾座的部位。損壞或組裝不完整的零件不僅影響飛行，更會造成不可預期的危險。注意：對損耗、有裂痕零件更新及定期保養檢查的重要性。
- ★ 檢查所有的連桿頭是否有鬆脫的情形，過鬆的連桿頭應先更新，否則將造成直昇機無法操控的危險。
- ★ 確認電池及電源接頭是否固定牢靠，飛行中的震動或激烈的飛行，可能造成電源接頭鬆脫而造成失控的危險。
- ★ 主旋翼務必慎選可耐用2800RPM 425~430mm長度碳纖維/玻纖維，嚴禁使用木製槳。

Standard Equipment 標準配備

							
500HC	500HH	500HB	500HT1	500HT	500HT3	500HG	500HZ
 M4x4 Set Screw x1 M4x4 止洩螺絲 x1 Motor Pinion Gear 13T x 1pc 馬達齒輪 13T x 1	 RCM-BL500MX 1600KV Brushless motor x 1 RCM-BL500MX 1600KV 無刷馬達 x 1	 RCE-BL70G Brushless ESC (Governor Mode) RCE-BL70G 無刷調速器 x 1	 DS510 Digital Servo x 3 DS510數位伺服器 x 3	 GP780 Herd Lock Gyro Combo GP780鎖定向陀螺儀組 (GP780+DS520)	 425 Carbon fiber blade x 1 425碳纖維主旋翼 x 1		

When you see the marks as below, please use glue or grease to ensure flying safety.

標有下符號之組裝步驟，請配合上膠或上油，以確保使用之可靠度。

- CA: Apply CA Glue to fix.**
- R48: Apply Anaerobics Retainer to fix.**
- T43: Apply Thread Lock to fix.**
- OIL: Add Grease.**

CA: 使用瞬間膠固定
R48: 使用金屬管狀固定缺氧膠固定
T43: 使用螺絲膠
OIL: 添加潤滑油



R48 metal tubular adhesive (eg. Bearings). T43 thread lock, apply a small amount on screws or metal parts and wipe surplus off. When disassembling, recommend to heat the metal joint about 15 Seconds. (NOTE: Keep plastic parts away from heat.)

R48 為強力金屬管狀(如軸承)接著劑，T43為螺絲膠，膠合螺絲或金屬內外徑請務必少量使用，必要時請用手去除多餘膠量，欲拆卸時可於金屬接合部位熱烤約15秒。(注意！塑膠件避免接近熱源)

When assembling ball links, make sure the "A" character faces outside.

各項塑膠製連桿頭扣接時，A字請朝外。

500HH2



When tightening linkage balls and screws to plastic parts, please note to tighten them firmly and the best tightening torque is within 4~4.5 kgf.cm. Do not over tighten, or the plastic parts will break off or the screws strip.

螺絲及球頭鎖入塑膠件請務必注意，適當扭力鎖緊即可，鎖入力道控制在4~4.5kgf.cm內為佳。若力道太大可能會造成塑膠件破裂或螺絲滑牙、斷裂。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.

原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

M3 collar screw
M3雙層軸套螺絲
M3x9.6mm

Metal main rotor housing
金屬主旋翼固定座

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

Bearing
軸承
φ4xφ7x2.5mm

Already assembled by Factory.
已組裝完成

Bearing
軸承
φ4xφ7x2.5mm

Already assembled by Factory.
已組裝完成

Pin
定位插梢
φ2x28mm

M3 collar screw
M3雙層軸套螺絲
M3x9.6mm

Flybar seesaw holder
平衡桿固定座

500HH3



500HH3A



Flybar rod
平衡翼桿
φ3x340mm

Linkage rod (B)
連桿(B)

Bearing
軸承
φ3xφ8x3mm

Already assembled by Factory.
已組裝完成

Washer
華司
φ3xφ4.8x0.3mm

Linkage ball A(T2.6x4.5)
球頭A(T2.6x4.5)
φ4.75x9.18mm

Bearing
軸承
φ3xφ6x2.5mm

Already assembled by Factory.
已組裝完成

Metal flybar control arm
金屬平衡翼控制臂

M3 Set screw
M3止淺螺絲
M3x4mm

Flybar control rod
平衡翼球型控制球桿
φ4.3x74.2mm

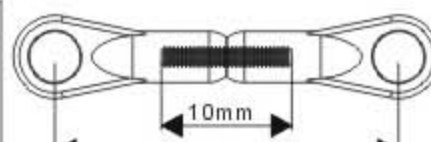
Collar
擺臂軸承襯套
φ3xφ4.5x1mm
Already assembled by Factory.
已組裝完成

SF Mixing arm
SF控制搖臂

Washer
華司
φ3xφ4.8x0.3mm

Socket screw
圓頭內六角螺絲
M2x5mm

Assemble linkage rod (B) before assembling flybar control set.
組裝平衡翼控制組先將連桿裝入。



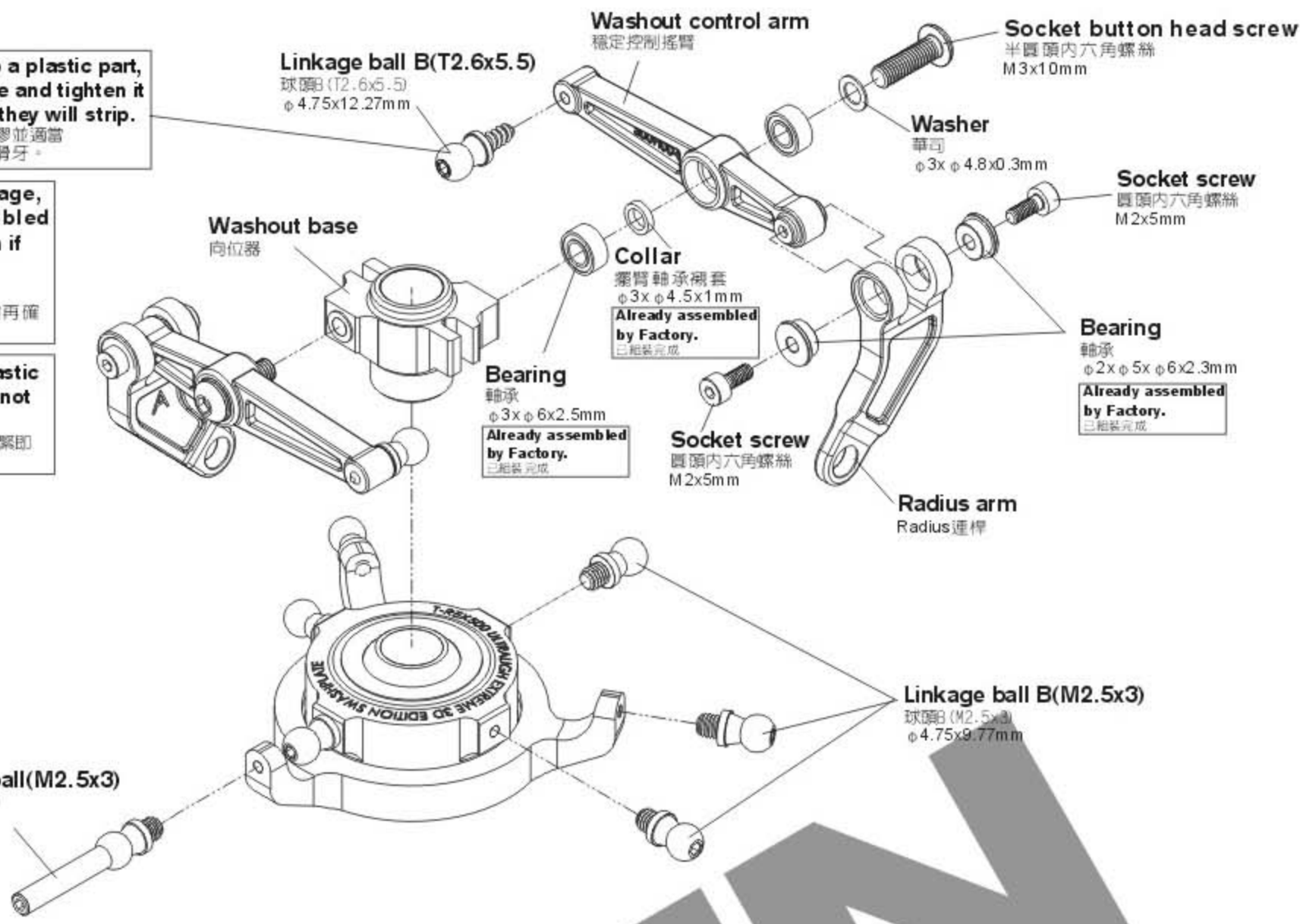
Socket button head self tapping screw
半圓頭內六角自攻螺絲
T3x12mm



When tightening a linkage ball to a plastic part, please note to use a little CA glue and tighten it firmly, but not over tightened, or they will strip.
球頭鎖入塑膠件請務必注意，使用少量CA膠並適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。



500HH4

- Socket collar screw
圓頭內六角軸套螺絲(M2.5x19mm) x 1
- M2.5 Nut
M2.5防鬆螺帽 x 1
- Socket button head screw
半圓頭內六角螺絲(M3x10mm) x 2
- Linkage ball B(T2.6x5.5)
球頭B(T2.6x5.5)(φ4.75x12.27mm) x 2
- Socket screw
圓頭內六角螺絲(M2x5mm) x 4

500HZ2

- 500 Linkage rod (C)
500連桿(C) φ1.96x34mm x 2

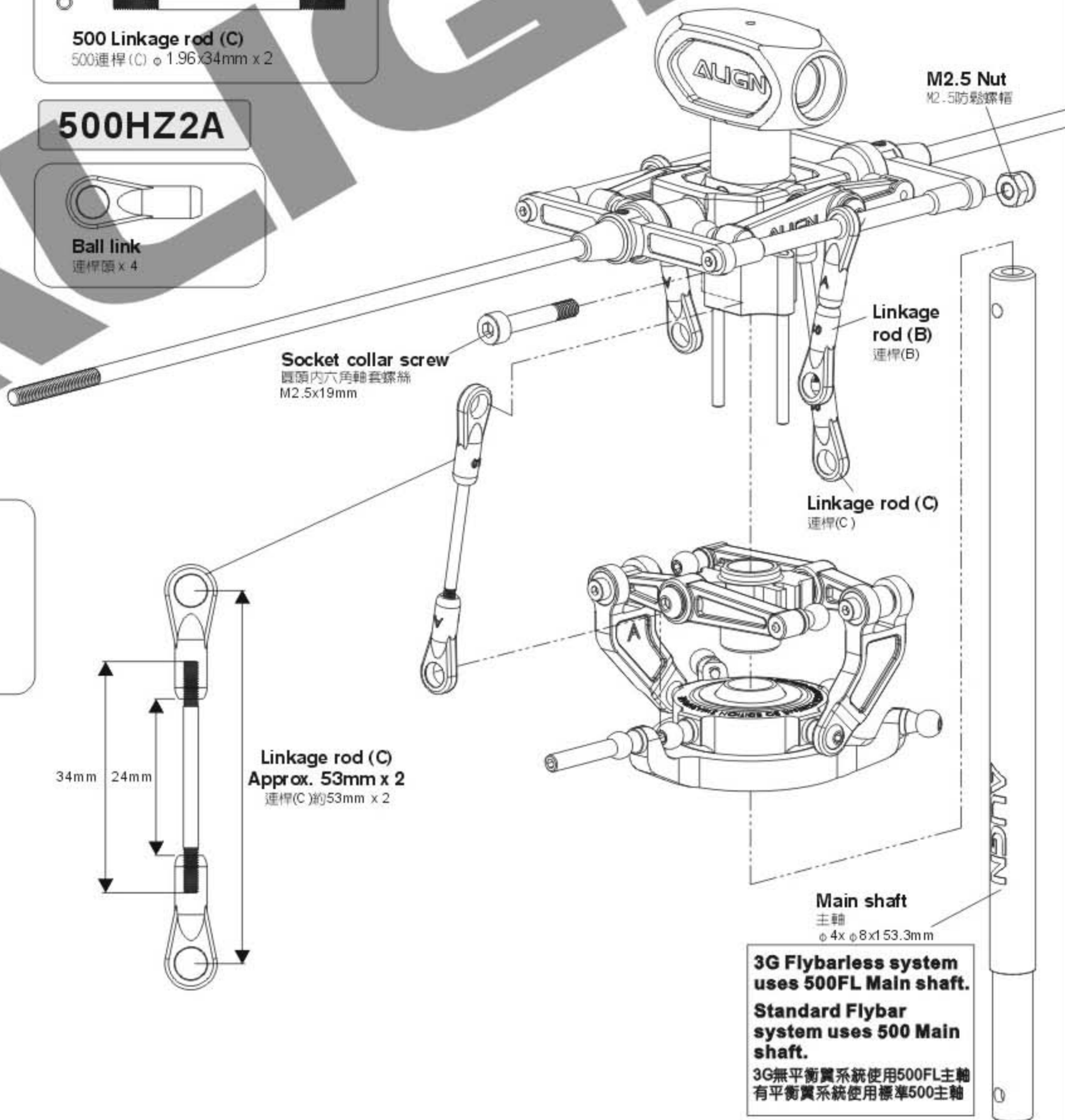
500HZ2A

- Ball link
連桿頭 x 4

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

500HH5

- Long linkage ball(M2.5x3)
導板長球頭(M2.5x3)(φ4.75x24.59mm) x 1
- Linkage ball B(M2.5x3)
球頭B(M2.5x3)(φ4.75x9.77mm) x 6



500HZ2

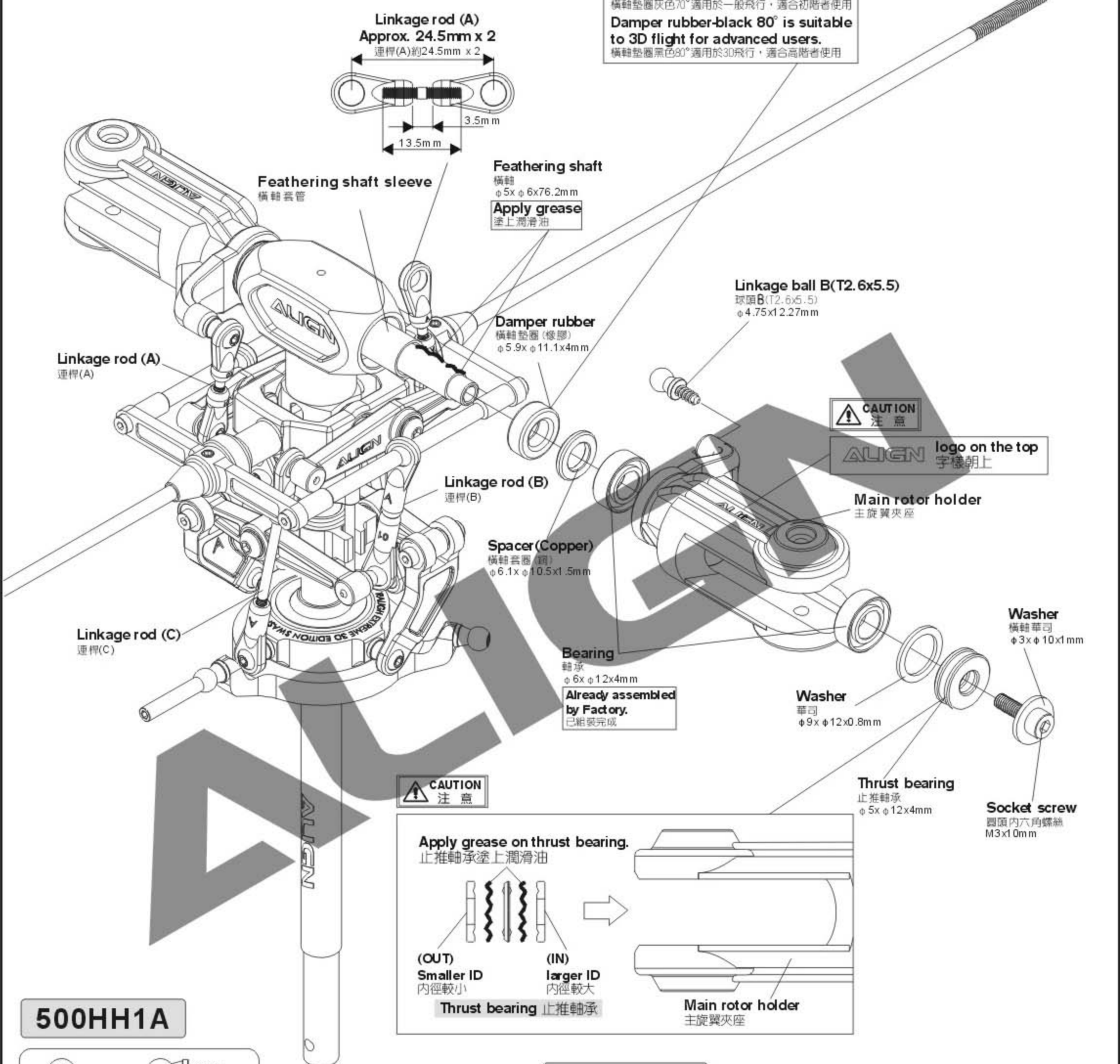
500HZ2A

Apply a little amount of T43 thread lock when fixing a metal part.
 螺絲鎖附於金屬件請使用適量T43(螺絲膠)

500 Linkage rod (A)
 500連桿(A) $\phi 1.96 \times 13.5 \text{mm} \times 2$

500 Ball link
 500連桿頭 $\times 4$

Damper rubber-gray 70° is suitable to general flight for beginners.
 橫軸墊圈灰色70°適用於一般飛行，適合初階者使用
Damper rubber-black 80° is suitable to 3D flight for advanced users.
 橫軸墊圈黑色80°適用於3D飛行，適合高階者使用



500HH1A

- Linkage ball B(T2.6x5.5)**
 球頭B(T2.6x5.5) ($\phi 4.75 \times 12.27 \text{mm}$) $\times 2$
- Thrust bearing**
 止推軸承($\phi 5 \times \phi 12 \times 4 \text{mm}$) $\times 2$
- Washer**
 華司($\phi 9 \times \phi 12 \times 0.8 \text{mm}$) $\times 2$

500HH2

- Socket screw**
 圓頭內六角螺絲(M3x10mm) $\times 2$
- Washer**
 橫軸華司($\phi 3 \times \phi 10 \times 1 \text{mm}$) $\times 2$

500HH2A

- Damper rubber-gray 70°**
 橫軸墊圈 灰色70° ($\phi 5.9 \times \phi 11.1 \times 4 \text{mm}$) $\times 2$
- Damper rubber-black 80°**
 橫軸墊圈 黑色80° ($\phi 5.9 \times \phi 11.1 \times 4 \text{mm}$) $\times 2$
- Spacer**
 橫軸套圈($\phi 6.1 \times \phi 10.5 \times 1.5 \text{mm}$) $\times 2$

CAUTION 注意
When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or it will strip.
 螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。
For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
 原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

Apply a little amount of T43 thread lock when fixing a metal part.
 螺絲鎖附於金屬件請使用適量T43(螺絲膠)

Socket screw
 圓頭內六角螺絲
 M2x8mm

Metal head stopper
 金屬旋翼頭制動器

Can choose to use or not use.
 可選擇使用或不使用

M3 Set screw
 M3止洩螺絲
 M3x4mm

Flybar paddle
 平衡翼

Flybar rod
 平衡翼桿
 φ3x340mm

500HH2A

Socket screw
 圓頭內六角螺絲(M2x8mm) x 1

500HH3A

M3 Set screw
 M3止洩螺絲(M3x4mm) x 2

CAUTION
 注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.

螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.

原廠零件出廠包裝如果是組裝品，請再確認各螺絲是否鎖緊上膠。

Approx. 108mm
 約108mm

Approx. 108mm
 約108mm

Flybar paddle
 平衡翼

Make sure both sides are equal in length.
 請保持平衡桿兩邊長度相等。

500HB1A

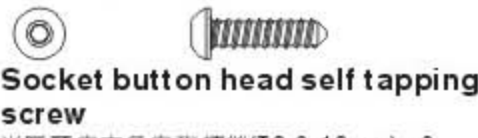


Bearing
軸承(φ8xφ16x5mm) x 2

500HB1B



Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x8mm) x 2



Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x10mm) x 6



Socket button head screw
半圓頭內六角螺絲(M2.5x10mm) x 8



Socket button head screw
半圓頭內六角螺絲(M3x6mm) x 4



M2.5 Specialty washer
M2.5特殊華司(φ2.5xφ6x2mm) x 16



Socket button head screw
半圓頭內六角螺絲(M2.5x8mm) x 2

500HG1



Socket screw
圓頭內六角螺絲(M2x10mm) x 4



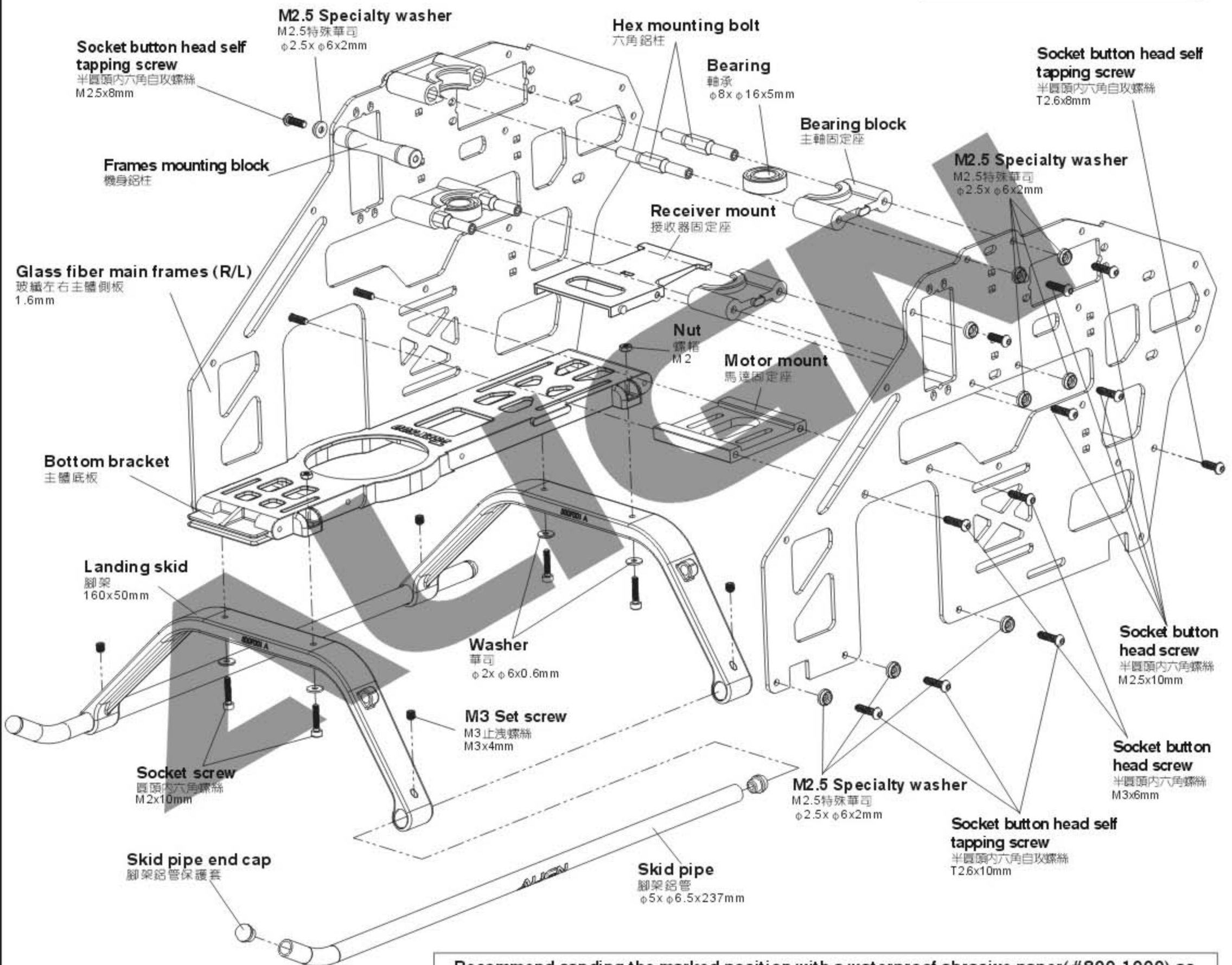
M3 Set screw
M3止洩螺絲(M3x4mm) x 4



Washer
華司(φ2xφ6x0.6mm) x 4

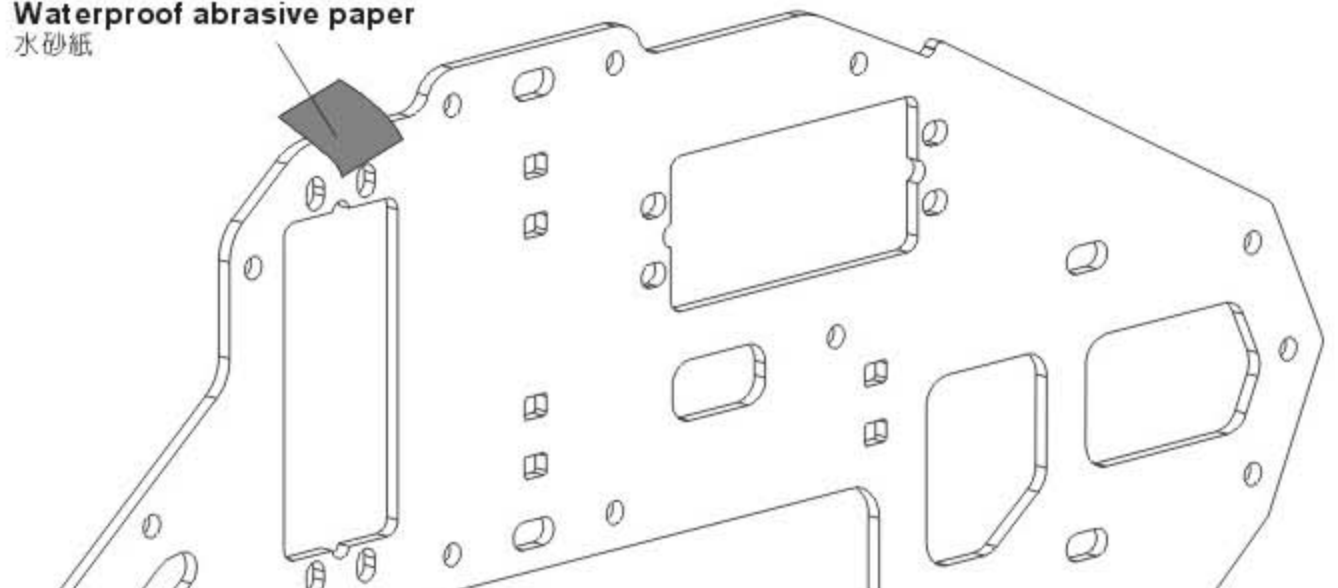


M2 Nut
M2螺帽 x 4



Recommend sanding the marked position with a waterproof abrasive paper(#800-1000) as below illustration to avoid the wires of electric parts to be cut.
建議於下圖色塊標示處，可使用#800-1000水砂紙打磨，可防止電子設備電線被割破。

Waterproof abrasive paper
水砂紙



CAUTION
注意

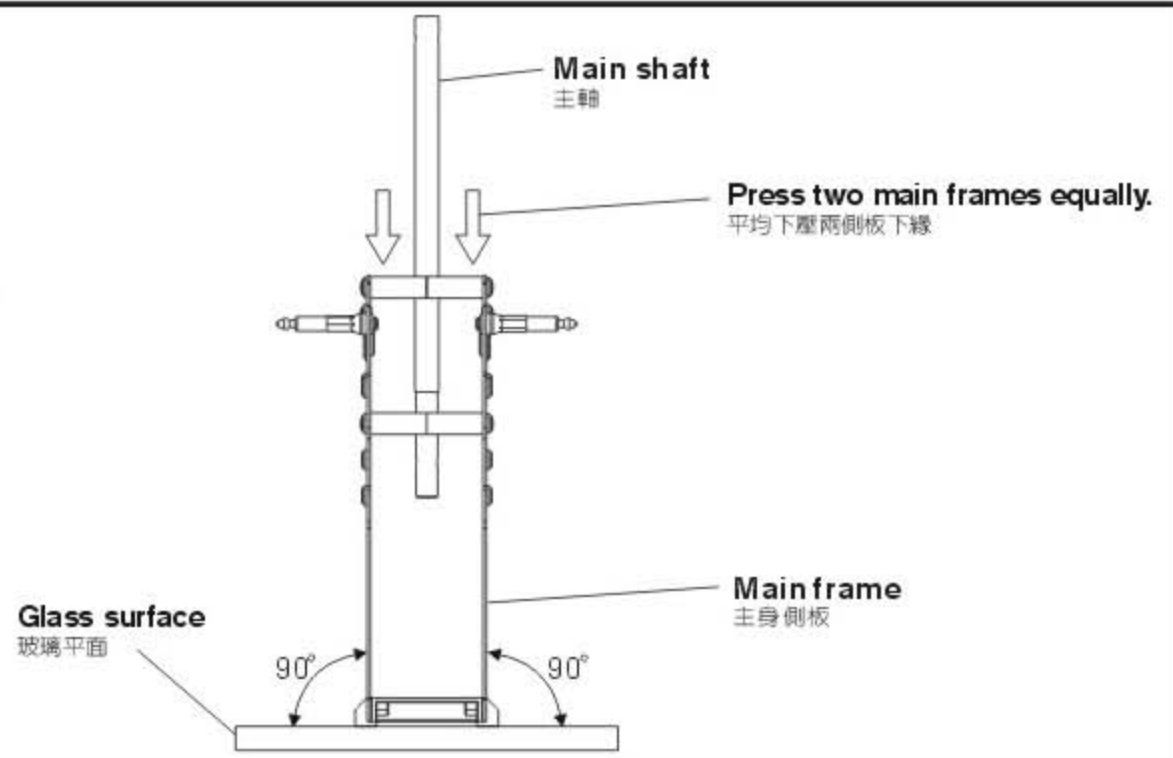
When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

Main frame assembly point:
First do not fully tighten the screws of main frames.
Put the main shaft through the two bearings and check if the movements (up/down) are smooth. The bottom bracket must be firmly touched the level table top (glass surface); please keep the smooth movements on main shaft and level bottom bracket, then slowly tighten the screws. A correct assembly can help for the power and flight performance.

機身側板組立重點：
 側板螺絲先不完全鎖緊，放入主軸貫穿二顆軸承確認上下移動必需滑順，主體底板必須與水平桌面（玻璃平面）踏實緊貼；請保持主軸滑順與底板平行桌面後慢慢鎖緊螺絲。正確側板的組裝對動力與飛行性能有顯著幫助。



Servo installation (DS3405/S9257/S9650)

伺服器安裝說明(DS3405/S9257/S9650)

500HB1B

Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x8mm) x 2

Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x14mm) x 2

500HZ3

Linkage ball A(M2x3.5)
球頭A(M2x3.5)(φ4.75x8.18mm) x 3

Linkage ball C(M2x4)
球頭C(M2x4)(φ4.75x13mm) x 3

Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x10mm) x 12

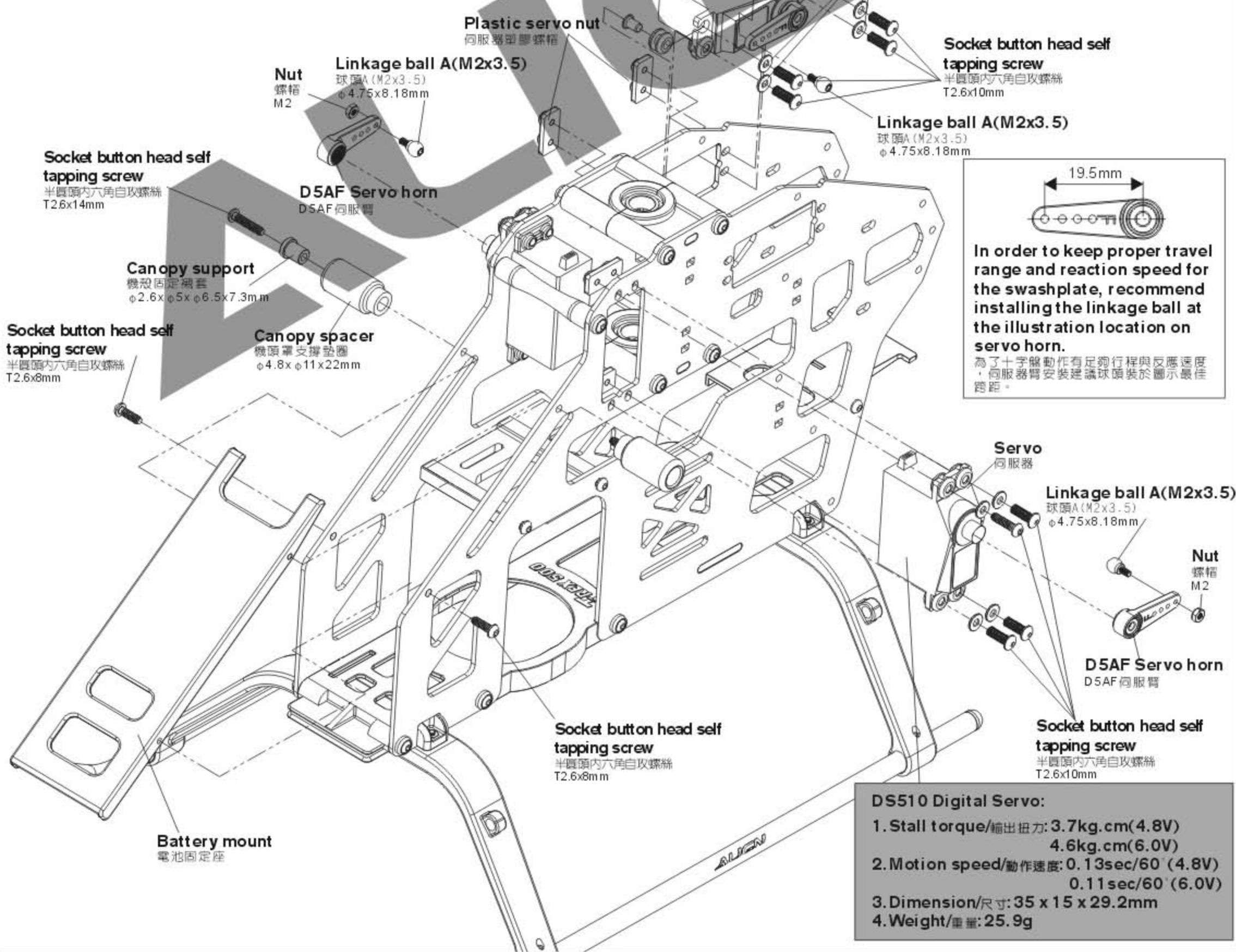
Washer
華司(φ2.6xφ5.8x0.6mm) x 12

M2 Nut
M2螺帽 x 3

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

CAUTION
注意
When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。



500HT1



Bearing

軸承 (φ4xφ9x4mm) x 2

500HT1A



Socket screw

圓頭內六角螺絲 (M3x10mm) x 2



M3 Nut

M3防鬆螺帽 x 2



Socket button head self tapping screw

半圓頭內六角自攻螺絲 (T2.6x10mm) x 8



M2.5 Specialty washer

M2.5特殊華可 (φ2.5xφ6x2mm) x 8

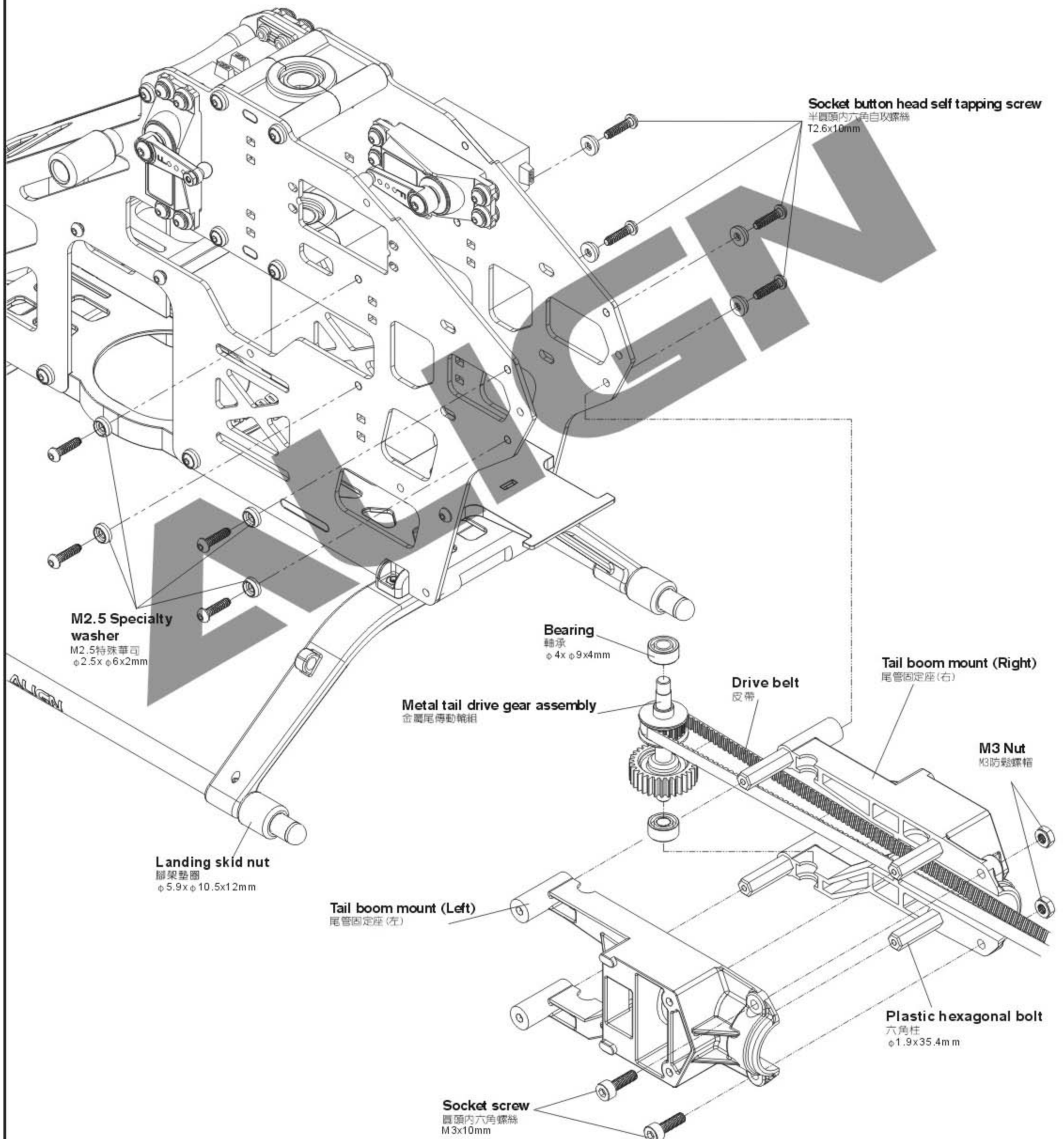
Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.

原廠零件出廠包裝如果是組裝品，請再確認各螺絲是否鎖緊上膠。



500HH4

M3 Set screw
M3止淺螺絲(M3x3mm) x 2

500HB1B

M2.5 Set screw
M2.5止淺螺絲(M2.5x12mm) x 2

500HB2

Hex socket self tapping screw
圓頭內六角自攻螺絲(T3x6mm) x 4

Washer
單向軸承華司(φ10xφ13x0.8mm) x 1

Socket collar screw
圓頭內六角軸套螺絲(M2.5x19mm) x 1

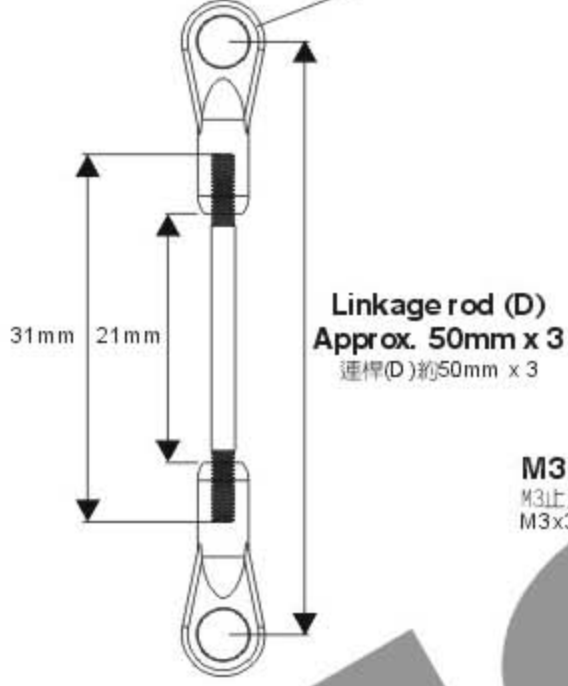
M2.5 Nut
M2.5防鬆螺帽 x 1

500HZ2

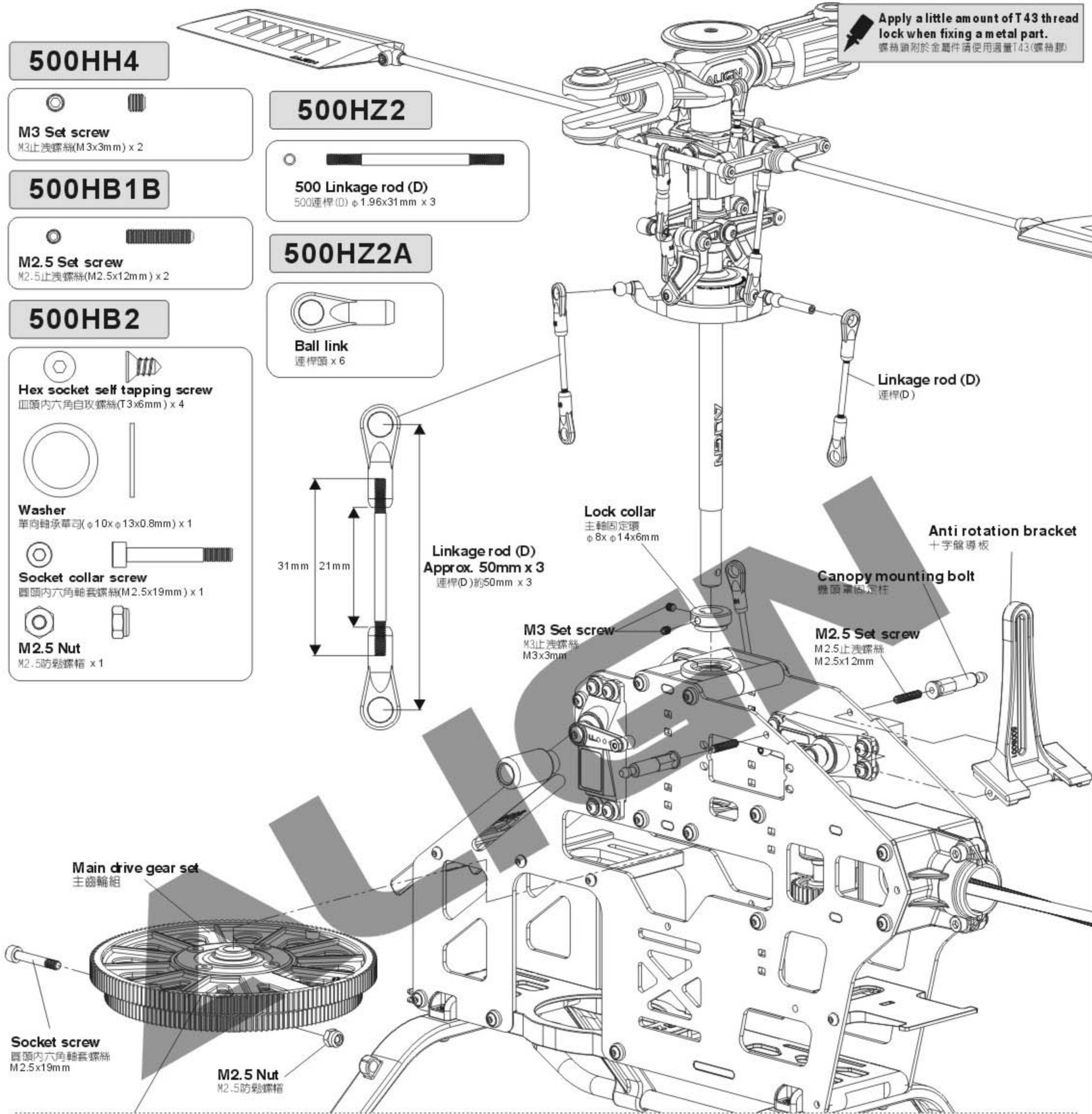
500 Linkage rod (D)
500連桿(D) φ1.96x31mm x 3

500HZ2A

Ball link
連桿頭 x 6



Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)



Autorotation tail drive gear
尾驅動主齒
145T

Main drive gear
主齒輪
162T

One-way bearing
單向軸承
φ10xφ14x12mm

Already assembled by factory,
please note to check again.
已組裝完成，請務必自行再確認。

Hex socket self tapping screw
圓頭內六角自攻螺絲
T3x6mm

Apply grease
塗上潤滑油

One-way bearing shaft
單向軸承套
φ7xφ10xφ12.6x27.25mm

Washer
單向軸承華司
φ10xφ13x0.8mm

Main gear case
主齒中心座

CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufacturer package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

Linkage rods A/B/C/D sizing and quantity reference chart

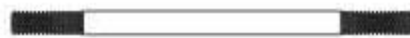
A/B/C/D連桿尺寸與數量對照圖



500 Linkage rod (A)
500連桿 (A) ϕ 1.96x13.5mm x 2



500 Linkage rod (B)
500連桿 (B) ϕ 1.96x10mm x 2



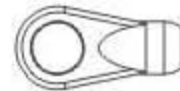
500 Linkage rod (C)
500連桿 (C) ϕ 1.96x34mm x 2



500 Linkage rod (D)
500連桿 (D) ϕ 1.96x31mm x 3



Ball link
連桿頭 x 14



500 Ball link
500連桿頭 x 4

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43 (螺絲膠)

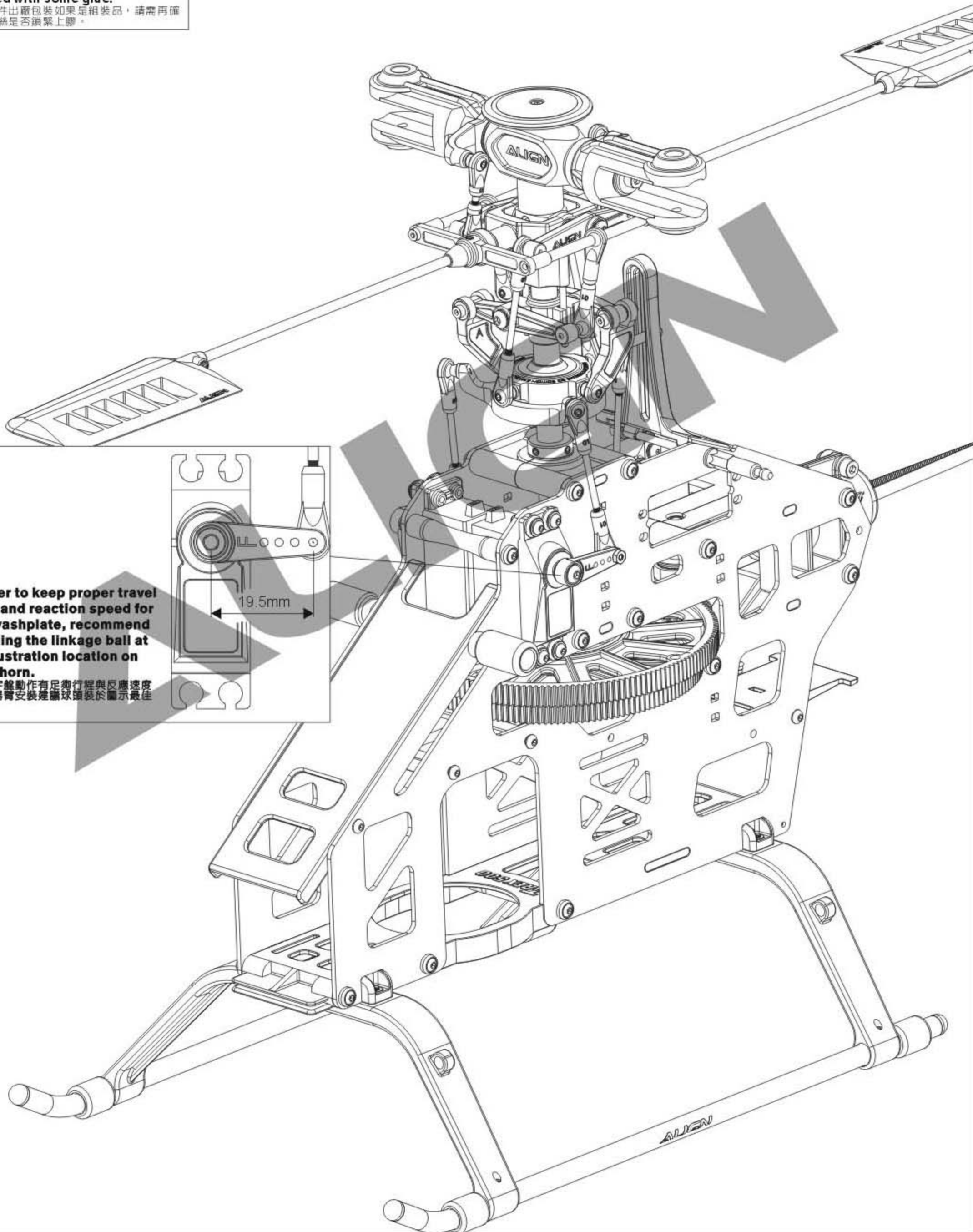
CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.

螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

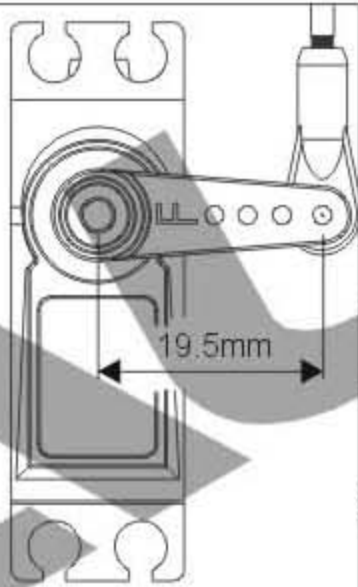
For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.

原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。



In order to keep proper travel range and reaction speed for the swashplate, recommend installing the linkage ball at the illustration location on servo horn.

為了十字盤動作有足夠行程與反應速度，伺服器背安裝連桿球頭於圖示最佳跨距。



500HZ3

Linkage ball A(M2x3.5)
球頭A(M2x3.5)(ϕ 4.75x8.18mm) x 1

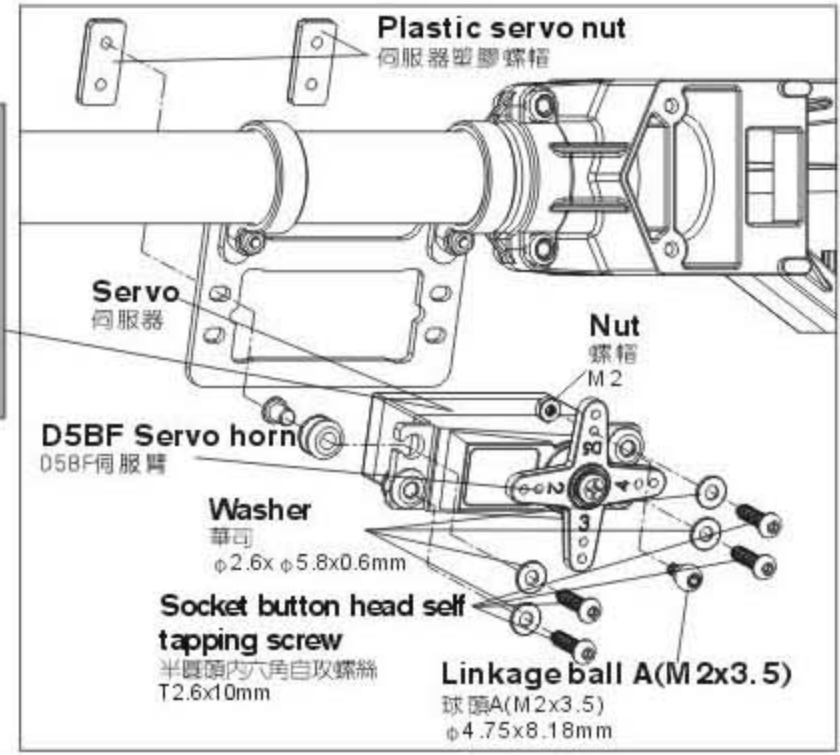
Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x10mm) x 4

Washer
華司(ϕ 2.6x ϕ 5.8x0.6mm) x 4

M2 Nut
M2螺帽 x 1

DS520 Digital Servo:

1. 1520 μ s standard band/1520 μ s 寬頻系統
2. Stall torque/輸出扭力: 1.9kg.cm(4.8V)
2.5kg.cm(6.0V)
3. Motion speed/動作速度: 0.09sec/60° (4.8V)
0.07sec/60° (6.0V)
4. Dimension/尺寸: 35 x 15 x 29.2mm
5. Weight/重量: 25.9g



After assembling the tail boom, please check if it is firmly tighten.
裝入尾管後請確實上緊

CAUTION
注意

Aim the opening of tail boom at the convex of the case and insert.
瞄準尾管上的凹槽和尾座凸出，並插入。

Please insert the opening of tail boom into the convex.
尾管缺口方向裝入時，請導入導尾管座卡榫內。

Tail boom
尾管 ϕ 15x ϕ 16x461mm

Rudder servo mount
尾伺服器固定座

Tail control guide
尾控制桿固定環

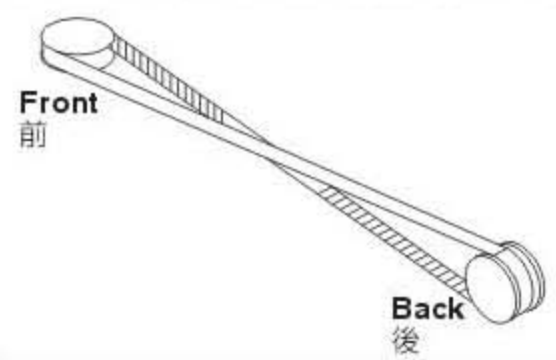
Socket button head self tapping screw
半圓頭內六角自攻螺絲 T2.6x10mm

Washer
華司 ϕ 2.6x ϕ 5.8x0.6mm

Glass fiber rudder servo bracket
玻璃纖維舵伺服器板

CAUTION
注意

Drive belt illustration 尾傳動皮帶裝配圖示



1. Check to rotate the belt 90 degrees when assembling.
2. Belt tension: Recommend to lightly tighten the drive belt after assembling tail boom to avoid vibration, belt friction and rotation slip.

1. 組裝時確認皮帶順轉90°。
2. 皮帶緊度：建議尾管組裝後皮帶請稍微拉緊，避免震動皮帶摩擦或轉動打滑。

Approx. 151mm
約151mm

Approx. 165mm
約165mm

500HT3C

Socket button head self tapping screw
半圓頭內六角自攻螺絲(T2.6x10mm) x 2

Washer
華司(ϕ 2.6x ϕ 5.8x0.6mm) x 2

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖劑於金屬件請使用適量T43(螺絲膠)

CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

500HT2A

500HT2DA



Socket button head screw
半圓頭內六角螺絲
M2.5x20mm

Washer
華司
φ2.6xφ5.8x0.6mm

Socket screw
圓頭內六角螺絲
M2.5x10mm

Tail case (R)
尾殼輪座(右)

M2.5 Nut
M2.5防鬆螺帽

Bearing 684ZZ
684ZZ軸承
φ4xφ9x4mm

Metal tail rotor shaft assembly
金屬尾旋翼主軸組

Glass fiber vertical stabilizer
玻纖垂直面翼

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

CAUTION
注意

Before/After assembling, please double check to avoid the drive belt bended or scraped to reduce the damage risk.
組裝前與後請檢查避免折彎或刮傷皮帶以降低損壞風險。

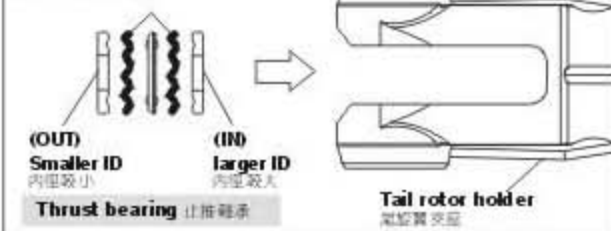
500HT2B

500HT2C



CAUTION
注意

Apply grease on thrust bearing.
止推軸承塗上潤滑油



Washer
華司
φ2xφ6x0.6mm

Socket screw
圓頭內六角螺絲
M2x6mm

Thrust bearing
止推軸承
φ3xφ8x3.5mm

Tail rotor holder
尾旋翼夾座

Bearing
軸承
φ5xφ9x3mm

Tail rotor hub
尾旋翼T型座
φ10x39.6mm

Collar B
尾連桿銅套B
φ2xφ3x3mm

Bearing
軸承
φ6xφ10x3mm

Bearing holder
尾翼控制組軸承套座

Collar
尾控制組軸承座鋁襯墊
φ6xφ7.4x2mm

Control link
尾控制連桿

Collar A
尾連桿銅套A
φ2xφ3x4mm

Bearing
軸承
φ6xφ10x3mm

T type arm
尾T型控制臂

Collar screw
軸套螺絲
M2x8mm

Slide shaft
尾軸滑套
φ4xφ7x15.2mm

Linkage ball A (T2.6x3.5)
球頭A (T2.6x3.5)
φ4.75x8.18mm

CAUTION
注意

While assembly the slide shaft, please use suitable amount of T43 on the thread. Please do not use R48 anaerobics retainer or other high strength glue to avoid damages while maintenance or repairs.
組立尾軸滑套時，請使用適量的T43螺絲膠在螺牙上，嚴禁使用R48高膠合性軸承膠防止膠合過緊，以避免日後拆修維護零件之損傷。

500HT2DA

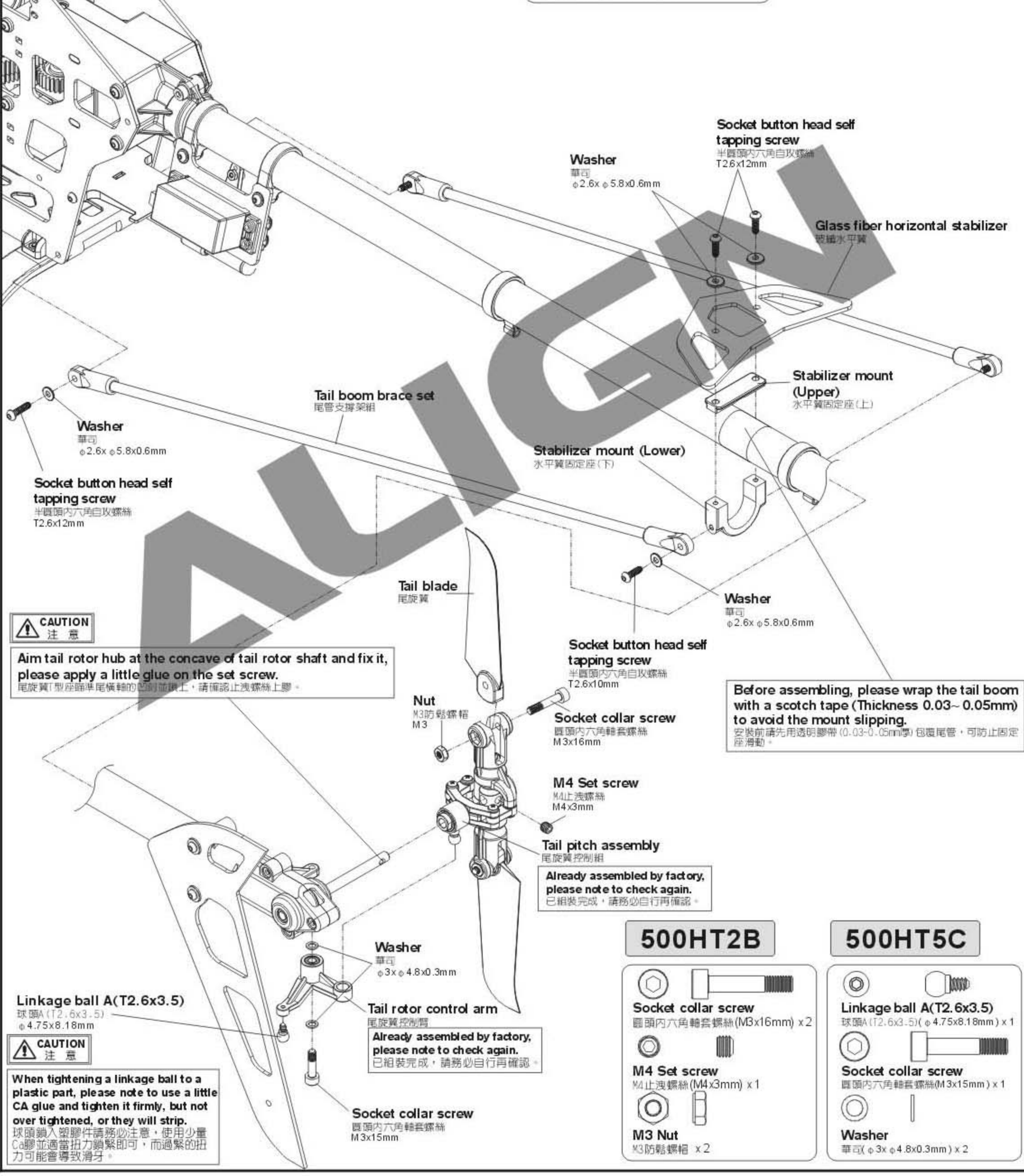
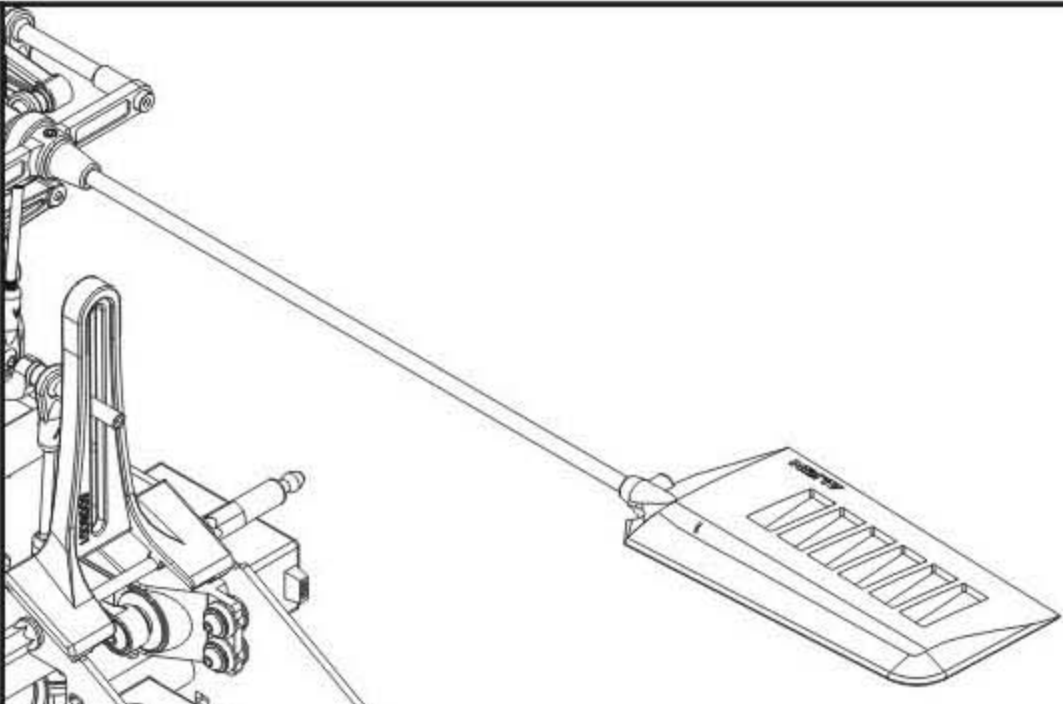
Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖附於金屬件請使用適量T43(螺絲膠)

CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original factory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

-  **Socket button head self tapping screw**
半圓頭內六角自攻螺絲(T2.6x12mm) x 4
-  **Socket button head self tapping screw**
半圓頭內六角自攻螺絲(T2.6x10mm) x 2
-  **Washer**
華司(φ2.6xφ5.8x0.6mm) x 6



Socket button head self tapping screw
半圓頭內六角自攻螺絲 T2.6x12mm

Washer
華司 φ2.6xφ5.8x0.6mm

Glass fiber horizontal stabilizer
玻璃水平翼

Tail boom brace set
尾管支撐架組

Stabilizer mount (Upper)
水平翼固定座(上)

Stabilizer mount (Lower)
水平翼固定座(下)

Washer
華司 φ2.6xφ5.8x0.6mm

Socket button head self tapping screw
半圓頭內六角自攻螺絲 T2.6x12mm

Tail blade
尾旋翼

Washer
華司 φ2.6xφ5.8x0.6mm

Socket button head self tapping screw
半圓頭內六角自攻螺絲 T2.6x10mm

Socket collar screw
圓頭內六角軸套螺絲 M3x16mm

M4 Set screw
M4止洩螺絲 M4x3mm

Tail pitch assembly
尾旋翼控制組

Already assembled by factory, please note to check again.
已組裝完成，請務必自行再確認。

Before assembling, please wrap the tail boom with a scotch tape (Thickness 0.03~0.05mm) to avoid the mount slipping.
安裝前請先用透明膠帶(0.03-0.05mm厚)包覆尾管，可防止固定座滑動。

CAUTION
注意

Aim tail rotor hub at the concave of tail rotor shaft and fix it, please apply a little glue on the set screw.
尾旋翼T型座與尾旋翼軸的凹面鎖上，請確認止洩螺絲上膠。

Linkage ball A(T2.6x3.5)
球頭A(T2.6x3.5) φ4.75x8.18mm

CAUTION
注意

When tightening a linkage ball to a plastic part, please note to use a little CA glue and tighten it firmly, but not over tightened, or they will strip.
球頭鎖入塑膠件請務必注意，使用少量CA膠並適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

Washer
華司 φ3xφ4.8x0.3mm

Tail rotor control arm
尾旋翼控制臂

Already assembled by factory, please note to check again.
已組裝完成，請務必自行再確認。

Socket collar screw
圓頭內六角軸套螺絲 M3x15mm

500HT2B

-  **Socket collar screw**
圓頭內六角軸套螺絲(M3x16mm) x 2
-  **M4 Set screw**
M4止洩螺絲(M4x3mm) x 1
-  **M3 Nut**
M3防鬆螺帽 x 2

500HT5C

-  **Linkage ball A(T2.6x3.5)**
球頭A(T2.6x3.5) (φ4.75x8.18mm) x 1
-  **Socket collar screw**
圓頭內六角軸套螺絲(M3x15mm) x 1
-  **Washer**
華司(φ3xφ4.8x0.3mm) x 2

Apply a little amount of T43 thread lock when fixing a metal part.
螺絲鎖劑於金屬件請使用適量T43 (螺絲膠)

CAUTION
注意

When tightening a screw to a plastic part, please tighten it firmly, but not over tightened, or they will strip.
螺絲鎖入塑膠件請務必注意，適當扭力鎖緊即可，而過緊的扭力可能會導致滑牙。

For original manufactory package, if the product is already assembled by Factory, please check again if screws are firmly secured and applied with some glue.
原廠零件出廠包裝如果是組裝品，請需再確認各螺絲是否鎖緊上膠。

Socket collar screw
圓頭內六角軸套螺絲
M3x22mm

425 Carbon fiber blade
425碳纖主旋翼

500HH1A



Socket collar screw

圓頭內六角軸套螺絲(M3x22mm) x 2

M3 Nut

M3防鬆螺帽 x 2

500HZ5



M4 Set screw

M4止洩螺絲(M4x4mm) x 1



Socket collar screw

圓頭內六角軸套螺絲(M3x10mm) x 2



M3 Washer

M3華司(φ3xφ8x1mm) x 2

Motor pinion gear 13T
馬達齒輪 13T

M4 Set screw
M4止洩螺絲
M4x4mm

Motor
馬達
1600kV

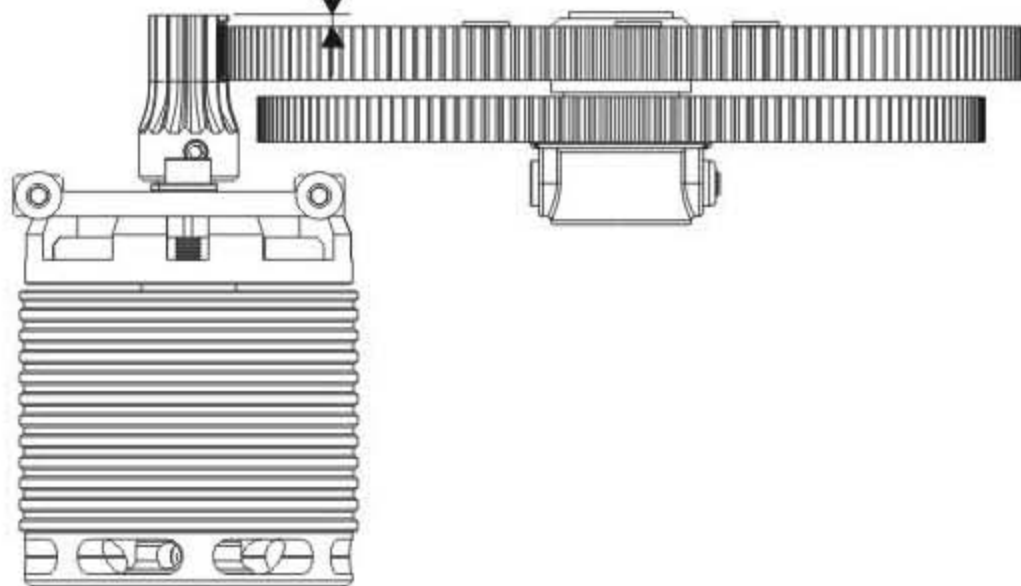
Sticker
平衡翼貼紙

Socket screw
圓頭內六角螺絲
M3x10mm

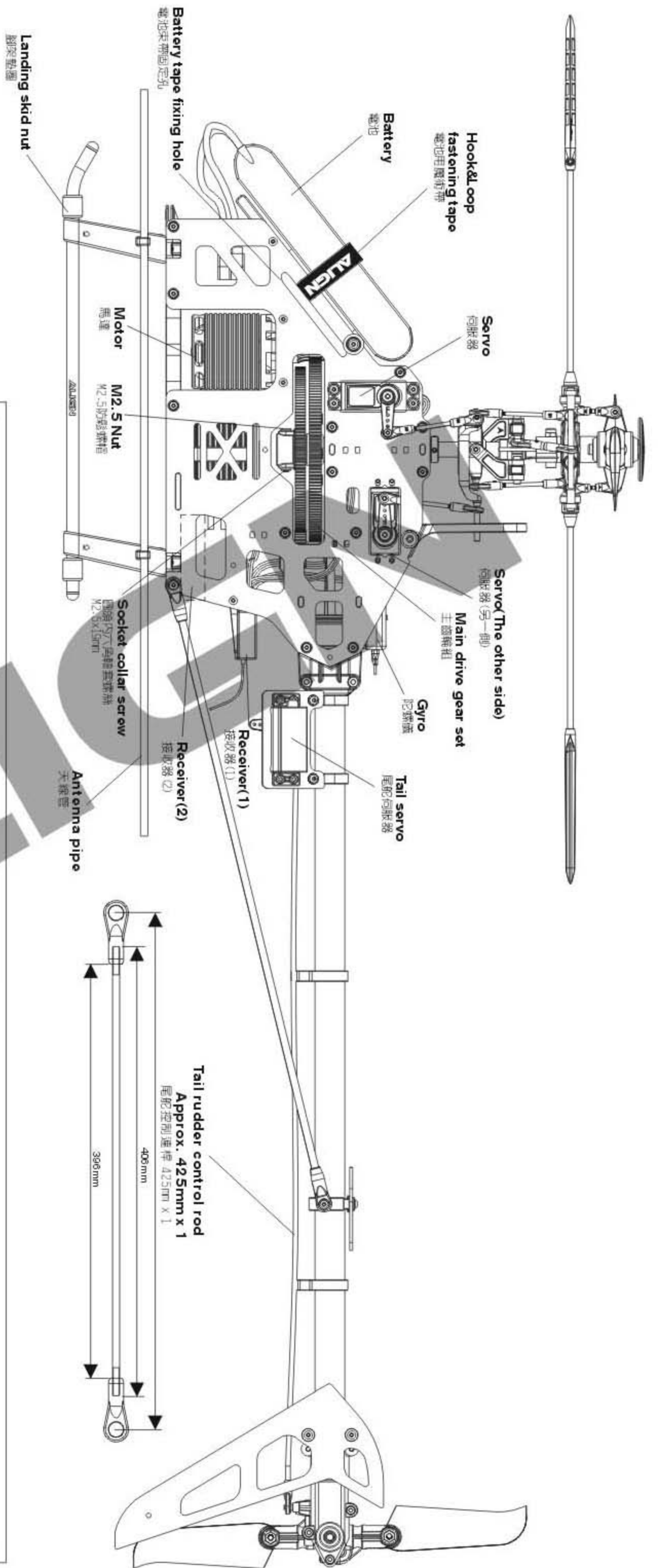
For motor fixing
馬達固定螺絲

M3 Washer
M3華司
φ3xφ8x1mm

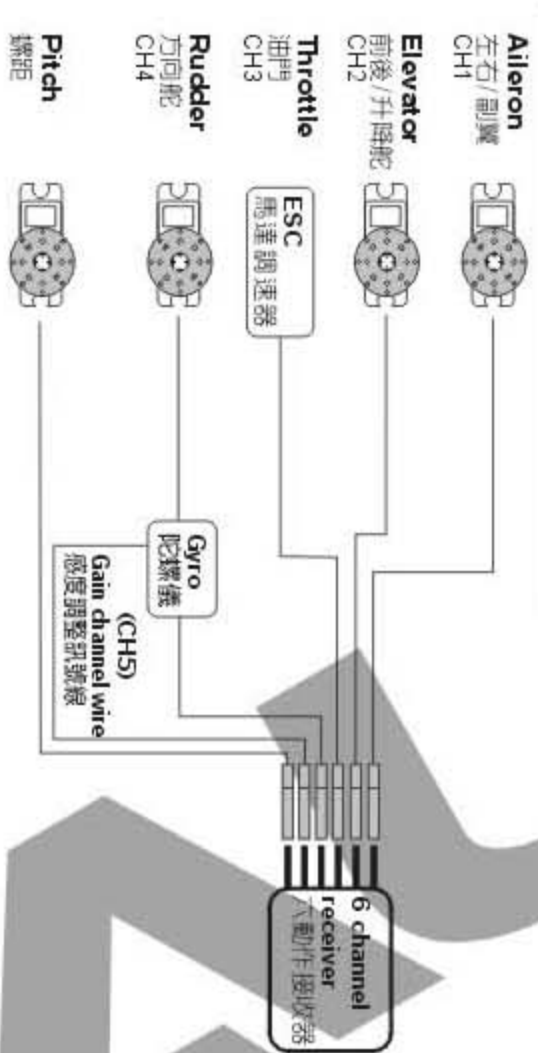
After assembling the motor pinion gear and main drive gear, the horizontal distance must be within 1mm and keep the gear mesh at a proper distance.
馬達齒輪與主齒盤組立後平行距離不可超過1mm，並保持兩齒咬合有適當間距。



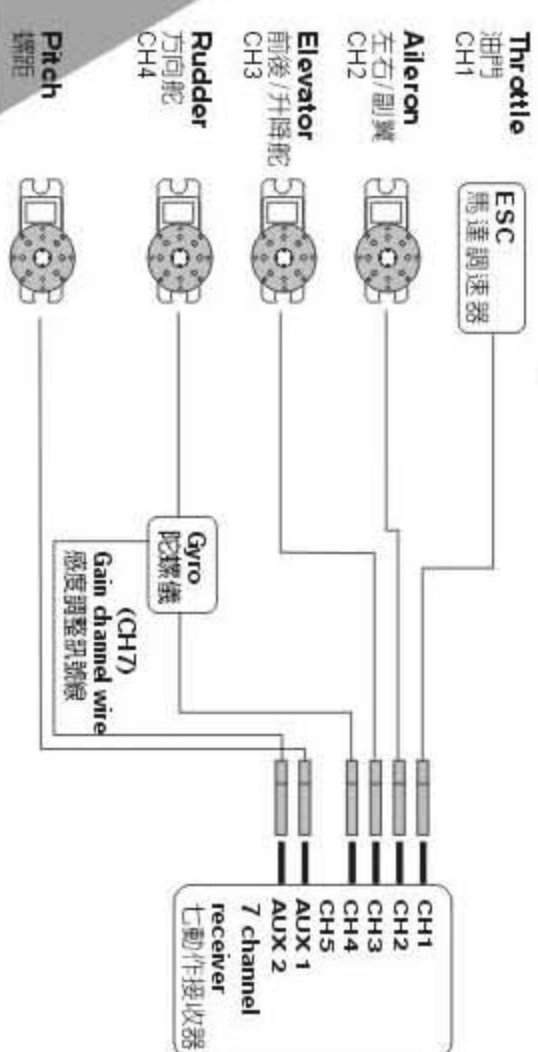
When fixing the screw of pinion gear, please aim at the fixing point on motor shaft.
馬達齒輪固定螺絲鎖緊時，請對準馬達心軸固定槽。



HITEC, FUTABA 6CH receiver wiring
HITEC, FUTABA 6CH接收器接線示意圖



JR 7CH receiver wiring
JR 7CH接收器接線示意圖

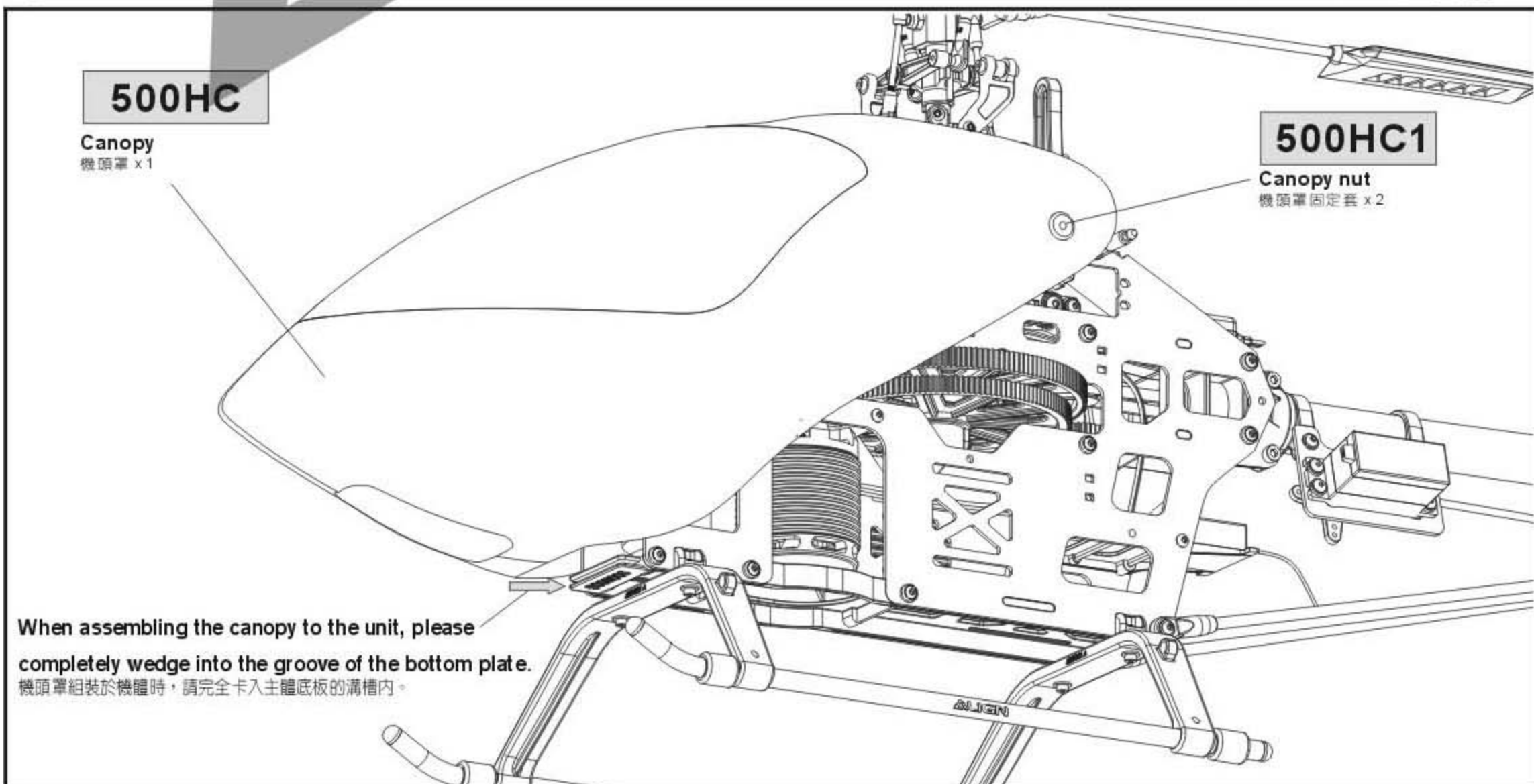
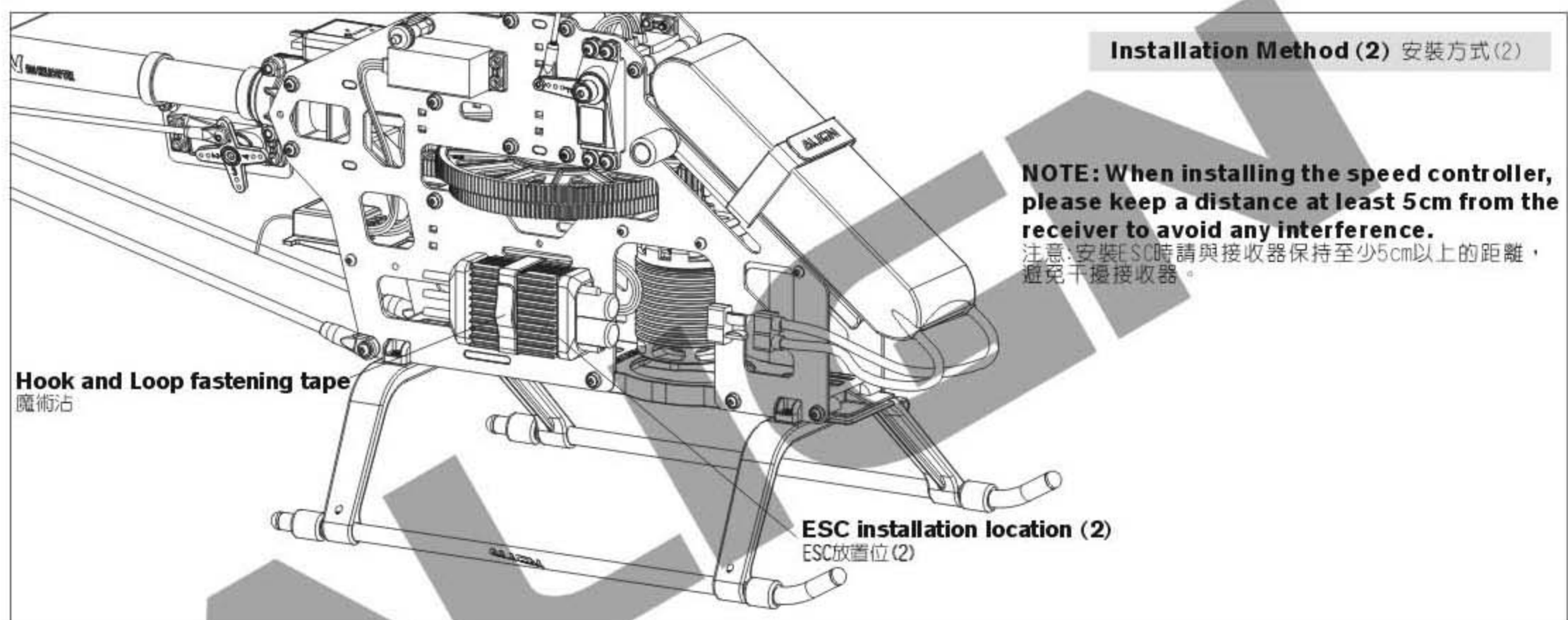
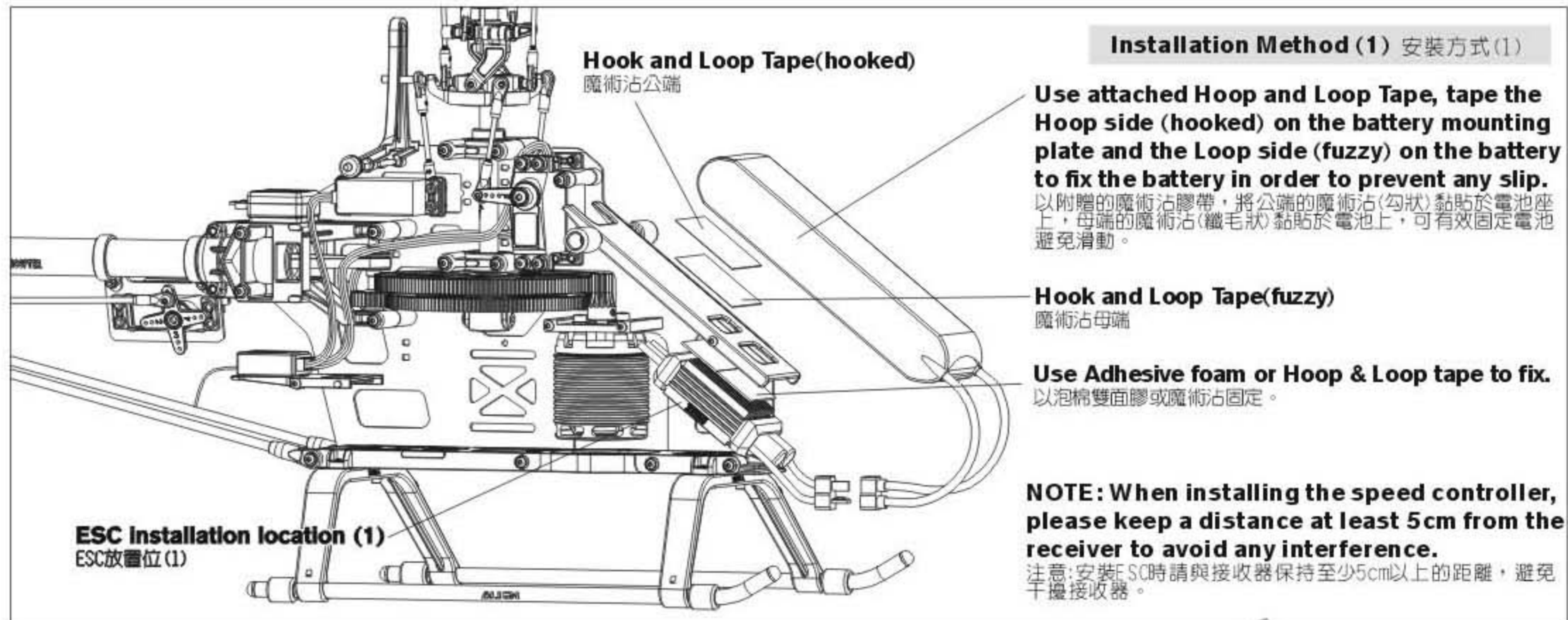


6-Channel Receiver is adequate for the requirements of T-REX helicopter. You will need the following channels at a minimum: Throttle, Rudder, Elevator, Aileron, and especially Pitch(CH6) and Gyro(CH5) controls.

六動作的接收器已足夠應對T-REX遙控直升機的所有頻道需求，除了油门、方向舵、升降舵、副翼等基本動作外，亦可以對應具備感度調整訊號線的陀螺儀(CH5)與螺距(CH6)。

7-Channel Receiver is adequate for the requirements of T-REX helicopter. You will need the following channels at a minimum: Throttle, Rudder, Elevator, Aileron, and especially Pitch(AUX 1) and Gyro(AUX 2) controls.

七動作的接收器已足夠應對T-REX遙控直升機的所有頻道需求，除了油门、方向舵、升降舵、副翼等基本動作外，亦可以對應具備感度調整訊號線的陀螺儀(AUX 2)與螺距(AUX 1)。



To set this option is to turn on the transmitter and connect to the helicopter power. Note: For the safety, please do not connect ESC to the brushless motor before the setting in order to prevent any accident caused by the motor running during the setting.

此項設定只要開啓發射器，接上直昇機電源即可進行操作。注意：為了安全起見，設定前請先不要將無刷調速器與無刷馬達的三條線接上，以免調整時啓動馬達而發生危險。

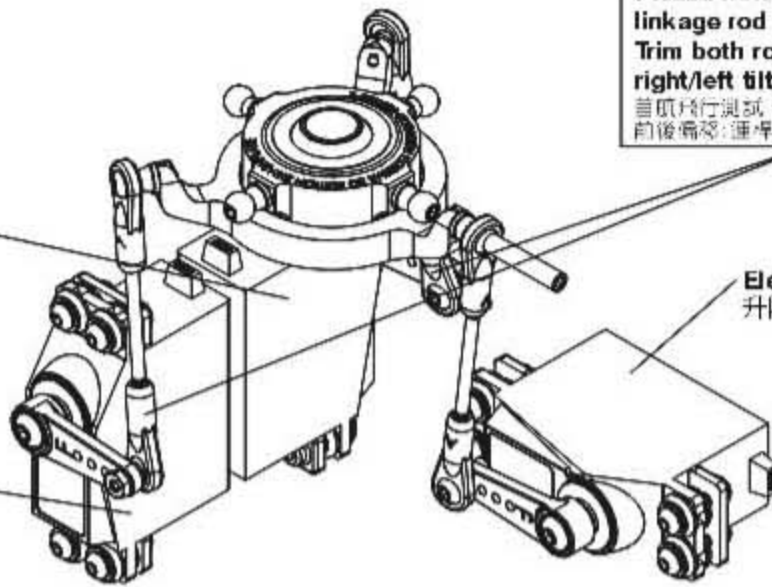
JR Transmitter/Servo
JR遙控器對應伺服器關係

Pitch:CH6
螺距:CH6

Aileron:CH2
副翼:CH2

Aileron:CH2
副翼:CH2

Pitch:CH6
螺距:CH6



Please note to set the subtrim neutral for the first trial flight. If the helicopter wags, please trim linkage rod (D). Trim both rods (D) simultaneously to adjust for forward/backward tilt. Trim rod (D) separately for right/left tilt.

首次飛行測試，注意遙控器微調均設定中立點，若發現飛行時，機身前後左右偏移，請先調整連桿(D)前後偏移，連桿(D)同步調整，左右偏移，連桿(D)單獨調整至標準。

Positions of CH2 · CH6 are exchangeable, After assembling as photo (Note:Set the transmitter under CCPM 120 degrees mode), pull throttle stick (pitch) upward. If one swashplate servo (or two servos) moves downward, adjust reverse switch (REV) on the transmitter to make it moves upward. If three servo move downward, adjust the travel value (+) of SWASH CH6 on the transmitter to make them move upward. When the actions of Aileron and Elevator are opposite, adjust travel values of SWASH CH2 and CH3.

CH2 · CH6可互換配置，依圖連結後(注意：遙控器須設定於CCPM 120°十字盤模式)，將油門搖桿(Pitch)往上推，若十字盤伺服器有1個或2個往下移動時，請調整遙控器的反轉開關(REV)使伺服器往上，若3個伺服器同時往下移動時，請調整遙控器 SWASH CH6 行程量的正負值，使伺服器同時往上升移，副翼與前後動作相反時，同樣調整 SWASH CH2 · CH3 行程量正負值。

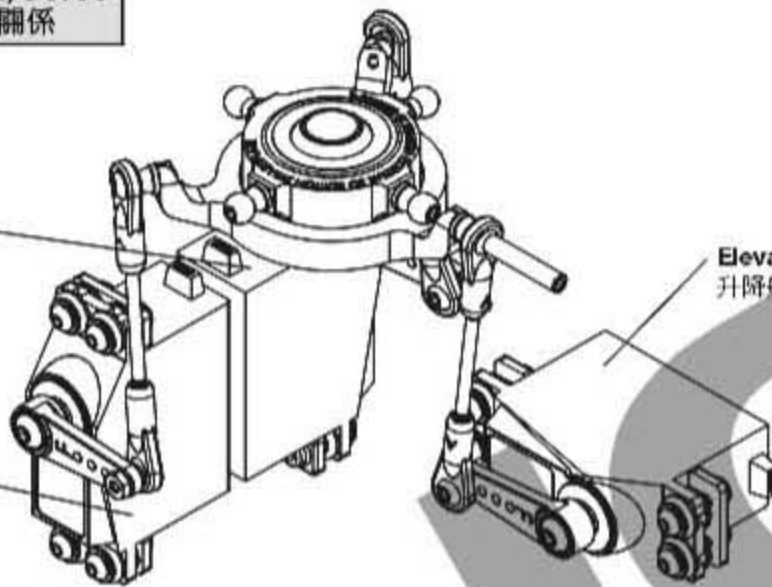
FUTABA/HITEC Transmitter/Servo
FUTABA/HITEC遙控器對應伺服器關係

Pitch:CH6
螺距:CH6

Aileron:CH1
副翼:CH1

Aileron:CH1
副翼:CH1

Pitch:CH6
螺距:CH6



Positions of CH1 · CH6 are exchangeable, After assembling as photo (Note:Set the transmitter under CCPM 120 degrees mode), pull throttle stick (pitch) upward. If one swashplate servo (or two servos) moves downward, adjust reverse switch (REV) on the transmitter to make it moves upward. If three servo move downward, adjust the travel value (+) of SWASH CH6 on the transmitter to make them move upward. When the actions of Aileron and Elevator are opposite, adjust travel values of SWASH CH1 and CH2.

CH1 · CH6可互換配置，依圖連結後(注意：遙控器須設定於CCPM 120°十字盤模式)，將油門搖桿(Pitch)往上推，若十字盤伺服器有1個或2個往下移動時，請調整遙控器的反轉開關(REV)使伺服器往上，若3個伺服器同時往下移動時，請調整遙控器 SWASH CH6 行程量的正負值，使伺服器同時往上升移，副翼與前後動作相反時，同樣調整 SWASH CH1 · CH2 行程量正負值。

11.ADJUSTMENTS FOR GYRO AND TAIL NEUTRAL SETTING 陀螺儀與尾翼中立點設定調整

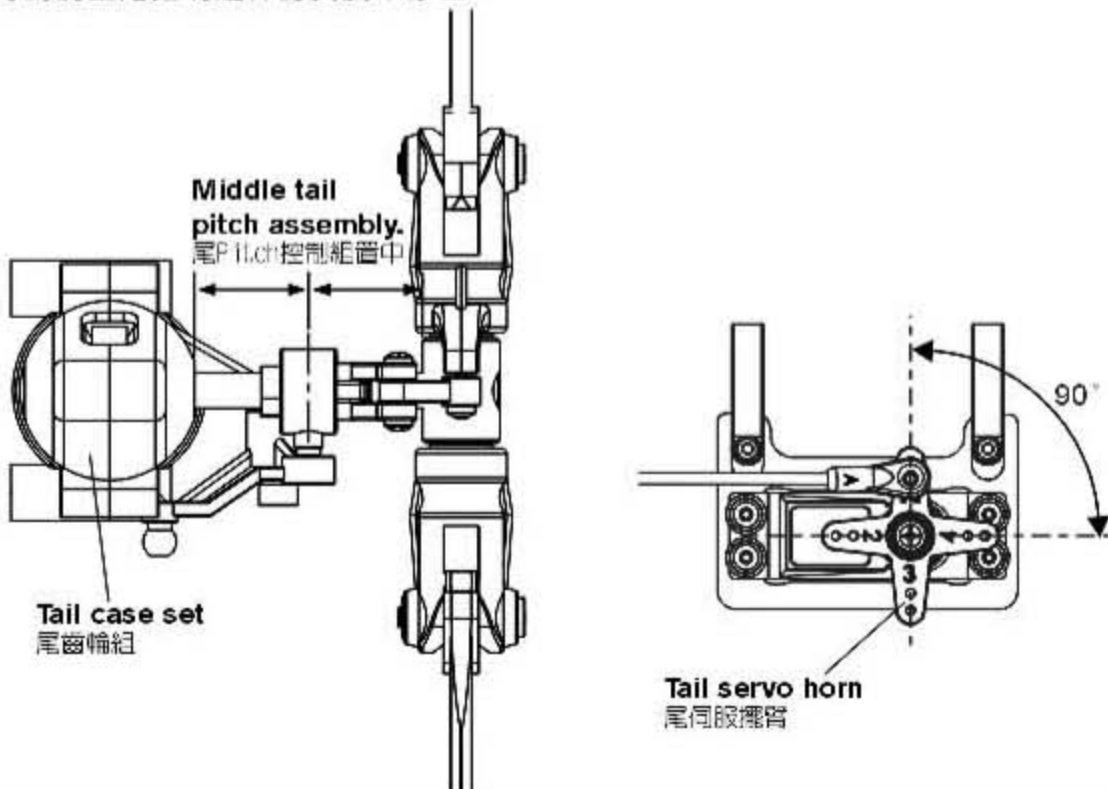
Recommend to choose Head Lock type for Gyro and turn off Revolution mixing(RVMX) mode on the transmitter, then set the gain switch on the transmitter and the gyro to Head lock mode. The gain setting is about 70%, and after transmitter setting, connect to the helicopter power for working on tail neutral setting. Note: When connecting to the helicopter power, please do not touch tail rudder stick and the helicopter. Then wait for 3 seconds, make tail servo horn and tail servo at a right angle(90 degrees), tail pitch assembly must be correctly fixed about in the middle of the travel of tail rotor shaft for standard neutral setting.

陀螺儀選擇，建議選用鎖定式陀螺儀，且發射器內陀螺儀設定請關閉根軸混控模式，並將發射器上的感度開關與陀螺儀切至鎖定模式，感度設約 70% 左右，發射器設定完成後接上直昇機電源，即可進行尾中立點設定。注意：當接上直昇機電源時請勿撥動尾舵搖桿或碰觸機體，待3秒陀螺儀鎖定後尾伺服器需與尾伺服器約成 90°，尾旋翼控制組須正確置於尾橫軸行程約中間位置，即為標準尾中立點設定。

TAIL NEUTRAL SETTING 尾中立點設定

After setting Head Lock mode, correct setting position of tail servo and tail pitch assembly is as photo. If the tail pitch assembly is not in the middle position, please adjust the length of rudder control rod to trim.

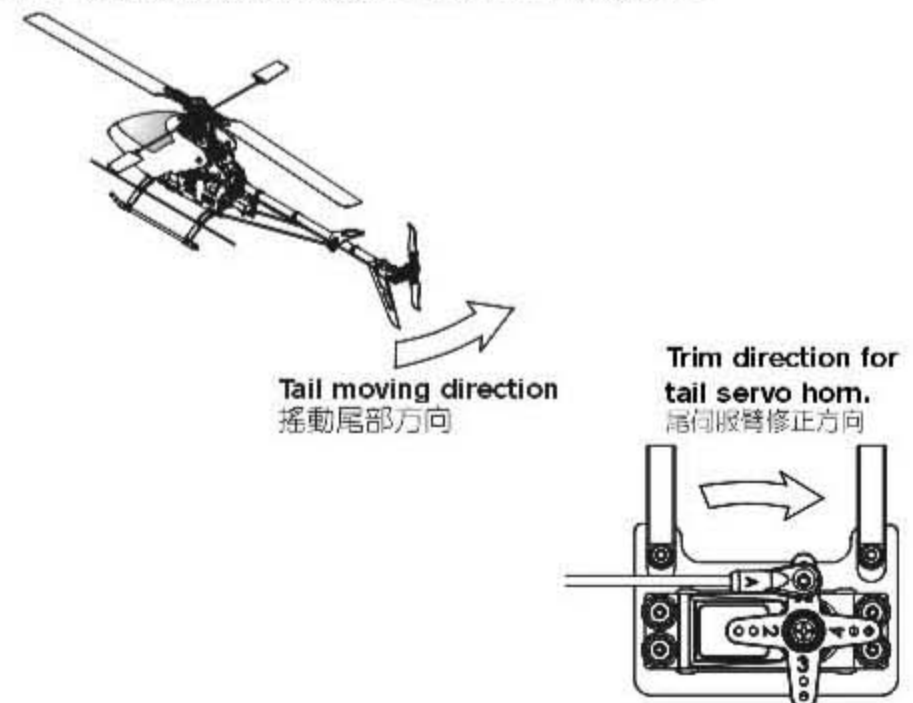
陀螺儀鎖定後尾伺服器與尾 Pitch控制組正確擺置位置。若尾 Pitch控制組未置中時請調整尾控制連桿的長度來修正。



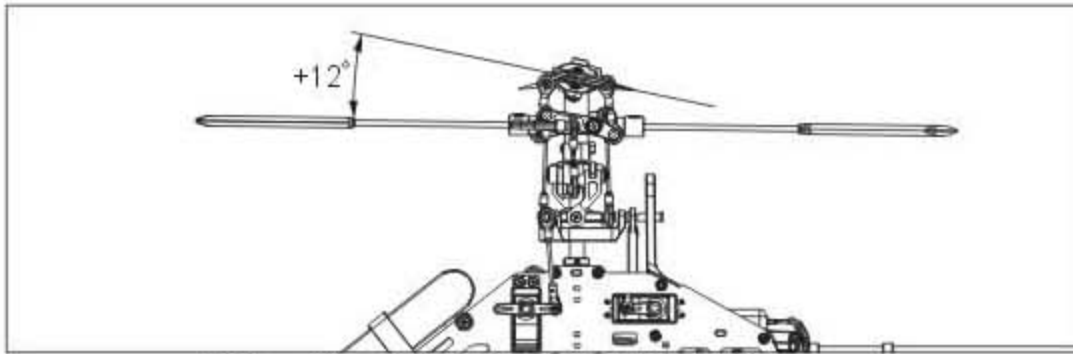
HEAD LOCK DIRECTION SETTING OF GYRO 陀螺儀鎖定方向設定

To check the head lock direction of gyro is to move the tail counterclockwise and the tail servo horn will be trimmed clockwise. If it trims in the reverse direction, please switch the gyro to "REVERSE".

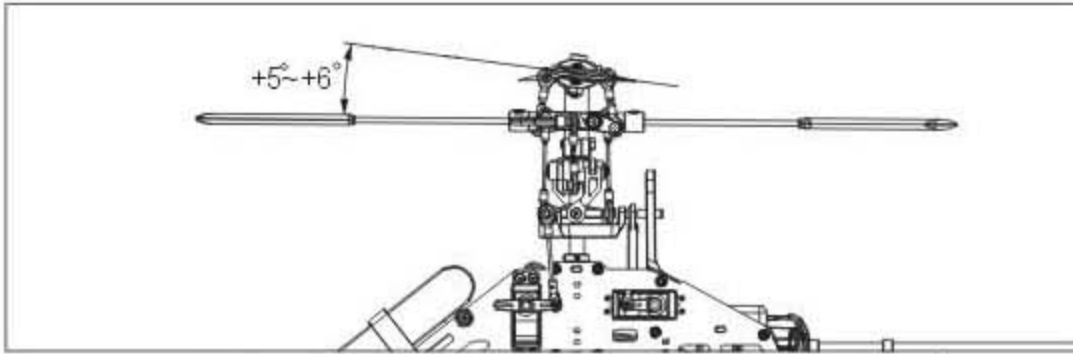
陀螺儀鎖定方向確認，當手搖尾部反時鐘擺動，尾伺服器應順時鐘修正，反向時請切換陀螺儀上"鎖定反向"開關修正。



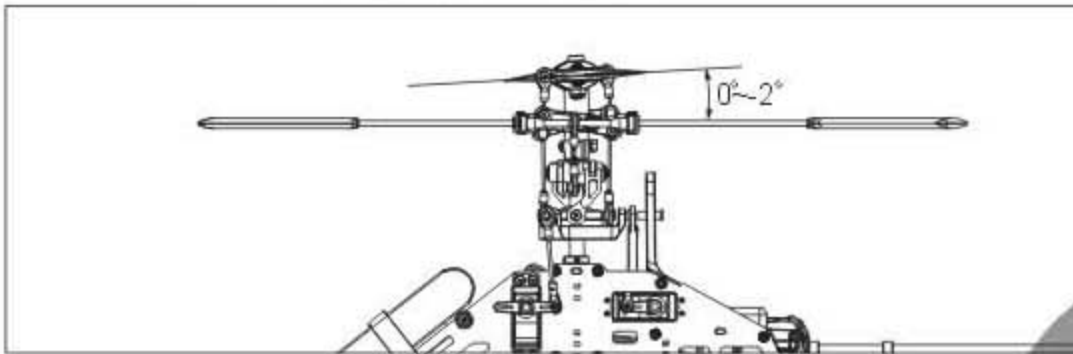
GENERAL FLIGHT 一般飛行模式



Stick position at high/Throttle 100%/Pitch +12°
搖桿高速/油門100%/Pitch+12°



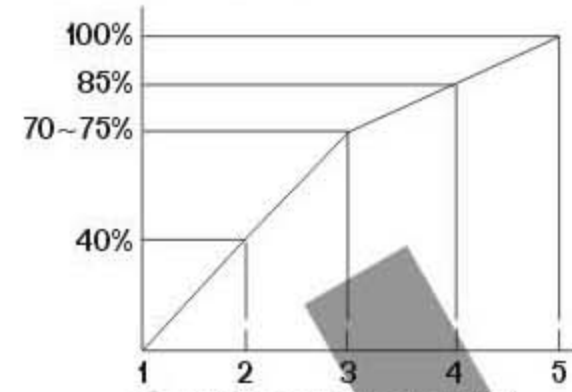
Stick position at Hovering/Throttle 70%~75%/ Pitch+5°~+6°
搖桿停懸/油門70%-75%/Pitch+5°~+6°



Stick position at low/Throttle 0%/Pitch -2°~0°
搖桿低速/油門0%/Pitch-2°~0°

GENERAL FLIGHT 一般飛行模式

	Throttle 油門	Pitch 螺距
5	100% High speed 100% 高速	+12°
4	85%	
3	70%~75% Hovering 70%~75% 停懸	+5°~+6°
2	40%	
1	0% Low speed 0% 低速	-2°~0°



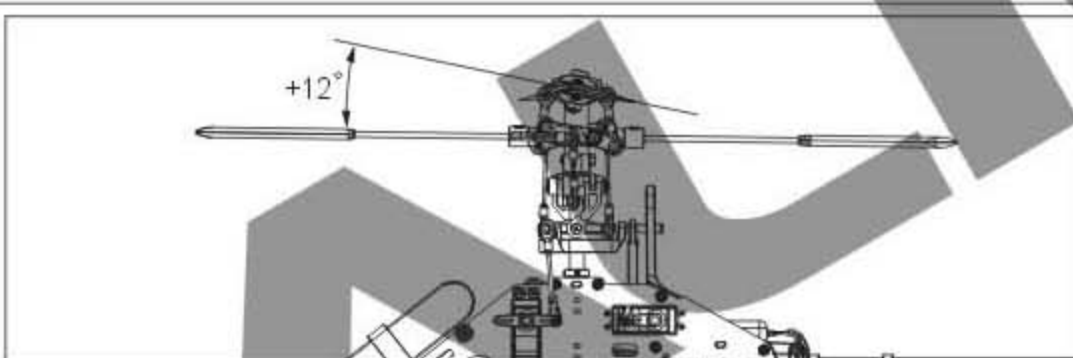
Throttle Curve (Hovering Flight)
停懸模式油門曲線

Pitch and Rotation Speed Pitch與轉速關係

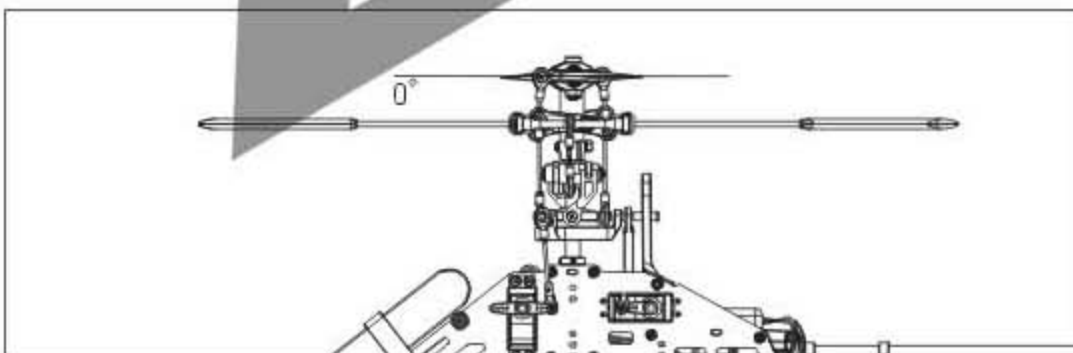
TIP: It is recommended to use a lower pitch setting when using higher RPM/Head speed. This will allow for better power.

搭配要領: 如果使用較高轉速馬達動力建議搭配調低 Pitch, 將獲得較佳動力效能。

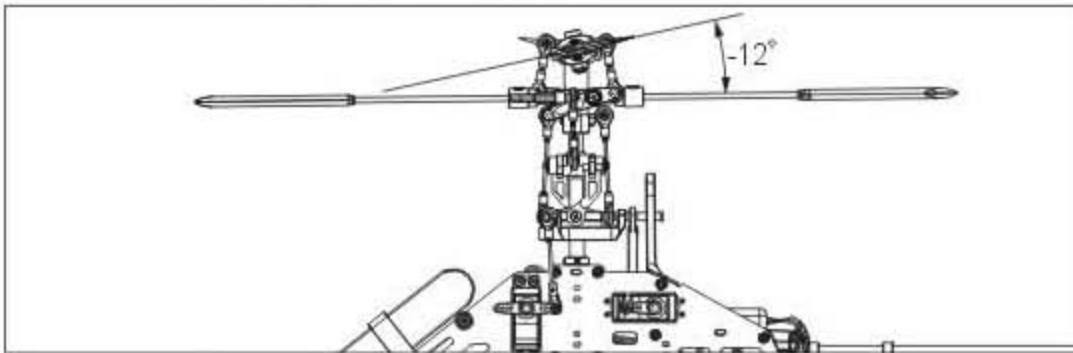
3D FLIGHT 3D特技飛行模式



Stick position at high/Throttle 100%/Pitch +12°
搖桿高速/油門100%/Pitch+12°



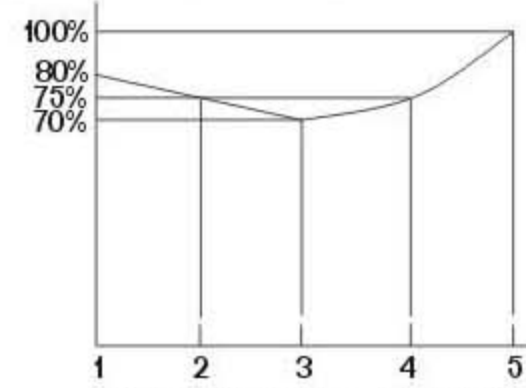
Stick position at middle/Throttle 85~90%/Pitch 0°
搖桿中速/油門85-90%/Pitch 0°



Stick position at low/Throttle 100%/Pitch -12°
搖桿低速/油門100%/Pitch-12°

IDLE 1: SPORT FLIGHT

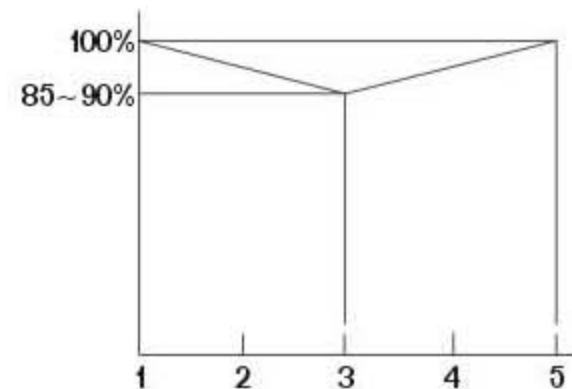
	Throttle 油門	Pitch 螺距
5	100%	+12°
4	75%	
3	70%	+5°~+6°
2	75%	
1	80%	-5°~6°



Throttle Curve (Simple Aerobatic Flight)
空中飛行模式油門曲線

IDLE 2: 3D FLIGHT

	Throttle 油門	Pitch 螺距
5	100% High 100% 高	+12°
3	85~90% Middle 85-90% 中	0°
1	100% Low 100% 低	-12°



Throttle Curve (3D Flight)
特技飛行模式油門曲線

1. Pitch range: Approx. 29(±14.5) degrees.
2. If the pitch is set too high, it will result in shorter flight duration and poor motor performance.
3. Setting the throttle to provide a higher speed is preferable to increasing the pitch too high.



1. 螺距 (Pitch) 總行程約 29°(±14.5)。
2. 過大螺距設定, 會導致動力與飛行時間降低。
3. 動力提升以較高轉速的設定方式, 優於螺距調大的設定。

BATTERY 電池: ALIGN Li-Poly 22.2V 2600mAh

Motor Pinion Gear 馬達齒輪	Main Rotor Blade 主旋翼規格	Pitch 螺距	Current(A) approx. 電流(A)大約值	Throttle Curve 油門曲線	RPM approx. 主旋翼轉速大約值	
13T	425 Carbon Fiber Blades 425碳纖維主旋翼	Hover 停懸	+5°	11	0/50/70/85/100%	2200
		Idle	0°	12	85%Middle中	2830
			0°	14.5	100/100/100/100/100%	2980 ⚠
			±12°	33		2750

NOTE: 1. Please use a pitch gauge to adjust the pitch value. Incorrect excess pitch setting will result poor helicopter performance and reduce ESC's life and battery's life.

⚠ 2. For the safeties of flight and helicopter structure, please do not equip the power of main blade over 2850 RPM.

註: 1. 請務必使用螺距規來量測調整螺距, 不正確的過大螺距設定不但無法發揮直昇機的特性, 反會影響到無刷調速器與電池的壽命。
 ⚠ 2. 為了飛行安全與機體結構安全, 主旋翼轉速設定禁止超過2850RPM。

14.RCE-BL70G BRUSHLESS SPEED CONTROLLER INSTRUCTION MANUAL 無刷調速器使用說明

PRODUCT FEATURES 產品特色

- 5-6V step-less adjustable BEC output allowing custom voltage setting to match servo specification.
- BEC output utilizing switching power system, suitable for 7.4-22.2V (2S-6S) Li battery, with continuous current rating of 3A, and burst rating of 5A.
- Three programmable throttle speed settings to support quick throttle response.
- Include soft start and governor mode.
- Small and compact PCB design for lightweight and simple installation.
- Large heat sink for optimum thermal performance.
- Highly compatible to work with 98% of all brushless motors currently on the market.
- Ultra-smooth motor start designed to run with all kinds of brushless motors.
- The power inlet utilizes a Japanese made "Low ESR" capacitor in order to provide stable power source.
- The throttle has more than 200 step resolution that provides great throttle response and control.

- 5~6伏特無段可調式BEC輸出, 可依伺服器規格與所需的特性自行設定電壓。
- BEC輸入端採用交換式電源設計, 適用7.4~22.2V (2S~6S) 鋰電, 持續耐電流3A, 瞬間5A。
- 三段可程式油門反應速度, 使動力的反應隨傳隨到。
- 具緩啟動及Governor Mode定速功能。
- 體積小, 窄型設計, 安裝於機身容易。
- 有散熱片設計, 可延長電變壽命。
- 超高相容性, 可對應市面上 98% 無刷馬達。
- 絕佳起步設計, 無論國產、進口、內轉、外轉無刷馬達皆起步順暢。
- 電池電源端採用日製 Low ESR 低阻抗電解電容, 大幅提高電源之穩定性。
- 油門達 200 段以上解析度, 無格數之油門感覺。

WIRING ILLUSTRATION 接線示意圖



SPECIFICATION 規格

Model 型號	Continuous Current 持續	Peak Current 瞬間	BEC Output BEC輸出	Dimension 尺寸	Weight 重量
RCE-BL70G	70A	110A 5sec	Output voltage: 5-6V step-less adjustment Continuous current 3A; Burst current 5A 輸出電壓: 5~6V無段可調式 承受電流: 持續3A、瞬間5A	65x31x18mm	72g

- Good temperature situation for working at the maximum current
 - Supporting motor types: 2 ~ 10 pole in/outrunner brushless motors.
 - Supporting maximum RPM: 2 pole → 190,000 rpm; 6 pole → 63,000 rpm.
 - Input voltage: 5.5V ~ 25.2V(2~6S Li-Po)
- NOTE: 1. When setting to the Quick throttle response speed, the accelerative peak current will increase.
 2. To minimize possible radio interference induced by switching power system, BEC should be installed at least 5cm away from the receiver. The use of PCM or 2.4G receiver is recommended.

- 持續最大電流需在機體散熱良好情況下。
 - 支援馬達型式: 二極至十數極之內外轉子無刷馬達。
 - 支援最高轉速: 二極→190,000rpm; 六極→63,000rpm。
 - 輸入電壓: 5.5V~25.2V (2~6s Li-Po)
- 注意: 1. 設定為高油門反應速度時, 加速瞬間電流會有增大情形。
 2. 內建Switching BEC, 安裝時請與接收器保持至少5cm以上的距離以避免干擾接收器(建議使用較穩定的PCM或2.4G系統接收器)。

FUNCTIONS 產品功能

- Brake Option - 3 settings that include Brake disabled/Soft brake/Hard brake.
- Electronic Timing Option - 3 settings that include Low timing/Mid timing/High timing. Generally, 2 pole motors are recommended to use low timing, while 6 or more poles should use Mid timing. High timing gives more power at the expense of efficiency. Always check the current draw after changing the timing in order to prevent overloading of battery.
- Battery Protection Option- 2 settings that include Li-ion, Li-poly High/Middle cutoff voltage protection.
 The default setting is high cutoff voltage protection. CPU will automatically determine cell number of input Lithium battery (2S~6S). This option will prevent over-discharge of the battery. The following reference is the guideline for setting the Battery Protection option.
 3-1 Li-ion/Li-poly High cutoff voltage protection-When the voltage of single cell drops to 3.2V, the first step of battery protection mode will be engaged by the ESC resulting in reduced power. The pilot should reduce the throttle and prepare landing. If the voltage of single cell drops to 3.0V, the second step of battery protection mode will be engaged resulting in power cutoff. (*Note 1) For 11.1V/3cells Lithium battery, the full charged voltage will be approximately 12.6V. According to this input voltage, CPU will determine that this is a 3cell battery.
 First step protection: 3.2V x 3cell=9.6V
 Second step protection: 3.0V x 3cell= 9.0V
 When the voltage drops to 9.6V, the power will be reduced. When the voltage drops to 9.0V, the power will be cut off.

3-2 Li-ion/Li-poly Middle cutoff voltage protection- This option is same as instruction 3-1, but when the voltage of single cell drops to 3.0V, the first step of battery protection will be engaged. When the voltage of single cell drops to 2.8V, the second step of battery protection will be engaged. (*Note 1)

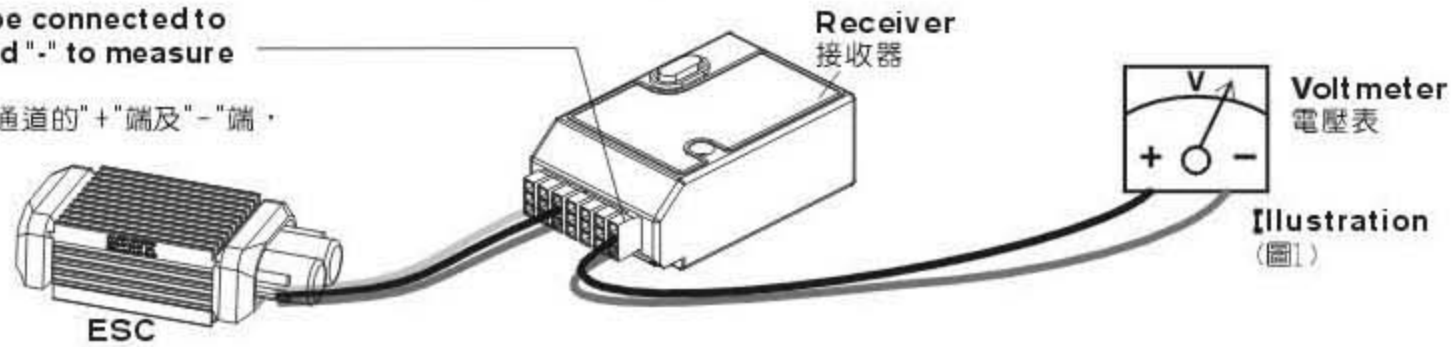
Note 1: Second step of battery protection only works when Aircraft mode is setting to the option 4-1.

NOTE: THIS OPTION IS ONLY SUITABLE FOR A FULLY CHARGED BATTERY PACK IN GOOD WORKING CONDITION.

- Aircraft Option: 3 settings that include Normal Airplane / Helicopter 1 / Helicopter 2.
Normal Airplane Mode is used for general airplanes and gliders. When flying Helicopters, you can choose Helicopter 1 Mode, or Helicopter 2 Mode. Helicopter 1 Mode provides Soft Start feature. Helicopter 2 Mode provides Soft Start and Governor Mode.
- Throttle response speed: 3 settings that include standard/ Medium/ Quick throttle response speed.
The default setting is "quick speed". Use this option to adjust the setting according to flight character. For example, setting at Medium or Quick speed for 3D and powerful flight to make the power response more quickly, but note the accelerative peak current and power expense will increase.
- BEC output voltage setting: 5-6V step-less adjustment.
This option allows custom voltage setting. Default setting is 5.5V; please adjust the voltage according to the specification of the servo (speed and resistance). Prior to entering the setup mode, a voltmeter needs to be connected to the power inlet of the receiver (as illustration) to monitor the selected voltage. The voltage is set by varying the throttle stick position from low (5V) to high (6V).

The voltmeter needs to be connected to any un-use inlets "+" and "-" to measure the selected voltage.

將電壓表連接到任一未使用通道的 "+" 端及 "-" 端，以量測所選擇的電壓。



NOTE: Certain servos are designed to work with high voltage, while other servos are designed for lower voltage.

To avoid damage to servos, please follow the servo's factory specification to determine the proper voltage setting.

注意: 部份伺服器不適合較高的電壓下操作，請依原廠適用電壓規格設定，避免造成伺服器燒毀。

- Thermal Protection: When the ESC temperature reaches 80 °C for any reason, it will engage the battery protection circuit, reducing power to the ESC.
We recommend mounting the ESC in a location with adequate air flow and ventilation.
 - Safe Power On Alarm: When the operator turns on the ESC, it will automatically detect the transmitter signal. The ESC will emit a confirmation tone and enter normal operation mode if the throttle is set to the lowest position. If the throttle position is at full throttle, it will begin to enter Setup Mode. If the throttle is in any other position, the ESC will emit an alarm and not enter into user mode for safety precautions.
 - Aircraft Locator: If the aircraft should land or crash in an unexpected location and become lost, the pilot can enable the Aircraft Locator Option. The Aircraft Locator Option is engaged by turning off the transmitter. When the ESC does not receive a signal from the transmitter for 30 seconds, it will start to send an alarm to the motor. The sound of the alarm will aid the pilot to locate the aircraft. This option will not work with a PCM receiver that has SAVE function enabled, or with low noise resistant PPM receivers.
- 煞車設定: 三段選擇分為無煞車 / 軟性煞車 / 急煞車
 - 進角設定: 三段選擇分為低進角 / 中進角 / 高進角
設定時機分為二極以上無破刷馬達，二極無破刷馬達一般適用低進角，若希望馬達轉速提高，可將進角設定為中進角。六極以上無破刷馬達一般適用中進角，若希望馬達轉速提高，可將進角設定為高進角。然而進角之調整需要注意電流之變化，避免電池過載，影響電池及馬達壽命。
 - 電池保護電壓設定: 二段選擇分為 Li-Ion / Li-Po 高截止電壓保護 / 中截止電壓保護
出廠設定為高截止電壓保護；此功能會自動判定所輸入鋰電池的 cell 數 (2~6S)，並提供使用者對該電池之放電保護，以避免因放電電壓過低而造成電池損壞，以下為設定值之解說：
3-1 Li-Ion/Li-Po 高截止電壓保護：當鋰電單 cell 壓降達 3.2V 時，電變會啟動第一階段保護，使動力間歇性中斷，此時使用者應將油門收小，準備降落；而當單 cell 電壓持續壓降達到 3.0V 時則會啟動第二階段保護，完全限制動力輸出(註1: 僅在 4-1 選項 "一般飛機模式" 下才會啟動第二階段保護)。
例: 以一個使用 11.1V 3cell 鋰電池之系統而言 11.1V 鋰電池充飽電壓約 12.6V，此輸入電壓 CPU 會自動判定為 3cell 鋰電。
第一階段保護: 3.2Vx3cell=9.6V，第二階段保護: 3.0Vx3cell=9.0V，當電壓降至 9.6V 時，動力會間歇性中斷，當電壓降至 9.0V 時則完全限制動力輸出。
3-2 Li-Ion/Li-Po 中截止電壓保護: 同 3-1 功能說明，但單 cell 壓降達到 3.0V 時，會啟動第一階段保護，單 cell 壓降達到 2.8V 時啟動第二階段保護(註1)。
注意: 以上功能僅適用於充飽電，且功能正常的鋰電池。
 - 飛機模式設定: 三段式選擇分為: 一般飛機模式 / 直昇機模式 1 / 直昇機模式 2
使用於一般飛機或滑翔機時，請設定於一般飛機模式，使用於直昇機時可選擇直昇機模式 1: 具有緩啟動功能，或直昇機模式 2: 具有緩啟動及 Governor Mode 定速功能。
 - 油門反應速度設定: 三段選擇分為標準 / 中速 / 快速
出廠設定值為 "快速" 油門反應速度，此功能提供使用者依所需的飛行特性來作適當的調整，例如 3D 飛機與劇烈的 3D 直昇機飛行時可設定為中速或快速，使動力反應更加快速、靈敏，但須注意提高油門反應速度時，加速瞬間電流與耗電量會有增大的情形。
 - BEC 輸出電壓設定: 5~6V 無段調整
本功能提供使用者自行設定 BEC 輸出電壓，初始電壓為 5.5V，使用者可依伺服器的規格與所需的特性 (速度與扭力) 自行更改設定；進入此項設定前，請先將電壓表連接到接收器的電源端 (如圖 1)，用以監看所選擇的電壓，設定時以油門搖桿的位置來決定輸出電壓，油門搖桿最低為 5 伏特，最高為 6 伏特，之間的電壓值可移動搖桿的位置任意設定。
 - 溫度保護: 當電變因不良之空氣對流或是過載輸出導致溫度上升達 80°C 時，電變會啟動溫度保護，而使動力間歇性中斷，建議將電變裝置在機艙內空氣對流之位置，並實際使用電流量表量測輸出電流，以達到電變之最佳效率。
 - 開機防暴衝提醒功能: 當使用者開啟電變電源時，系統會自動偵測發射機之設定，如果發射機油門未置於最低點，或未置於最高點準備進入設定模式，馬達將不會轉動，同時會有警示警響提醒。
 - 尋機功能: 當飛機降若再長草區無法以目視定位時，使用者可將發射機關閉，當電變無法接收來自接收機信號時，電變會於三十秒後使馬達發出警示警響，以利定位。此功能不適用於設定了 SAVE 功能之 PCM 接收機，或抗雜訊低之 PPM 接收機。

SETUP MODE 設定模式

- Setup mode: Make sure to connect the ESC to the throttle channel of the receiver. Please refer to the user manual of your radio system. The second step is to connect the 3 power-out signal pins to the brushless motor. Before you turn on the transmitter, please adjust the throttle stick to the maximum full throttle position. Proceed to connect the battery to the ESC. You will hear confirmation sounds as soon as you enter the SETUP MODE. Please refer the attached flow chart for details.
- Throttle stick positions in Setup mode: Setup mode includes six settings: Brake, Electronic Timing, Battery Protection, Aircraft, Throttle Response Speed and BEC output voltage. Every setting has three options. Simply place the throttle stick in the highest, middle, and lowest positions for each setting. For example, first brake setting (Hard): move the stick to the highest position. Then timing setting (mid): move the throttle stick in the middle position.

- 進入設定模式: 將電變與接收器之油門 Channel 連接，不同之遙控系統請參閱您遙控系統之使用手冊，馬達之三條線亦與電變連接，將發射器之油門搖桿推到最高點，使之於全油門狀態，先開啟發射器電源，再將電源連接至電變，進入設定模式後，馬達將有設定模式之提示警響。請參考第二頁程式化設定模式說明。
- 設定模式中之動作: 設定模式共含有六項設定，分別為煞車、馬達進角、電池保護、飛機模式、油門反應速度級 BEC 輸出電壓等設定，詳細內容請參考產品功能之解說。每一項設定中各含三段設定，各項設定以油門搖桿之上、中、下位置來決定其設定值。
例如: 煞車設定時，油門搖桿撥至最高，則設定為急煞車，進入第二項進角設定時，油門搖桿撥至中間，則設定為中進角。

Mode 設定模式	Throttle position 油門搖桿	Low 低	Middle 中	High 高
Brake 煞車設定		● Brake disabled(1-1) 無煞車 (1-1)	Soft brake(1-2) 軟性煞車 (1-2)	Hard brake(1-3) 急煞車 (1-3)
Electronic Timing 進角設定		Low-timing(2-1) 低進角 (2-1)	● Mid-timing(2-2) 中進角 (2-2)	High-timing(2-3) 高進角 (2-3)
Battery Protection 電池保護電壓設定		● High cutoff voltage protection(3-1) 高截止電壓保護 (3-1)	Middle cutoff voltage protection(3-2) 中截止電壓保護 (3-2)	—
Aircraft 飛機模式設定		Normal Airplane/Glider(4-1) 一般飛機 / 滑翔機 (4-1)	● Helicopter 1 (Soft Start)(4-2) 直昇機模式 1 (緩啟動功能) (4-2)	Helicopter 2 (Soft Start + Governor Mode)(4-3) 直昇機模式 2 (緩啟動 + Governor Mode 定速功能) (4-3)
Throttle response speed 油門反應速度設定		Standard(5-1) 標準 (5-1)	Medium speed(5-2) 中速 (5-2)	● Quick speed(5-3) 快速 (5-3)
BEC output voltage BEC 輸出電壓設定		5.0V	● 5.5V	6.0V

Note: ● default setting
註: ● 表示出廠設定值

Chart A
表 A

ESC START-UP INSTRUCTION 開機使用模式



CURRENT SETTINGS INDICATOR BEEPS EXPLANATION 開機模式設定響音提示說明

<p>First Beep Group Brake Status 第一個響音 煞車設定狀態提示</p> <ul style="list-style-type: none"> 1 beep = Brake disabled = 無煞車 2 beeps = Soft brake = 軟性煞車 3 beeps = Hard brake = 急煞車 	<p>Second Beep Group Electronic Timing 第二個響音 進角設定狀態提示</p> <ul style="list-style-type: none"> 1 beep = Low timing (apply to 2 pole inrunner motors) = 低進角 (適合2級內轉子馬達) 2 beeps = Mid timing (apply to 6 pole in/outrunner motors) = 中進角 (適合6級內外轉子馬達) 3 beeps = High timing (apply to high power output) = 高進角 (適用於高功率輸出) <p>High-timing/big power power expense 高進角模式有較大功率與耗電特性</p>	<p>Third Beep Group Battery protection Cutoff 第三個響音 電池保護設定狀態提示</p> <ul style="list-style-type: none"> 1 beep = High cutoff voltage protection = 高截止電壓保護 2 beeps = Middle cutoff voltage protection = 中截止電壓保護 	<p>Fourth Beep Group Aircraft Status 第四個響音 飛機模式設定狀態提示</p> <ul style="list-style-type: none"> 1 beep = Normal airplane/Glider = 一般飛機/滑翔機 2 beeps = Helicopter 1 (Soft start) = 直昇機模式1 (緩啟動功能) 3 beeps = Helicopter 2 (Soft start + Governor Mode) = 直昇機模式2 (緩啟動功能+Governor Mode定速功能) 	<p>Fifth Beep Group Throttle Response 第五個響音 油門反應速度設定狀態提示</p> <ul style="list-style-type: none"> 1 beep = Standard = 標準 2 beeps = Medium speed = 中速 3 beeps = Quick speed = 快速
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INSTRUCTIONS ON AIRCRAFT MODE SETTINGS 飛機模式設定使用說明

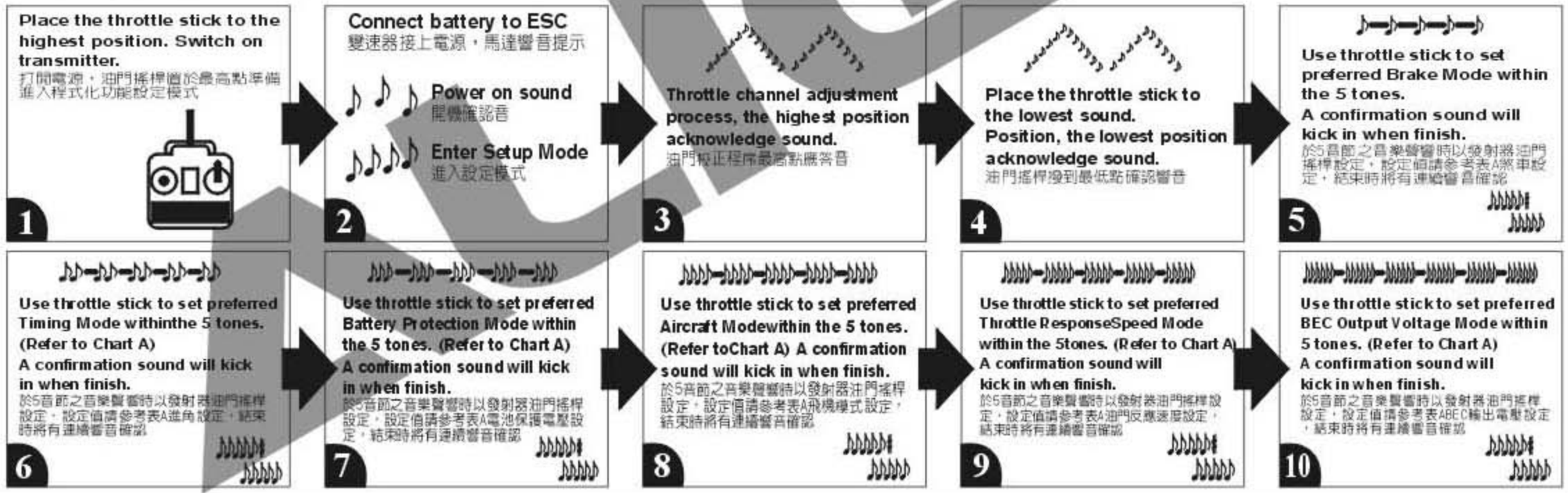
Normal Airplane/Glider Mode (Option 4-1):
This option is applied to general airplanes and gliders.

Helicopter 1 Mode (Option 4-2):
This option provides a soft start feature and is applied to Helicopters for Normal, Idle Up 1, or Idle Up 2 modes. Please note that the sensitivity of the gyro should be set lower when flying in Idle Up 1 or Idle Up 2 modes if tail hunting (wag) occurs due to higher rotor speed.

Helicopter 2 Mode (Option 4-3):
This option supports soft start as well as Governor Mode features and is applied to Helicopters for Idle Up 1 and Idle Up 2 modes (not suitable for Normal Flight Mode). When Governor Mode is in use, the throttle should be set between 75% and 85%. Again if tail wag occurs, lower the sensitivity of the gyro to eliminate the hunting effect. The Governor Mode may not work properly in cases of insufficient rotor speed (due to improper gear ratio), poor battery discharge capability, and improper setting of gyro sensitivity and the blade pitch, etc. Please make sure all the proper adjustments have been done when using Governor Mode.

一般飛機模式 (選項4-1): 適用於一般飛機及滑翔機。
直昇機模式1 (選項4-2): 具有緩啟動功能, 適用於Normal、Idle1、Idle2等飛行模式, 當切換至Idle1或Idle2模式, 如有較高轉速造成陀螺儀有輕微的追蹤現象, 此時應將陀螺儀的感度設定分別降低。
直昇機模式2 (選項4-3): 具有緩啟動及Governor Mode定速功能, 適用於Idle1、Idle2特技飛行模式 (不適合Normal飛行模式下選用), 選擇定速功能時, 油門應定速在75%-85%之間, 如果飛行時發現有輕微的追蹤現象時, 應降低陀螺儀的感度; 由於轉速不足 (齒比搭配不當)、電池效能不佳, 陀螺儀感度設定不當, Pitch設定錯誤, 皆會導致無法發揮定速的功能, 甚至產生尾部偏擺的情形, 所以選擇此模式時應針對相關條件進行確認。

SETUP MODE 程式化設定模式 Minimum 4 channel radio is required 四動以上標準發射器均可執行設定



15.GP780 HEAD LOCK GYRO SET USER MANUAL GP780鎖定式陀螺儀組使用說明



Features 產品特色

- Utilizes Silicon Micro Machines (S.M.M) sensor with excellent stability to dramatically reduce in-flight tail drifts.
- Utilizes AHTCS (Active Helicopter Tail Control System) to compensate any drift caused by wind direction and force, as well as unintended yaw induced by helicopter itself during flight maneuvers.
- Tailor made specifically for use with high speed digital rudder servos. This gyro features high sensitivity and minimal reaction time, fully utilizing the potential of modern high speed digital rudder servos.
- Suitable for all sizes of helicopters, from micro indoor to large 90 size glow helicopters.
- Metallic dampening plate built into bottom gyro casing, dramatically increasing anti-vibration and anti-interference abilities.
- Features 1520 μs pulse wide and 760 μs narrow pulse wide frame rate.
- Digital/Analog servo switchable.
- Reverse switch.
- Rudder servo travel limit adjustment (ATV).
- Mode switch for large/mini helicopter.
- Delay adjustment.
- Gyro locking mode and gain can be adjusted remotely from the transmitter.
- 採用S.M.M矽微細加工技術感知器, 具有極佳的穩定性, 大幅降低尾舵偏移的機會。
- 採用AHTCS (Active Helicopter Tail Control System)主動式直昇機尾旋翼控制系統, 主動修正因風向、風力變化與直昇機不同飛行姿態所產生之偏移。
- 專為高速型數位伺服器量身打造, 具有高靈敏度與極短的反應時間, 完全發揮伺服器高速反應的鎖定能力。
- 適用迷你型室內電直至大型90油直。
- 下蓋與金屬防震片一體成型, 大幅提升抗震防干擾能力。
- 相容標準1520 μs與窄頻760 μs伺服器。
- 數位/類比伺服器切換。
- 尾舵正逆向控制切換。
- LIMIT尾舵行程量設定。
- 大/小型直昇機模式切換。
- DELAY控制延遲量設定。
- 可由遙控器控制鎖定與非鎖定模式, 以及調整陀螺儀感度。

Setting type 設定項目	1520/760 μ s	DS/AS	NOR / REV	LIMIT	Helicopter mode / DELAY 直昇機模式 / DELAY
"STATUS" green "STATUS" 綠燈	▲ Standard 1520 μ s Servo ▲ 標準 1520 μ s 伺服器	▲ Digital servo ▲ DS 數位伺服器	▲ Normal rotation ▲ NOR 正轉	Left (Right) Travel limit 左 (右) 行程量	Medium / large heli, suitable for T-REX 500/600/700 中型 / 大型直昇機 適用 T-REX 500/600/700
"STATUS" red "STATUS" 紅燈	Narrow band 760 μ s Servo 窄頻 760 μ s 伺服器	Analog Servo AS 類比伺服器	Reverse rotation REV 反轉	Right (Left) Travel limit 右 (左) 行程量	Mini / Micro heli, suitable for T-REX 250/450 小型 / 迷你型直昇機 適用 T-REX 250/450
Setting instruction 設定方式說明	See no. 2 in setting instructions 參照設定方式第2項	See no. 3 in setting instructions 參照設定方式第3項	See no. 5 in setting instructions 參照設定方式第5項	See no. 6 in setting instructions 參照設定方式第6項	See no. 8 in setting instructions 參照設定方式第8項

NOTE: 1. "▲" Default setting. 2. Wrong heli mode will affect the performance of gyro. Do not fly before the complete setting.
註: 1. "▲" 表示出廠設定值。 2. 錯誤的直昇機模式將影響陀螺儀性能，未完成設定前請勿飛行。

T-REX500 Standard setting T-REX500 標準設定

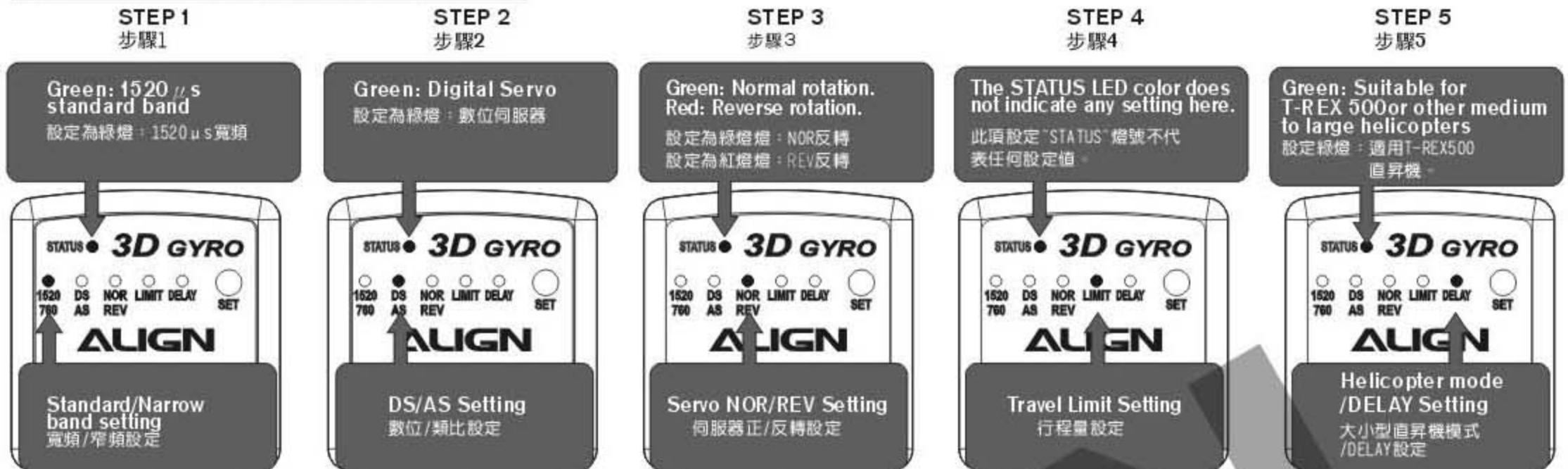
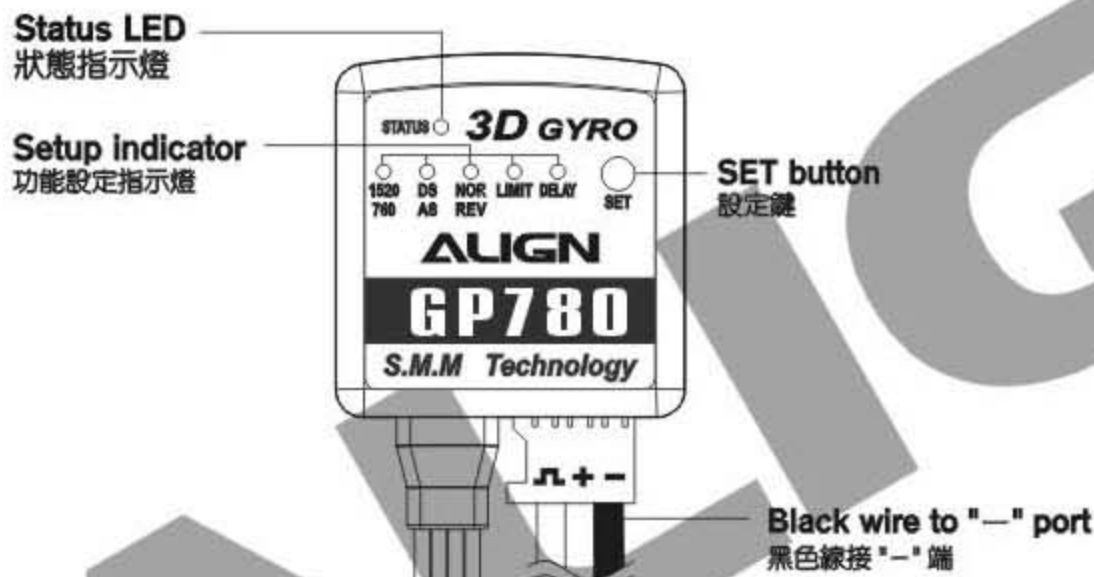


Diagram 各部名稱



GP780 Gyro Specifications GP780 陀螺儀產品規格

- Operating Voltage: DC 4.5~7V
- Current Consumption: <80mA @ 4.8V
- Angular Detection Speed: ± 500 degrees/sec
- Operating Temperature: $-20^{\circ}\text{C} \sim 65^{\circ}\text{C}$
- Operating Humidity: 0%~95%
- Size: 26x25x11mm
- Weight: 14g
- RoHS compliant
- 適用電壓: DC 4.5~7V
- 消耗電流: <80mA @ 4.8V
- 偵測角速度 ± 500 度/sec
- 操作溫度: $-20^{\circ}\text{C} \sim 65^{\circ}\text{C}$
- 操作濕度: 0%~95%
- 尺寸: 26x25x11mm
- 重量: 14g
- 符合RoHS限用規章

DS520 Digital Servo DS520 數位伺服器

- Speed: 0.09sec / 60 degrees (4.8V)
0.07sec / 60 degrees (6.0V)
- Torque: 1.9kg.cm (4.8V)
2.5kg.cm (6.0V)
- Dimension: 35 x 15 x 29.2mm
- Weight: 25.9g (Servo horn not included)
- 1520 μ s (standard band)
- 動作速度: 0.09sec/60° (4.8V)
0.07sec/60° (6.0V)
- 輸出扭力: 1.9kg.cm (4.8V)
2.5kg.cm (6.0V)
- 尺寸: 35x15x29.2mm
- 重量: 25.9g (不含舵角片)
- 1520 μ s (寬頻系統)

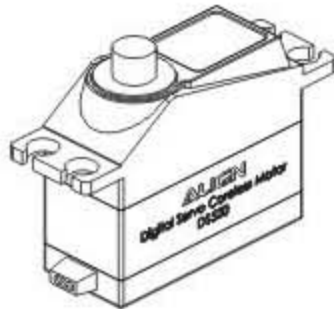
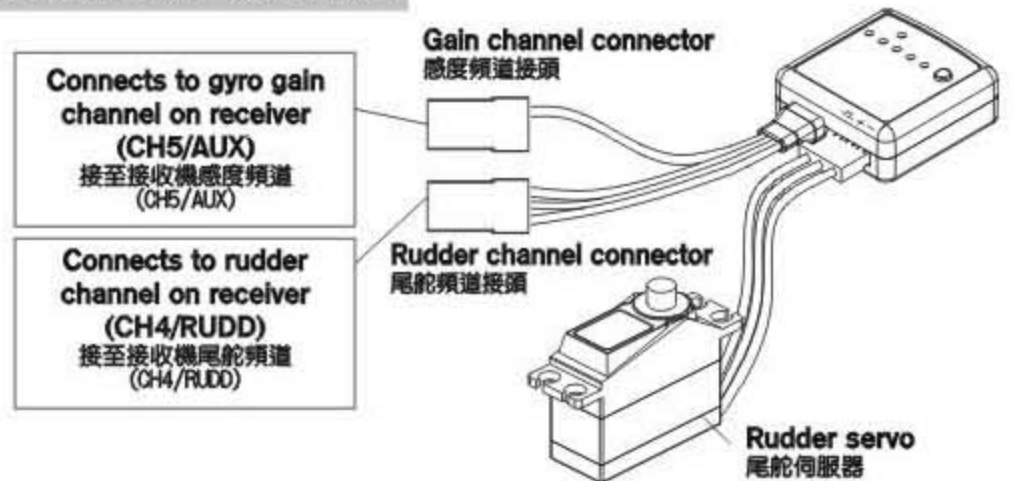


Illustration 接線示意圖

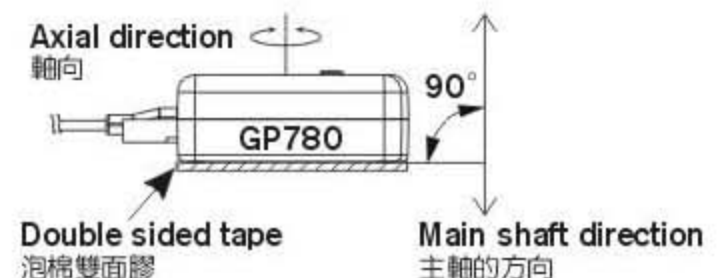


Gain and Rudder channel mapping diagram 連接對照表:

Transmitter type 遙控器種類	Rudder channel on Receiver 尾舵頻道接頭至接收器	Gain channel on Receiver 感度頻道接頭至接收器
JR PPM/SPCM	"RUDD"	"AUX 2" or "AUX 3"
Hitec、Futaba PPM/PCM	"CH4"(RUD)	"CH5"
JR ZPCM	"RUDD"	"AUX 2"

Gyro Installation 陀螺儀的安裝

- Utilizing the included double sided foam tape as shown in diagram beside, mount the gyro on a solid platform or designated gyro mounting location on the helicopter. Ensure gyro mounting area have proper ventilation and away from heat sources.
- To avoid drift induced by erroneous yaw detection, the bottom surface of gyro must be perpendicular (90 degrees) relative to the main shaft.
- For installation on electric powered helicopters, the gyro should be installed as far away from the electronic speed controller (ESC) as possible to avoid interference (minimum 5cm).



- 利用所提供的泡棉雙面膠如右圖方式，把陀螺儀固定在穩定的平台上或機體預留的陀螺儀座，並確保它在通風良好的區域，遠離熱源。
- 陀螺儀底部水平貼附與直昇機的主軸垂直90度，否則會影響感知器對角度變化的偵測，造成偏移。
- 安裝於電動直昇機時盡量遠離(5公分以上)馬達與電子調速器，避免干擾情形發生。

1. Transmitter Settings: After powering up transmitter, make sure rudder subtrim is zeroed. Then power on the receiver and gyro. The gyro will go through initializing process indicated by flashing LED from left to right. Do not touch the heli or transmitter sticks until initializing is complete, as indicated by a steady lit LED. A green LED indicates gyro is in AHTCS locking mode, while red LED indicates gyro is in normal mode.

Note: The GP780 is set to 1520 μ s at the factory. If 760 μ s servo is used in 1520 μ s mode, rudder servo will deflect to the side and unable to center. For more critically, the linkage rod may jam and cause the servo burned out. Please follow the instruction (Usage setting 2) to change the setting if 760 μ s servo is used. Please ensure the following mixing functions (if available) are disabled or zeroed on the transmitter.

- ATS
- Pilot authority mixing
- Throttle to rudder mixing
- Rudder to gyro mixing
- Pitch to rudder mixing
- Revolution mixing

2. 1520 μ s (standard) or 760 μ s (narrow band) servo selection: GP780 offers compatibility for two types of frame rates under digital mode.

Please set the GP780 to 760 mode if 760 μ s frame rate rudder servos (such as Futaba S9256, S9251, BLS251) are used.

Most other servos have 1520 μ s frame rate, and GP780 should be set to 1520 mode if those servos are used.

To enter the setup mode: Press and hold the SET button for 2 seconds, and the STATUS LED will begin flashing. When the 1520/760 indicator lit up, you are in the servo frame rate setup menu. Use the rudder stick on your transmitter to select the frame rate: move the stick to left (or right) and STATUS led changes to green, the frame rate has been set to 1520 μ s. If you want to set the frame rate to 760 μ s, move the stick to opposite end 3 times to make STATUS led changes to red. (Note: The faceplate of GP780 has the setting values listed in the corresponding green/red letters.)

Press the SET to confirm the current setting and enter the next setting. The GP780 will exit setting mode if left idle for 10 seconds.

3. Digital (DS) / Analog (AS) Servo Selection: Servo speed is of paramount importance in maximizing the gyro's performance.

Fast servos are able to respond to gyro commands quickly, resulting in the speed and precision of overall system. Due to the high sensitivity of GP780 gyro, high speed digital servos such as Align DS650, DS620, DS520, DS420, Futaba S9257, S9256, S9254, S9253, or other similar spec servos are recommended. Select "DS" when digital servos are used, and "AS" when analog servos are used.

To enter the setup mode: Press and hold the SET button for 2 seconds, and the STATUS LED will begin flashing. Press the SET button repeatedly until DS/AS led is lit. Use the rudder stick on your transmitter to select the Servo type: move the stick to left (or right) and STATUS led changes to green, the servo type is set to DS. Move the stick to opposite direction and STATUS led changes to red, the servo type is set to AS.

Warning: The use of analog servo under "DS" mode will result in servo failure. The GP780 gyros are set to "DS" mode at the factory. Please set the proper servo type based on servo used.

4. Check the direction of rudder: move the rudder stick on transmitter left/right and check the helicopter's instruction manual for correct rudder direction. Servo reverse function on the transmitter can be used for reversed rudder. Set the transmitter gyro gain channel to normal mode, or press and hold the SET button for 2 seconds to center the rudder servo. Adjust the servo horn so it is perpendicular (90 degrees) relative to the pushrod. Then adjust the rudder linkage length so the tail pitch control system is within range.

Setting Method: Press and hold the SET button for 2 seconds to enter the setup menu, and select DELAY setting. Push the rudder stick left or right and observe the STATUS LED. Red represents mini/micro helis, green represents medium/large helis.

The amount of delay is set by holding the rudder stick at the position corresponding the delay percentage, 0% at middle stick position and 100% at the end position, and pressing the SET button to confirm the delay setting.

1. 檢查遙控器的設定: 先開啟遙控器電源, 將尾舵的微調歸零後, 再開啟直昇機的接收機電源, 此時陀螺儀會先進入初始化狀態, 所有指示燈會由左至右閃爍, 接著使尾舵伺服器回到中立點, 在此之前請勿晃動直昇機或撥動尾舵搖桿, 當狀態指示燈為綠色時表示陀螺儀在鎖定的狀態, 指示燈為紅色時表示陀螺儀在非鎖定的狀態。

※註: GP780出廠時內建為 1520 μ s 系統, 若使用 760 μ s 窄頻伺服器時, 開機後尾舵伺服器將會偏向一邊無法居中, 甚至造成連桿卡死而使伺服器燒毀, 請參照使用及設定方式第2項更改設定值。

如果您的遙控器有下列功能時, 請設定為關閉(OFF)或數值設定為零

- ATS
- Pilot authority mixing
- Throttle to rudder mixing
- Rudder to gyro mixing
- Pitch to rudder mixing
- Revolution mixing

2. 1520 μ s (標準) 或 760 μ s (窄頻) 伺服器選擇: GP780 相容兩種波寬控制系統, 若您使用的伺服器屬於 760 μ s 系統 (如 Futaba S9256、S9251、BLS251), 則必須將 GP780 設定於 760 的模式, 其他未標示 760 μ s 規格的伺服器, 一般皆為 1520 μ s 系統, 必須將 GP780 設定為 1520 的模式。

如何進入功能設定模式: 持按面板上的 "SET" 設定鍵約 2 秒, 此時 "STATUS" 狀態指示燈會開始閃爍, 且 "1520/760" 的功能設定指示燈會亮起, 表示進入標準/窄頻伺服器選項, 利用遙控器方向舵搖桿的左右方向來選擇設定值, 例如方向舵搖桿往左 (或右) 時, "STATUS" 指示燈為綠色, 表示設定值為 1520 μ s 系統; 若要設定為窄頻 760 μ s 系統時, 必須將搖桿由中立點往相反方向連續撥動 3 次, 使 "STATUS" 指示燈亮紅色, 才會進入 760 μ s 系統。(註: GP780 的面板標識上已使用綠/紅色的字體提示 "STATUS" 燈色所代表的設定值)。設定完成後按 "SET" 鍵一次可進入下一個設定, 或是 10 秒內不做任何設定, GP780 會自動離開設定模式。

3. DS 數位 / AS 類比伺服器選擇: 伺服器動作速度感關陀螺儀的性能, 伺服器動作愈快, 就能立即反應陀螺儀送出的指令, 發揮快速精準的效能; 由於 GP780 具有相當快速的反應時間與靈敏度, 所以建議您搭配高速型數位伺服器, 如 ALIGN DS650、DS620、DS520、DS420、Futaba S9257、S9256、S9254、S9253 或其他相同規格伺服器, 以獲得最佳效能。設定方式: 持按 "SET" 鍵 2 秒進入功能設定模式, 再按 "SET" 鍵選擇 DS/AS 選項, (DS/AS 指示燈亮起), 利用方向舵搖桿選擇數位 DS (STATUS 為綠燈) 或類比 AS (STATUS 為紅燈) 伺服器。

注意: 在 DS 模式下連接類比伺服器將導致伺服器燒毀, 本產品出廠時設定在 DS 模式, 請自行依所搭配的伺服器類型選擇正確的模式。

4. 檢查尾舵伺服器正逆轉方向與調整連桿: 左右撥動尾舵搖桿, 確認尾舵伺服器移動的方向是否正確, 若不正確請更改遙控器上的尾舵伺服器正逆轉方向。將 GP780 切換成非鎖定模式或持按 GP780 的 "SET" 鍵 2 秒, 使尾舵伺服器保持在中立點的位置上, 調整伺服舵片, 儘可能使尾舵連桿與伺服舵片呈 90 度, 接著調整連桿長度使尾 Pitch 控制組置中。



5. Setting of gyro direction nor/rev: Check the gyro direction by moving the heli on the yaw axis while holding by hand. Observe the direction gyro is moving the rudder servo. If direction is incorrect, switch the direction switch on the gyro to compensate.

To enter the setup mode: Press and hold the SET button for 2 seconds, and the STATUS LED will begin flashing.

Press the SET button repeatedly until NOR/REV led is lit. Use the rudder stick on your transmitter to select the Servo type: move the stick to left (or right) and STATUS led changes to green, the servo direction is set to NOR.

Move the stick to opposite direction and STATUS led changes to red, the servo direction is set to REV.

Warning: Flying with reversed gyro will cause the heli to spin out of control. Please double check the direction before attempting to fly the heli.

6. Rudder Servo Travel Limit Adjustment: Press and hold the SET button for 2 seconds until the STATUS LED flashes.

At this point the rudder servo will be centered. Press

the SET button repeatedly until LIMIT led is lit. While observing the heli tail, gradually move the rudder stick on your transmitter left until the tail pitch slider reaches its mechanical end (without binding), then center the rudder stick and wait 2 seconds until STATUS LED flashes red. Now perform the same for right rudder: move the rudder stick on your transmitter right until the tail pitch slider reaches the other end, center the stick and wait 2 seconds for LED to flash again. This will set the travel limit of the servo on both sides. Insufficient rudder servo travel limit will result in decreased rudder performance, while excessive rudder servo travel will overload the rudder servo and cause failures.

Caution: Rudder travel setting can not be below 50%, or else GP780 will not register the settings. If excessive travel is observed even after performing the above rudder travel adjustments, please relocate the rudder servo linkage ball closer to the center of servo horn.

7. Gyro Gain Adjustments: For radio with GYRO function, gain can be adjusted using this function. The AHTCS (heading lock) gain is set by adjusting the GYRO setting between 50% to 100%, while the normal mode gain is set by adjusting the GYRO setting between 0 to 49%.

Actual gain settings will differ amongst different helis and/or servo. The goal is to achieve as high of gain as possible without the tail oscillating (wagging), therefore such adjustment can only be done under actual flight conditions.

Suggested initial settings are 70~80% during hover, and 60~70% during idle-up conditions. Gyro gain can be increased or decreased after observing the presence of tail oscillation during flights.

Note: For radio systems using 0-100% as gain adjustment under heading lock mode (such as Futaba), the recommended gain setting is approximately 30~35%. For radio system using 50-100% as gain adjustment under heading lock mode (such as JR and Hitec), the recommended gain setting is approximately 70~75%.

8. helicopter mode and delay setting. These settings incorporates two functions:

(1) GP780 supports mini/micro indoor helicopters. Set the setting based on the appropriate helicopter class.

For example: Set the helicopter mode to mini/micro setting (Status LED turns red) for T-Rex 250 and 450; set the helicopter mode to medium/large setting (Status LED turns green) for T-Rex 500/600/700.

(2) Slow rudder servos may cause tail oscillation as it receives the faster signal from gyro. If tail oscillation occurs after hard stop from stationary pirouette, increase the gain setting until such oscillation stops.

Setting Method: Press and hold the SET button for 2 seconds to enter the setup menu, and select DELAY setting. Push the rudder stick left or right and observe the STATUS LED. RED STATUS represents mini/micro helis such as T-REX250/450, GREEN STATUS represents medium/large helis such as T-REX500/600/700. The amount of delay is set by holding the rudder stick at the position corresponding the delay percentage, 0% at middle stick position (DELAY STATUS LED is flashing) and 100% at the end position, and pressing the SET button to confirm the delay setting.

5. NOR/REV陀螺儀正逆轉開關設定: 提起直昇機, 將機頭往左擺動, 若尾舵伺服器的擺動方向與遙控器的方向舵搖桿打右舵同方向時, 表示陀螺儀的動作方向設定正確, 若不正確時請更改正逆轉設定。設定方式: 持按"SET"鍵2秒進入功能設定模式, 選擇NOR/REV選項, 以方向舵選擇NOR (STATUS為綠燈) 或REV (STATUS為紅燈)。

注意: 陀螺儀的正逆轉方向設定錯誤時會造成直昇機高速自旋的危險, 請務必確認。

6. LIMIT尾舵伺服器行程量調整: 持按"SET"鍵2秒進入功能設定模式, 此時尾舵伺服器會保持在中立點的位置上, 選擇LIMIT選項, 接著將方向舵搖桿慢慢的往左移動, 使尾控制組達到該側的最大行程限度後, 將搖桿回歸中立點不動, 待2秒後"STATUS"指示燈會亮紅燈閃爍, 表示左側行程量已記憶; 接著將尾舵搖桿向右移動至控制組最大行程限度後, 再將搖桿回歸中立點不動, 待2秒後"STATUS"指示燈亮紅燈閃爍, 即完成左右行程量設定, 行程量不足時會影響陀螺儀與直昇機的性能, 行程量過大易造成伺服器損壞。

注意: 尾舵行程量設定不可低於50%, 否則GP780將不予記憶, 若發生行程量設定後, 尾控制組仍會超過最大行程, 請將尾舵擺臂的球頭向內移動, 避免行程量不足影響陀螺儀性能。

7. 感度調整: 一般具有陀螺儀感度設定功能的遙控器, 可直接進入GYRO功能選項進行感度值的設定, 設定值50%則陀螺儀的感度為0, 設定值50%~100%, 則陀螺儀感度值為鎖定狀態的0~100%; 設定值50%~0%, 則陀螺儀感度值為非鎖定狀態的0~100%。感度值的大小會隨著伺服器與直昇機的不同而有所差異, 一般而言, 在不產生追蹤現象(直昇機尾部出現左右搖擺的情況)的前提下感度值愈高愈好, 所以只能透過實際飛行的狀況來進行調整。

進入遙控器感度設定的選項, 剛開始停懸時建議先設定在70~80%左右, Idle up飛行時設定在60~70%左右, 之後再依實際飛行的狀態再行修正, 如果沒有追蹤現象發生時可再調整高感度, 若發生追蹤現象時, 則調低感度。

※註: 鎖定感度值為0~100%的遙控器, 如Futaba, 建議設定在30~35%左右; 鎖定感度值為50~100%的遙控器, 如JR、HITEC, 建議感度值設定在70~75%左右。

8. 直昇機模式與DELAY控制延遲量調整, 此設定結合兩項功能:

(1) GP780支援小型/迷你型室內電直, 請依您直昇機的類型選擇適合的模式, 如: T-REX 250/450請選擇小型/迷你型模式(設定時"STATUS"指示燈為紅色); T-REX500/600/700請選中大型直昇機模式(設定時"STATUS"指示燈為綠色)

(2) 使用速度較慢的尾舵伺服器較容易產生追蹤現象, 當直昇機停懸時, 打方向舵使直昇機快速自轉, 當方向舵回到中立點使直昇機停止自轉時, 此時若發生追蹤現象, 請增加控制延遲的設定量, 一般而言在不產生追蹤現象的原則下控制延遲的設定量愈小愈好, 否則尾舵的動作會變得遲緩。

設定方式: 持按"SET"鍵2秒進入功能設定模式, 選擇至DELAY選項, 以方向舵搖桿選擇小型/迷你型電直如T-REX 250/450 (STATUS為紅燈), 或中大型直昇機如T-REX500/600/700 (STATUS為綠燈), 若要同時設定DELAY控制量時, 則利用方向舵搖桿的位置來設定, 搖桿由中立點推至"DELAY"燈開始閃爍時為0%, 推至最大行程時控制量為100%, 將搖桿推至所需的延遲量時保持不動, 並按下"SET"鍵確認, 即可同時設定直昇機模式與延遲量。

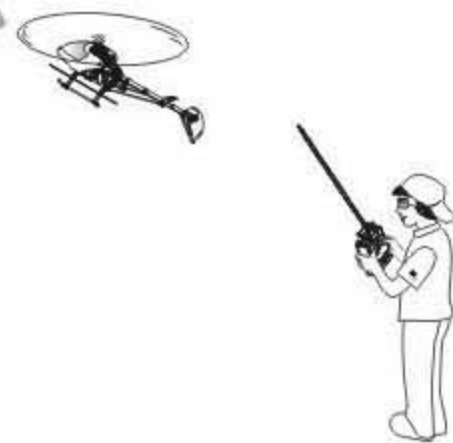
16. FLIGHT ADJUSTMENT AND SETTING 飛行動作調整與設定

ALIGN

PLEASE PRACTICE SIMULATION FLIGHT BEFORE REAL FLYING 飛行前請事先熟練模擬飛行

Do a simulation flight until you familiarize your fingers with the movements of the rudders, and keep practicing until the fingers move naturally.

1. Place the helicopter in a clear open field (Make sure the power OFF) and the tail of helicopter point to yourself.
2. Practice to operate the throttle stick (as below illustration) and repeat practicing "Throttle high/low", "Aileron left/right", "Rudder left/right", and "Elevator up/down".
3. The simulation flight practice is very important, please keep practicing until the fingers move naturally when you hear operation orders being call out.
4. Another safe and effective practice method is to use the transmitter flying on the computer through simulator software sold on the market.



在還沒瞭解直昇機各動作的操控方式前, 嚴禁通電飛行, 請先進行模擬飛行的練習, 並不斷的重複, 直到手指可熟練的控制各個動作及方向。

1. 將直昇機放在空曠的地方(確認電源為關閉), 並將直昇機的機尾對準自己。
2. 練習操作遙控器的各搖桿(各動作的操作方式如下圖), 並反覆練習油門高/低、副翼左/右、升降舵前/後及方向舵左/右操作方式。
3. 模擬飛行的練習相當重要, 請重複練習直到不需思索, 手指能自然隨著喊出的指令移動控制。
4. 另外一種最有效、最安全的練習方式, 就是透過市面販售的模擬軟體, 以遙控器在電腦上模擬飛行, 熟悉各種方向的操控。

Mode 1	Mode 2	Illustration 圖示
		<p>Move left 左移</p> <p>Rotate left 左轉</p> <p>Move right 右移</p> <p>Rotate right 右轉</p>
		<p>Fly forward 前進</p> <p>Forward rotate 前翻</p> <p>Fly backward 後退</p> <p>backward rotate 後翻</p>
		<p>Ascent 上升</p> <p>Descent 下降</p>
		<p>Turn right 右旋</p> <p>Turn left 左旋</p>

FLIGHT ADJUSTMENT AND NOTICE FOR BEGINNERS 初學飛行調整與注意



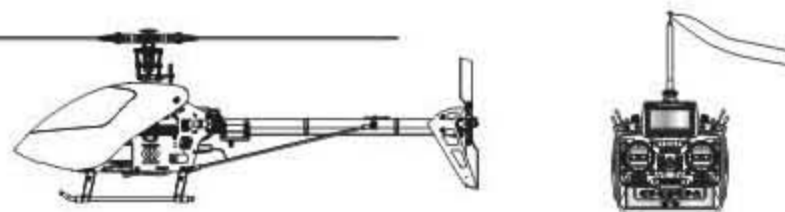
- Check if the screws are firmly tightened.
- Check if the transmitter and receivers are fully charged.
- 再次確認→螺絲是否鎖固?
- 發射器和接收器電池是否足夠。



If there are other radio control aircraft at the field, make sure to check their frequencies and tell them what frequency you are using. Frequency interference can cause your model, or other models to crash and increase the risk of danger. 假使飛行場有其他遙控飛機, 請確認他們的頻率, 並告知他們你正在使用的頻率, 相同的頻率會造成干擾導致失控和大大地增加風險。

★ When arriving at the flying field.

★ 當抵達飛行場



STARTING AND STOPPING THE MOTOR 啓動和停止馬達



First check to make sure no one else is operating on the same frequency. Then place the throttle stick at lowest position and turn on the transmitter.
首先確認附近沒有其他相同頻率的使用，然後打開發射器將油門搖桿推到低點。

- ★ Check the movement.
- ★ 動作確認



ON! Step 1
First turn on the transmitter.
先開啟發射器



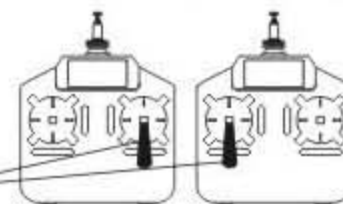
Check if the throttle stick is set at the lowest position.
確認油門搖桿是在最低的位置。

- ⊙ Are the rudders moving according to the controls?
- ⊙ Follow the transmitter's instruction manual to do a range test.
- ⊙ 方向舵是否隨著控制方向移動?
- ⊙ 根據發射器說明書進行距離測試。



ON! Step 2
Connect to the helicopter power
接上直昇機電源

Mode 1 Mode 2



OFF! Step 3
Reverse the above orders to turn off.
關閉電源時請依上述操作動作反執行。



Main rotor adjustments 主旋翼雙槳平衡調整



Tracking adjustment is very dangerous, so please keep away from the helicopter at a distance of at least 5m.
調整軌跡非常危險，請於距離飛機最少5公尺的距離。

1. Before adjusting, apply a red piece of tape on one blade, or paint a red stripe with a marker or paint to identify on blade.
2. Raise the throttle stick slowly and stop just before the helicopter lifts-off ground. Look at the spinning blades from the side of the helicopter.
3. Look at the path of the rotor carefully. If the two blades rotate in the same path, it does not need to adjustment. If one blade is higher or lower than the other blade, adjust the tracking immediately.
4. Linkage rod (A): Regular pitch trim (For large variations). Linkage rod (C): Slight pitch trim (For slight variations).

1. 調整前先在其中一支主旋翼的翼端，貼上有顏色的貼紙或畫上顏色記號，方便雙槳調整辨識。
2. 慢慢的推起油門搖桿到高點並且停止，在飛機離開地面前，從飛機側邊觀察主旋翼轉動。
3. 仔細觀察旋翼軌跡(假如兩支旋翼移動都是相同軌跡，則不需要調整;可是如果一支旋翼較高或較低產生“雙槳”的情形時，則必須立刻調整軌跡)。
4. 連桿(A)為一般螺距調整(雙槳大時使用)。連桿(C)為螺距微調調整(雙槳微幅差異時使用)。

- A. When rotating, the blade with higher path means the pitch too big. Please lengthen pitch linkage rod (A) for regular trim or shorten linkage rod (C) for slight pitch trim.
B. When rotating, the blade with lower path means the pitch too small. Please shorten pitch linkage rod (A) for regular trim or lengthen linkage rod (C) for slight pitch trim.

- A. 旋翼轉動時較高軌跡的主旋翼表示螺距(PITCH)過大，請調長連桿(A)修正，或需要更小的螺距微調時，請調短連桿(C)修正。
B. 旋翼轉動時較低軌跡的主旋翼表示螺距(PITCH)過小，請調短連桿(A)修正，或需要更小的螺距微調時，請調長連桿(C)修正。



Incorrect tracking may cause vibrations. Please repeat adjusting the tracking to make sure the rotor is correctly aligned. After tracking adjustment, please check the pitch angle is approx. $+5\sim 6^\circ$ when hovering.

不正確的旋翼軌跡會導致震動，請不斷重複調整軌跡，使旋翼軌跡精準正確。在調整軌跡後，確認一下Pitch角度在停旋時應為大約 $+5\sim 6^\circ$ 。



FLIGHT ADJUSTMENT AND NOTICE FOR BEGINNERS 初學飛行調整與注意



- ⊙ Make sure that no one or obstructions in the vicinity.
- ⊙ You must first practice hovering for flying safety. This is a basic flight action. (Hovering means keeping the helicopter in mid air in a fixed position)

- ⊙ 確認鄰近地區沒有人和障礙物。
- ⊙ 為了飛行安全，你必須先練習停懸，這是飛行動作的基礎(停懸：直昇機滯留空中並保持固定位置)。

- ⊙ Please stand approximately 5m diagonally behind the helicopter.
- ⊙ 練習時，請站在直昇機後方5公尺。

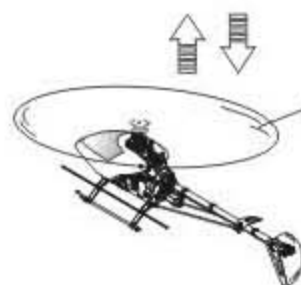
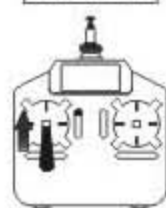
Beginner may install a training landing gear to avoid any crash caused by offset effect while landing.
必要時初學者可以在腳架下方安裝練習架，可避免降落時因重心偏移導致主旋翼或直昇機損毀。



STEP 1 THROTTLE CONTROL PRACTICE 油門控制練習

Mode 1

Mode 2



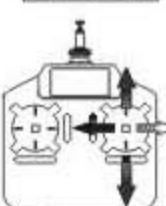
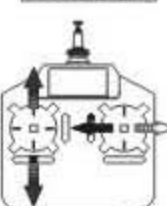
- ⊙ When the helicopter begins to lift-off the ground, slowly reduce the throttle to bring the helicopter back down. Keep practicing this action until you control the throttle smoothly.

- ⊙ 當直昇機開始離地時，慢慢降低油門將飛機降下。持續練習飛機從地面上升和下降直到你覺得油門控制很順。

STEP 2 AILERON AND ELEVATOR CONTROL PRACTICE 副翼和升降控制練習

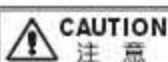
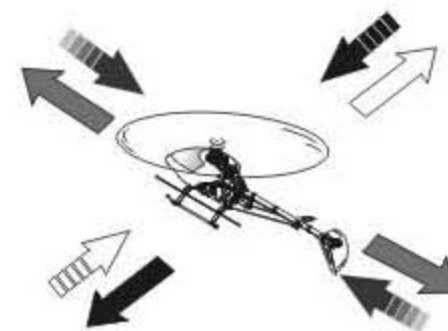
Mode 1

Mode 2



1. Raise the throttle stick slowly.
2. Move the helicopter in any direction back, forward, left and right, slowly move the aileron and elevator sticks in the opposite direction to fly back to its original position.

1. 慢慢升起油門搖桿。
2. 使直昇機依指示：移動向後/向前/向左/向右，慢慢的反向移動副翼和升降搖桿並將直昇機開回到原來位置。

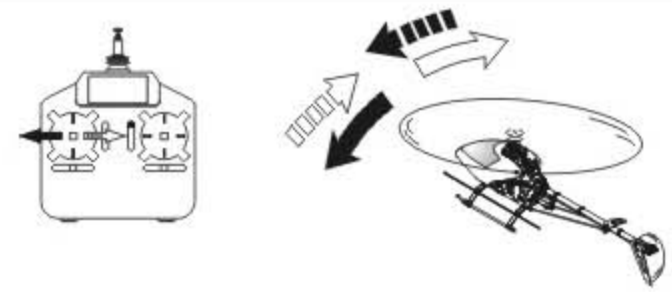


- ⊙ If the nose of the helicopter moves, please lower the throttle stick and land the helicopter. Then move your position diagonally behind the helicopter 5m and continue practicing.
- ⊙ If the helicopter flies too far away from you, please land the helicopter and move your position behind 5m and continue practicing.
- ⊙ 當直昇機機頭偏移時，請降低油門並且降落，然後移動自己的位置到直昇機的正後方5公尺再繼續練習。
- ⊙ 假如直昇機飛離你太遠，請先降落直昇機，並到直昇機後5公尺再繼續練習。

STEP 3 RUDDER CONTROL PRACTICING 方向舵操作練習

1. Slowly raise the throttle stick.
2. Move the nose of the helicopter to right or left, and then slowly move the rudder stick in the opposite direction to fly back to its original position.

1. 慢慢升起油門搖桿。
2. 將直昇機機頭移動左或右，然後慢慢反向移動方向舵搖桿並將直昇機飛回原本位置。

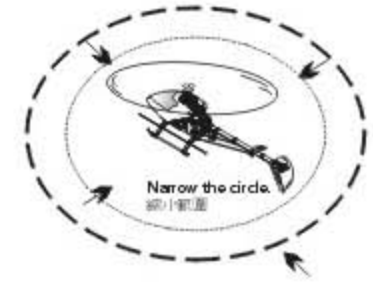


STEP 4

After you are familiar with all actions from Step1 to 3, draw a circle on the ground and practice within the circle to increase your accuracy.

當你覺得 step1~3 動作熟悉了，在地上畫圈並在這個圈內的範圍內練習飛行，以增加你操控的準確度。

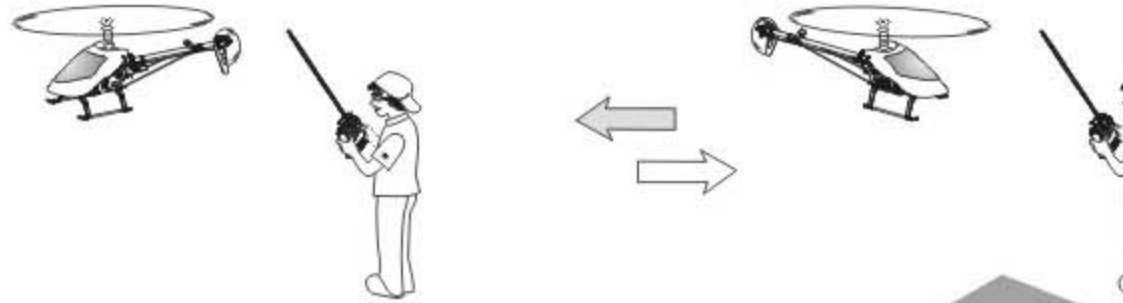
- ◎ You can draw a smaller circle when you get more familiar with the actions.
- ◎ 當你更加習慣操作動作，你可以畫更小的圈。



STEP 5 DIRECTION CHANGE AND HOVERING PRACTICE 改變直昇機方向和練習停懸

After you are familiar with Step1 to 4, stand at side of the helicopter and continue practicing Step1 to 4. Then repeat the Step1 to 4 by standing in front of the helicopter.

當你覺得 step1~4 動作熟悉了，站在面對直昇機側邊並繼續練習 step1~4。之後，站在直昇機機頭前方重複步驟練習。



ADJUSTMENT OF EACH TRIM 飛行動作微調

Slowly raise the throttle stick and just as the helicopter lift-off the ground, you can use the trim to correct the action if the helicopter leans in a different direction.

慢慢升起油門搖桿，當直昇機剛剛離開地面時，若直昇機傾向不同方向，可使用微調修正動作。

1. Adjustment of elevator trim 調整升降舵微調

Just before the helicopter lift-off, the nose lean forward/backward...

When leans forward, adjust the trim down.

When leans backward, adjust the trim up.

在直昇機正要起飛時，機頭朝前/後方向偏移...

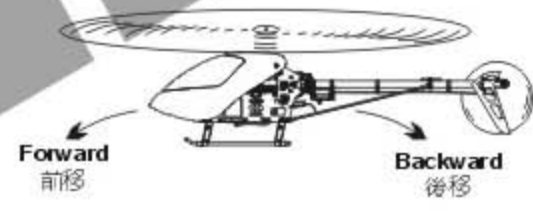
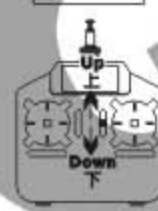
向前偏移時，微調向下調整。

向後偏移時，微調向上調整。

Mode 1



Mode 2



2. Adjustment of Aileron trim 調整副翼微調

Just before the helicopter lift-off, the body lean left/right...

When leans right, adjust the trim to left side.

When leans left, adjust the trim to right side.

在直昇機正要起飛時，機身朝左/右方向偏移...

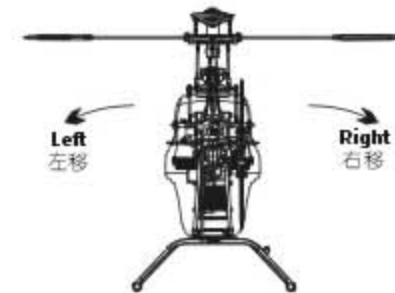
向右偏移時，微調向左調整。

向左偏移時，微調向右調整。

Mode 1



Mode 2



TROUBLE SHOOTING DURING FLIGHT 如何排除飛行中的狀況

	Situation 狀況	Cause 原因	Way to deal 對策
Blade Tracking 雙槳平衡	Out of tracking 雙槳	Adjustment of pitch rod has not been done. PITCH連桿長度調整不平均	Adjust the length of linkage rod(A)→Regular trim Adjust the length of linkage rod(C)→Slight trim 調整連桿(A)長度→一般調整 調整連桿(C)長度→微調整
During Hovering 停懸	Low rotation of the rotor 主旋翼轉速偏低	★ Pitch of main blade is high. ★ 主旋翼的PITCH偏高 ★ Throttle curve is too low during hovering. ★ 停懸點油門曲線過低	★ Lower the pitch about 5~6° during hovering(The rotation should be about 2,000~2,200rpm during hovering). ★ 調低Pitch停懸Pitch約5~6°(停懸時主旋翼需為約2000~2200rpm) ★ Heighten the throttle curve during hovering. ★ 調高停懸點油門曲線
	High rotation of the rotor 主旋翼轉速偏高	★ Pitch of main blade is low. ★ 主旋翼的PITCH偏低 ★ Throttle curve is too high during hovering. ★ 停懸點油門曲線過高	★ Adjust the pitch rod(A)(The rotation should be about 2,000~2,200rpm during hovering). ★ 調整連桿(A)(停懸時主旋翼需為約2000~2200RPM) ★ Lower the throttle curve during hovering. ★ 調低停懸點油門曲線
Sensitivity of the gyro 陀螺儀敏感度	The tail leans to one side during hovering, or when trim the rudder and return to the neutral, the tail lags and cannot stay in a control position. 停懸時尾翼向某一邊偏移，或撥動方向舵並回復到中立點時，尾翼產生延遲，無法停頓在所控制位置上。	★ Failure setting of tail neutral point. ★ 尾中立點設定不當 ★ The sensitivity of the gyro is low. ★ 陀螺儀敏感度偏低	★ Reset tail neutral point. ★ 重設尾中立點 ★ Increase the sensitivity. ★ 增加敏感度
	The tail wags left and right during flight at hovering or full speed. 停懸或全油門時尾翼左右來回搖擺。	The sensitivity of the gyro is high. 陀螺儀敏感度偏高	Decrease the sensitivity. 降低敏感度

※ If the problem is still there even after tried above, stop flying and contact with your seller.

※ 在做完以上調整後，仍然無法改善情況時，應立即停止飛行並連絡您的經銷商。

ALIGN

Specifications & Equipment/規格配備:

Length/機身長:840mm

Height/機身高:310mm

Main Blade Length/主旋翼長:425mm

Main Rotor Diameter/主旋翼直徑:970mm

Tail Rotor Diameter/尾旋翼直徑:200mm

Motor Pinion Gear/馬達齒輪:13T

Main Drive Gear/傳動主齒:162T

Autorotation Tail Drive Gear/尾驅動主齒:145T

Tail Drive Gear/尾翼傳動齒:31T

Drive Gear Ratio/齒輪傳動比:1:12.46:4.68

Weight(Without Power System)/空機重:980g

Flying Weight/全配重:Approx. 1700g

